

NASA CONTRACTOR
REPORT



NASA CR-2498

NASA CR-2498

A THEORETICAL METHOD
FOR THE ANALYSIS AND DESIGN
OF AXISYMMETRIC BODIES

T. D. Beatty

Prepared by

MCDONNELL DOUGLAS AIRCRAFT CORPORATION

Long Beach, Calif. 90801

for Langley Research Center



NATIONAL AERONAUTICS AND SPACE ADMINISTRATION • WASHINGTON, D. C. • MARCH 1975

1. Report No. NASA CR-2498		2. Government Accession No.		3. Recipient's Catalog No.	
4. Title and Subtitle A THEORETICAL METHOD FOR THE ANALYSIS AND DESIGN OF AXISYMMETRIC BODIES				5. Report Date MARCH 1975	
				6. Performing Organization Code	
7. Author(s) T. D. BEATTY				8. Performing Organization Report No.	
				10. Work Unit No. 501-06-01-01-00	
9. Performing Organization Name and Address McDONNELL DOUGLAS AIRCRAFT CORP. LONG BEACH, CALIF.				11. Contract or Grant No. NAS1-12986	
				13. Type of Report and Period Covered CONTRACTOR REPORT	
12. Sponsoring Agency Name and Address NATIONAL AERONAUTICS AND SPACE ADMINISTRATION WASHINGTON, D.C. 20546				14. Sponsoring Agency Code	
15. Supplementary Notes FINAL REPORT.					
16. Abstract A THEORETICAL METHOD IS PRESENTED FOR THE COMPUTATION OF THE FLOW FIELD ABOUT AN AXISYMMETRIC BODY OPERATING IN A VISCOUS, INCOMPRESSIBLE FLUID. A POTENTIAL FLOW METHOD IS USED TO DETERMINE THE INVISCID FLOW FIELD. THESE RESULTS YIELD THE BOUNDARY CONDITIONS FOR THE BOUNDARY LAYER SOLUTIONS. BOUNDARY LAYER EFFECTS IN THE FORCES OF DISPLACEMENT THICKNESS AND EMPIRICALLY MODELED SEPARATION STREAMLINES ARE ACCOUNTED FOR IN SUBSEQUENT POTENTIAL FLOW SOLUTIONS. THIS PROCEDURE IS REPEATED UNTIL THE SOLUTIONS CONVERGE. AN EMPIRICAL METHOD IS USED TO DETERMINE BASE DRAG ALLOWING CONFIGURATION DRAG TO BE COMPUTED.					
17. Key Words (Suggested by Author(s)) AXISYMMETRIC BODY POTENTIAL FLOW AXISYMMETRIC BODY BOUNDARY LAYER FLOW COUPLED VISCOUS/INVISCID FLOW SOLUTIONS FLOW SEPARATION ON AXISYMMETRIC BODIES				18. Distribution Statement UNCLASSIFIED - UNLIMITED STAR CATEGORY 34	
19. Security Classif. (of this report) UNCLASSIFIED		20. Security Classif. (of this page) UNCLASSIFIED		21. No. of Pages 279	
				22. Price* \$8.75	

SUMMARY

A theoretical method is presented for the computation of the flow field about an axisymmetric body operating in a viscous incompressible fluid. This approach combines a smoothing routine, a potential flow method based on a surface source distribution, and a finite-difference boundary-layer method to accomplish the analysis. An empirical method used for modeling separated flow is shown to work reasonably well for cases of extreme flow separation. Results obtained by this method are presented which show very good agreement with experimental data. Suggestions are made for extending this method both to include a better model for separated flow and to calculate the "viscous" flow about axisymmetric bodies at angle of attack. A detailed instruction manual for inputting data to the computer program is given in Appendix A. Appendix B contains the necessary information to place this program on to a computer. This appendix also contains a complete description of output parameters from the computer program, as well as basic flow charts of some of the major subroutines. Appendix C contains a complete listing of the computer program for operation on either a CDC or an IBM computer.

TABLE OF CONTENTS

	<u>Page</u>
SUMMARY	iii
INTRODUCTION	1
DEFINITION OF SYMBOLS	3
TECHNICAL DISCUSSION	6
Geometry Definition	6
Point distribution	6
Smoothness of input coordinates	6
Potential Flow Method	7
Boundary Layer Method	9
Basic boundary layer equations	9
Eddy-viscosity equations	12
Low Reynolds number effects	14
Transverse curvature	14
Transition region effect	15
Boundary layer transition location	16
Calculation Procedure	17
EXPERIMENTAL CORRELATIONS	22
CONCLUDING REMARKS	24
APPENDIX A	26
APPENDIX B	49
APPENDIX C	75
REFERENCES	253
ILLUSTRATIONS	258

A THEORETICAL METHOD
FOR THE ANALYSIS AND DESIGN
OF AXISYMMETRIC BODIES

by T. D. Beatty
McDonnell Douglas Aircraft Corporation

One of the ultimate goals in aerodynamics is the achievement of the ability to obtain the real fluid flow field about an arbitrary three-dimensional configuration by theoretical calculation rather than by resorting to expensive and time consuming wind tunnel tests. The exact treatment of this problem requires the solution of the full Navier-Stokes equations, which is currently not practical. However, a good approximation to this real flow can be obtained by displacing the surface boundaries of the original body to account for viscosity as shown by Thwaites in Reference (1).

This technique of displacing the boundary surface to obtain a viscous solution has been used in two-dimensional flows quite successfully, as shown in References 2, 3, and 4. The extension of this approach to three-dimensional flow requires that appropriate computational routines be available to calculate the potential and viscous flow parameters. A potential flow routine which can calculate the flow about arbitrary three-dimensional bodies is available (Reference 5), although the comparable three-dimensional boundary layer method is not currently in the state of the art. At the present time, the general three-dimensional problem cannot be solved. However, both an axisymmetric potential flow method and an axisymmetric boundary layer method which can calculate the inviscid and viscous flow field about a body of revolution at zero degrees angle of attack are currently available.

Because of its simple nature and its common appearance in fluid dynamics, it was decided that a body of revolution would be a good starting point for the development of a three-dimensional method for calculating inviscid and viscous flow fields.

The axisymmetric potential flow routine (References 6 & 7), used in the present method was developed at the Douglas Aircraft Company under the guidance of A. M. O. Smith and has proven over the years to be an extremely versatile

and accurate method, as well as the only purely axisymmetric potential flow method, generally available in industry today. This method has been well disseminated throughout industry; only a brief discussion will, therefore, be presented in a following section.

The boundary layer method presented in this report (Reference 8) is a finite difference technique which uses an eddy-viscosity concept to replace the Reynolds shear stress term. Since this method is relatively new and has been modified extensively since Reference 8 was reported, a detailed description will be presented.

The capability of the present method to determine the viscous flow about axisymmetric bodies is shown by correlations between the calculated results and experimental data.

Recommendations are presented for extending the present method to the calculation of the flow field about axisymmetric bodies at angle of attack.

DEFINITION OF SYMBOLS

A	Damping length or frontal area, wherever applicable
A ⁺	Damping constants
C _F	Total skin friction coefficient
C _p	Pressure coefficient
c	Chord
c _f	Local skin friction coefficient $\tau_w / (\frac{1}{2} \rho u_e^2)$
D	Maximum diameter
f	Dimensionless stream function
G	Spot formation parameter
H	Shape factor, θ/δ
K _L	Mixing-length constant
k	Power to determine 2-D or axisymmetric flow
L	Reference body length
l	Mixing length
P ⁺	Pressure gradient parameter
R _c	Chord Reynolds number, $u_\infty c/\nu$
R _D	Diameter Reynolds number, $u_\infty D/\nu$
R _x	Local Reynolds number, $u_e x/\nu$
R _θ	Momentum thickness Reynolds number, $U_e \theta/\nu$
r	Radial distance from axis of revolution
r _o	Local radius of body of revolution
T	Absolute temperature, °K or °R.
t	Transverse curvature term
U _∞	Free stream velocity
u _τ	Friction velocity, $\sqrt{\tau_w/\rho}$
u	x component of velocity

u_e	Velocity at edge of boundary layer
v	y-component of velocity
x	Distance along surface measured from leading edge or from stagnation point
y	Distance normal to the surface of the body
α	Angle between normal to the surface y and the radius r
α	Constant in outer eddy viscosity equation
β	Dimensionless velocity - gradient term, $\beta = (2\xi/u_e)(du_e/d\xi)$
γ_{Tr}	Transitional parameter
δ	Boundary layer thickness
δ^*	Boundary layer displacement thickness
ϵ	Eddy viscosity
ϵ^+	Ratio of eddy viscosity to kinematic viscosity, ϵ/ν
η	Transformed y-coordinate
θ	Momentum Thickness
μ	Dynamic viscosity
ν	Kinematic viscosity
ξ	Transformed x-coordinate
ρ	Density
τ	Shear stress

SUBSCRIPTS

c	Switching point between the inner and outer eddy viscosity formulas
e	Outer edge of boundary layer
i	Inner region
l	Laminar

o Outer Region

t Turbulent

Tr Transition

w Wall

∞ Free-stream conditions

Primes denote differentiation with respect to η .

TECHNICAL DISCUSSION

Geometry Definition

The geometry input to the Douglas Neumann Potential Flow Program must satisfy two primary requirements: the coordinates must be distributed properly and the surface curvature must be smooth. These requirements are easily achieved on an analytical body shape, since the input coordinates may be calculated exactly for any prescribed distribution. However, some method of determining accurate input coordinates for an arbitrary axisymmetric body is necessary, since the body may not always be amenable to exact analytical definition. The approach adopted in the following method is to assume that the coordinates are input in the proper distribution about the body, but that they are not necessarily smooth. These two requirements will be discussed in some detail in the following sections.

Point distribution. - In order to obtain a high degree of accuracy in defining a pressure distribution when using the Douglas Neumann Potential Flow program, surface coordinates should be concentrated in regions of high surface curvature where rapid changes in the surface pressures would be expected. Since the total number of points per body is fixed, the distribution of these points about the body contour becomes extremely important. The Neumann program uses the input coordinates to create linear segments between points, thus approximating the body by a series of Frustums of Cones. The basis distribution required is then quite simple: more points and thus smaller segment sizes in regions of high curvature and less points and thus larger segment sizes in the other areas of the body. The basic guidelines to follow to insure proper point distribution are simply that the surface lengths of adjacent elements should not change by more than twenty to thirty percent and the maximum length of any segment should not exceed either five percent of the body chord or fifty percent of the local body thickness.

Smoothness of input coordinates. - The Douglas Neumann program, or any similar potential flow method, is sensitive to the derivative of the surface slopes, or the curvature of the surface. The surface defined by the input coordinates must therefore have smooth first and second derivatives. The approach used in the

present method to smooth these coordinates, is a five point smoothing routine, which assumes that the input coordinates are smooth and continuous to graphical accuracy, i.e., points are chosen from a small graph (approximately a 10 inch chord). The output points from this routine will be moved very slightly to smooth the derivatives, but this movement will be negligible as far as the body shape is concerned. The equations used to accomplish this smoothing are as follows:

$$\bar{x}_j = \frac{1}{16} \left\{ -x_{j-2} + 4x_{j-1} + 10x_j + 4x_{j+1} - x_{j+2} \right\} \quad (1a)$$

$$\bar{y}_j = \frac{1}{16} \left\{ -y_{j-2} + 4y_{j-1} + 10y_j + 4y_{j+1} - y_{j+2} \right\} \quad (1b)$$

where x_j and y_j are the unsmoothed input coordinates

and \bar{x}_j and \bar{y}_j are the smoothed coordinates.

Potential Flow Method

The Douglas Neumann method, (References 6 and 7) is very general in that it can calculate the potential flow about virtually any body. There is no restriction, for example, to slender bodies; in fact, the "body" in question need not be a single body but may be an ensemble of bodies. In principle, the calculated solution may be made as accurate as desired by suitably refining the numerical procedure; accordingly, the so-called Neumann method is designated an exact method in this sense.

The Neumann method is based on the use of a distribution of source density over the body surface. Applying the condition of zero normal velocity on the body surface yields an integral equation for the source distribution. Specifically, the equation is a Fredholm integral equation of the second kind over the body surface. Once this has been solved for the source distribution, all flow quantities of interest, i.e., velocity, pressure, etc., can be calculated by rapid straightforward procedures. To implement this method on a computer, the body surface is approximated by a large number of small surface segments, over each of which the source density is assumed constant. The

integral equation is replaced by a set of linear algebraic equations for the values of the source density on the segments. Input to the computer program consists of the coordinates of a set of points defining the body surface; these points are then used to determine the surface segments for approximating the body. There is no assumption made that the body can be analytically represented.

The usefulness of potential flow with its neglect of viscosity and compressibility is due to the fact that it is a good approximation to real flow under a wide variety of circumstances. With regard to viscosity, the program obtains useful results except in regions of catastrophic separation. To verify the usefulness of potential flow as a predictor of real flow, results calculated by the Neumann program have been compared with experimental data. Several collections of comparisons have been made. Reference 9 was a very complete collection but is now rather old. Reference 10 is a more recent collection that shows a smaller number of comparisons. In the calculation of the viscous flow about axisymmetric bodies it is necessary to add the boundary layer displacement thickness to the body as will be shown in a subsequent section. This results in an "open" trailing edge body. This "open" body can be evaluated by the Neumann program without any difficulty even though the boundary surface does not close. Reference 11 presents an explanation of this phenomenon which proceeds as follows: for a closed body the integral of the source density over the body is zero; for an "open" trailing edge body, this integral is not zero, and a streamtube leaves the trailing edge of the open body which proceeds downstream and approaches infinity parallel to \vec{u}_∞ as a constant cross section streamtube. Thus, the flow that is calculated may be thought of as that about a semi-infinite body consisting of the open body and an extension defined by this streamtube. The shape of the extension is unknown but is presumably unique, having both zero normal velocity and zero source density.

The potential flow program has many useful options available which do not pertain directly to the present development. The details of these options are described in References 12 through 17.

Boundary Layer Method

Basic boundary layer equations. - The calculation of the viscous flow over an axisymmetric body involves the solution of the laminar and turbulent flow equations. For laminar flows, the problem is strictly mathematical because the governing differential equations can be written exactly. For turbulent flows on the other hand, an exact solution of the governing equations is not possible. Consequently, in order to proceed at all, one must rely on a certain degree of empiricism. In the past, most of the work in this area has concentrated on so-called momentum and/or energy integral methods as a means of evaluating the viscous flow parameters. Thus, the exact mathematical solution to the problems of the turbulent flow was bypassed, leading to fast and simple methods with varying degrees of accuracy. These methods usually rely quite heavily on empirical correlations and generally are restricted to a limited range of flow conditions.

The Douglas Boundary-Layer Method (Reference 8), eliminates many of the disadvantages of the integral methods by proceeding to solve the full partial-differential equations governing the flow, thereby, being classified as a differential method. For two-dimensional and axisymmetric incompressible flows, turbulent boundary-layer equations contain terms involving time means of fluctuating velocity components known as Reynolds stress terms. At present the exact relationship between these terms and the mean velocity distribution in the boundary layer still remains unknown. In the present method, a relation based on the eddy-viscosity concept is used giving highly satisfactory results for a variety of flow conditions.

If the normal-stress terms are neglected, the incompressible turbulent boundary-layer equations for two-dimensional and axisymmetric flows can be written as in Reference 8:

Continuity

$$\frac{\partial}{\partial x} [r^k u] + \frac{\partial}{\partial y} [r^k v] = 0 \quad (2)$$

Momentum

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} = u_e \frac{du_e}{dx} + \frac{1}{\rho_\infty} \frac{1}{r^k} \frac{\partial}{\partial y} \left(r^k \tau \right) \quad (3)$$

where

$$\tau = \tau_\ell + \tau_t$$

with

$$\tau_\ell = \mu_\infty \frac{\partial u}{\partial y} \quad (\text{For laminar flow only}) \quad (4)$$

$$\tau_t = -\rho_\infty \overline{u'v'} \quad (\text{Additional term due to turbulent flow})$$

and

$$\overline{u'v'} = \text{Reynolds shear stress term}$$

$$k = 0 \quad \text{for two-dimensional flow}$$

$$k = 1 \quad \text{for axisymmetric flow}$$

The basic notation and coordinate scheme are shown in Figure 1, where U_∞ is a reference velocity and $u_e(x)$ is the velocity just outside the boundary layer. The coordinate system is a curvilinear one in which x is the distance along the surface measured from the stagnation point or leading edge, and y is measured normal to the surface. Within the boundary layer, the velocity components in the x - and y -directions are u and v , respectively. The body radius is r_0 .

The boundary conditions for equation (3) are

$$u(x,0) = 0 \quad (5a)$$

$$v(x,0) = 0 \quad (5b)$$

$$\lim_{y \rightarrow \infty} u(x,y) = u_e(x) \quad (5c)$$

Before equations (2) and (3) can be solved, they must be transformed to a coordinate system which removes the singularity at $x = 0$ and stretches the coordinate normal to the flow direction. First, these equations are placed in an almost two-dimensional form by the Probstein-Elliott transformation (Reference 18):

$$d\bar{x} = \left[\frac{r_0(x)}{L} \right]^{2k} dx \quad (6)$$

$$d\bar{y} = \left[\frac{r(x,y)}{L} \right]^k dy \quad (7)$$

where $r_o(x)$ is the body radius and $r(x,y)$ is a radius which accounts for the transverse curvature effect which will be subsequently discussed. A stream function Ψ is defined that satisfies the continuity equation (2):

$$\frac{\partial \Psi}{\partial y} = r^k u \quad \frac{\partial \Psi}{\partial x} = -r^k v \quad , \quad \bar{\Psi} = \frac{\Psi}{L} \quad (8)$$

The resulting equations are transformed by the Levy-Lees transformation (Reference 19) in order to remove the singularity at $\bar{x} = 0$ and stretch the coordinates in the \bar{x} and \bar{y} directions. The Levy-Lees transformations are:

$$d\xi = \rho_\infty \mu_\infty u_e d\bar{x} \quad (9a)$$

$$d\eta = \frac{\rho_\infty u_e}{(2\xi)^{1/2}} d\bar{y} \quad (9b)$$

A dimensionless stream function, f , is introduced which is related to Ψ as follows:

$$\Psi = (2\xi)^{1/2} f(\xi, \eta) \quad (10)$$

Combining the Levy-Lees and the Probstein-Elliott transformations given above we have

$$d\xi = \rho_\infty \mu_\infty u_e \left[\frac{r_o(x)}{L} \right]^{2k} dx \quad (11a)$$

$$d\eta = \frac{\rho_\infty u_e}{(2\xi)^{1/2}} \left[\frac{r(x,y)}{L} \right]^k dy \quad (11b)$$

Introducing an eddy viscosity term to account for the Reynolds shear stress terms,

$$\epsilon \equiv - \frac{\overline{u'v'}}{\frac{\partial u}{\partial y}} \quad , \quad \epsilon^+ \equiv \frac{\epsilon}{U} \quad (12)$$

and a transverse curvature term t along with a pressure parameter term

$$\beta = \frac{2\xi}{u_e} \frac{du_e}{d\xi} \quad (13)$$

The momentum equation (3) then becomes, with $f' = u/u_e$,

$$\left[(1+t)^{2k} (1+\epsilon^+) f'' \right]' + f f'' + \beta \left[1 - (f')^2 \right] = 2\xi \left[f' \frac{\partial f'}{\partial \xi} - f'' \frac{\partial f}{\partial \xi} \right] \quad (14)$$

The boundary conditions given by equation (5) become

$$f(\xi, 0) = f_w = 0 \quad (15a)$$

$$f'(\xi, 0) = 0 \quad (15b)$$

$$\lim_{\eta \rightarrow \infty} f'(\xi, \eta) = 1 \quad (15c)$$

The momentum equation is then solved by a very efficient numerical scheme developed by Keller, (Reference 20) and applied to boundary layer calculations by Cebeci and Keller, (References 21 and 22).

Eddy viscosity equations. - The eddy viscosity concept is used to relate the time-mean fluctuating velocities to a mean velocity distribution as given in equation (12)

$$\epsilon \equiv - \frac{\overline{u'v'}}{\frac{\partial u}{\partial y}} \quad (12)$$

A two-layer model of the eddy viscosity within the boundary layer will be used as shown in figure 2.

In the inner region of the boundary layer an eddy viscosity model, based on Prandtl's mixing-length theory, is used:

$$\epsilon_1 = \ell^2 \left| \frac{\partial u}{\partial y} \right| \quad (16)$$

where ℓ , the mixing length is given by

$$\ell = K_1 Y \quad (17)$$

A modified expression for ℓ has been developed by Van Driest (Reference 23) to account for the viscous sublayer close to the wall. This modification is

$$\ell = K_1 Y \left[1 - e^{-(Y/A)} \right] \quad (18)$$

where A is given by

$$A = A^+ \frac{v_\infty}{N} \left[\frac{\tau_w}{\rho_\infty} \right]^{-1/2} \quad (19)$$

and

$$A^+ = 26.0 \quad (20)$$

$$N = \left[1 - 11.8 P^+ \right]^{-\frac{1}{2}} \quad (21)$$

$$P^+ = \frac{v_{\infty} u_e}{u_{\tau}^3} \frac{du_e}{d\xi} \rho_{\infty} \mu_{\infty} u_e \left(\frac{r_o}{L} \right)^{2k} \quad (22)$$

$$u_{\tau} = \left(\frac{\tau_w}{\rho_{\infty}} \right) \quad (23)$$

Now for axisymmetric flows the value of ℓ is replaced by

$$\ell = .4r_o \ln \left(\frac{r}{r_o} \right) \left[1 - e^{-\frac{r_o}{A} \ln \left(\frac{r}{r_o} \right)} \right] \quad (24)$$

which is developed in reference 24. If transverse curvature effects are desired then

$$\begin{aligned} \frac{r}{r_o} &= \frac{r_o + Y \cos \alpha}{r_o} = 1 + \frac{Y}{r_o} \cos \alpha \\ &= 1 + t \end{aligned} \quad (25)$$

$$\text{where } t = \frac{Y}{r_o} \cos \alpha$$

then ℓ becomes

$$\ell = .4r_o \ln (1+t) \left[1 - e^{-\frac{r_o}{A} \ln (1+t)} \right] \quad (26)$$

The eddy viscosity in the outer region of the boundary layer is given by

$$\epsilon_o = \alpha u_e \delta_k^* \quad (27)$$

where δ_k^* is the boundary layer displacement thickness defined by

$$\delta^* = \int_0^{n_\infty} \left[1 - \left(\frac{u}{u_e} \right) \right] dn \quad (28)$$

which in the transformed plane becomes

$$\delta_k^* = \left[\frac{L}{r_0} \right]^k \frac{(2\xi)^{\frac{1}{2}}}{\rho_\infty u_e} \int_0^{n_\infty} (1-f')(1+t)^{-k} dn \quad (29)$$

where

$$1+t = \left[1 + \frac{2L \cos \alpha}{r_0^2} \frac{(2\xi)^{\frac{1}{2}}}{\rho_\infty u_e} \int_0^{n_\infty} dn \right]^{\frac{1}{2}} \quad (30)$$

This relationship for ϵ_0 is the same for two-dimensional or axisymmetric flows as shown in Reference 24.

Low Reynolds number effects. - The calculation of turbulent boundary layers about two-dimensional and axisymmetric bodies must often be done at low Reynolds number, i.e., momentum thickness Reynolds number, R_θ , less than 6000. Most of the boundary layer methods including the one presented above are based on empirical data which were obtained at high Reynolds numbers. A correction term to account for low Reynolds numbers which was developed by Cebeci (Reference 25) based on prior work by Coles (Reference 26) is, therefore, applied to the outer eddy viscosity by varying the α in equation (27) with R_θ in the following manner.

$$\text{if } R_\theta < 425 \text{ then } \alpha = (.0168)(1.55) \quad (31a)$$

$$\text{if } R_\theta > 6000 \text{ then } \alpha = .0168 \quad (31b)$$

$$\text{if } 425 < R_\theta < 6000 \text{ then } \alpha = .0168 \left[\frac{1.55}{1+\Pi} \right] \text{ where}$$

$$\Pi = .55 \left[1 - e^{-0.243\sqrt{\gamma} - .298 \gamma} \right] \text{ and } \gamma = \left(r_\theta / 425 \right) - 1 \quad (31c)$$

Transverse curvature. - In developing the axisymmetric boundary layer equations a radius term is introduced as shown in equations (2) and (3). If the assumption is made that the body radius is very large compared to the boundary layer thickness then the radii in equations (2) and (3) reduce to the local body radius r_0 and the effect of the transverse (i.e.,

circumferential) curvature in the momentum equation is neglected. If, however, the body radius is small compared to the boundary layer thickness then the effect of the transverse curvature cannot be ignored and r must be a function of the distance into the boundary layer, y . The relationship between y , r_0 , and r is given by:

$$r = r_0 + y \cos \alpha \quad (32)$$

As observed in figure 3, α is simply the surface slope in the longitudinal direction. i.e.,

$$\tan \alpha = \frac{dr}{dx} \quad (33)$$

For slender cylinders where $\alpha = 0^\circ$,

$$r = r_0 + Y \quad (34)$$

The inclusion of the transverse curvature terms in the boundary layer equations is shown in References 24 and 27 to substantially improve the accuracy of the calculation of the local skin friction as well as the other viscous parameters.

Transition region effect. - The boundary layer method has the capability of calculating transition from laminar flow to turbulent flow in two different ways. The first approach is to use the transition point as a switching point between laminar and turbulent boundary layer calculations. At the transition point the turbulent boundary layer calculations are started by activating the eddy viscosity coefficient. In general, especially at low Reynolds numbers this approach can lead to errors as shown by Cebeci in Reference 28. The second approach which is available uses the intermittency factor given by Chen and Thyson (Reference 29) to modify the eddy viscosity equations to account for a region of transition. This modification was developed from the point of view of intermittent production of turbulent spots and is a further extension of Emmons' spot theory (Reference 30). The modification to be used is to multiply the inner and outer eddy viscosities equations (16) and (27) by the following parameter:

$$\gamma_{Tr} = 1 - e^{-Gr_o(x_{Tr}) \left[\int_{x_{Tr}}^x \frac{dx}{r_o} \right] \left[\int_{x_{Tr}}^x \frac{dx}{u_e} \right]} \quad (35)$$

$$G = \left(\frac{3}{3600} \right) \left(\frac{u_e^3}{v_\infty^2} \right) Re_{Tr}^{-1.34}$$

$$\text{where } Re_{Tr} = \frac{u_e x_{Tr}}{v_\infty}$$

The effect of this transition region correction can be seen in figure 4 which compares experimental data to theoretical calculations for local skin friction with and without the above correction on a two-dimensional ellipse. This transitional effect will be assumed to be the same for axisymmetric bodies.

Boundary layer transition location. - The location of boundary layer transition from laminar to turbulent flow can be either input to the boundary layer method or calculated internally within the program. The approach used to calculate the transition location is one developed for two-dimensional flow by Michel (Reference 31) and later verified by Smith (Reference 32). This method correlates the local momentum thickness Reynolds number, R_θ and the local distance Reynolds number, R_x , as shown in figure 5 which comes from Reference 32. The procedure used is to calculate the values of R_x and R_θ at each station and to compare them to the curve in figure 5. If the value of R_θ is less than the value of $R_{\theta TR}$ then transition has not been reached but if the value of R_θ is greater than $R_{\theta TR}$ then transition has occurred.

The above method was extended to axisymmetric flow by the use of Mangler's transformation. The parameters R_θ and R_x are calculated by the axisymmetric boundary layer routine and they are then transformed to two-dimensional values by the following relationships:

$$\theta_{2-D} = \left(\frac{r_o}{L} \right) \theta_{\text{AXISYMMETRIC}} \quad (36a)$$

$$x_{2-D} = \int_0^{x_{\text{LOCAL}}} \left(\frac{r_o}{L} \right)^2 (dx)_{\text{AXISYMMETRIC}} \quad (36b)$$

These values of θ_{2-D} and X_{2-D} are used to determine values of R_θ and R_x which can be used in conjunction with figure 5.

A study of transition location calculation for axisymmetric bodies was recently completed by Kaups (Reference 33). In this study empirical methods due to Granville, Hall and Gibbons, and the method of Michel presented above were compared to the stability analysis technique of Smith (Reference 32). It was determined that for flows where transition occurred in an adverse pressure gradient all of the above techniques predicted transition fairly accurately. For flows where transition occurred in favorable pressure gradients, only the method of Smith (Reference 32) gave satisfactory results as shown in figure 6 which is taken from Reference 33. The method of Smith, however, requires extremely lengthy computer calculation times which makes it undesirable for the iterative type of calculation presented in this report. Therefore, based on the results of Reference 33, the method of predicting transition in the present program should not be used for flows with very large Reynolds numbers where the transition location might occur in a favorable gradient, but rather the transition point should be input to the program.

Calculation Procedure

The viscous flow field about an axisymmetric body is simulated by calculating the inviscid flow about an equivalent "viscous" body which is formed by adding the boundary layer displacement thickness to the original body surface. This technique of defining the inviscid body has been used quite successfully for two-dimensional flows as shown in Reference 2 and has also been used for axisymmetric flows as presented in Reference 34. This equivalent body is formed by combining the previously discussed geometry routine, potential flow method, and boundary layer method under control of the axisymmetric design and analysis method computer program known as ADAM.

Given the desired axisymmetric configuration and flow conditions, the ADAM program utilizes these sections, as shown in figure 7, in the following iterative manner:

1. Precise geometry definition for input into the potential flow program.

2. Calculation of the exact nonlinear potential flow for specified geometry and flow conditions.
3. Calculation of the viscous flow characteristics based on the results of the potential flow program.
4. Addition of boundary-layer displacement thickness to the basic geometry for each element.
5. Recalculation of the pressure distribution utilizing the potential flow program, based on the redefined geometry.
6. Recalculation of viscous flow field based on recalculated pressure distribution from redefined geometry, if desired.
7. Possible iteration of the above scheme; the degree to which this is required is presented in the subsequent discussion on correlations with experimental data.

The above technique must be modified when the boundary layer separates or when the local body radius approaches zero at the trailing edge of the body. When the dimension of the local body radius approaches zero at the trailing edge, the boundary layer equations become invalid since the $1/r$ term in equation (3) approaches infinity. When this occurs, the boundary layer results are ignored from this point downstream to the trailing edge. The assumption is then made that the boundary layer displacement area at the point where

$$\delta^* \cos \alpha = r_o \quad (37)$$

is defined by

$$DAREA = \pi \left\{ \left(r_{op} + \delta^* \cos \alpha_p \right)^2 - r_{op}^2 \right\} \quad (38)$$

where p refers to the point where equation (37) is first satisfied. This displacement area is then considered to remain constant from the point p to the trailing edge. The new "viscous" body coordinates in this region are then defined by

$$y_{new} = \left\{ \frac{\pi r_o^2 + DAREA}{\pi} \right\}^{1/2} \quad (39)$$

The second problem area occurs when the boundary layer separates from

the body creating a separation bubble. This bubble must be accounted for in the creation of a "viscous" body if the flow about this configuration is to be predicted accurately. The simplest technique of modeling this separation bubble is to assume that the flow leaves the surface parallel to the free-stream direction, producing a cylindrical wake shape as shown in figure 8. This approach, however, gives decelerations in the flow at the junction of the body with the cylinder as shown in figure 9, which do not exist in the real flow field. To minimize this problem, a circular arc is used to fair the body into the separated cylinder.

This circular arc is defined by passing a circle through the last three "viscous" body coordinates defined prior to the separation point. The radius of this circle is then used to create a circular arc which is tangent to the "viscous" body at the point of separation. The center of this arc is then defined according to whether the surface slope of the body at separation is positive or negative.

If the surface slope is positive then the center is taken as the center of the circle passed through the three points as defined above. This center is defined by

$$x_c = x_{sep} + R \sin \left[\tan^{-1} \left| \frac{dy}{dx} \right| \right] \quad (40a)$$

$$y_c = y_{sep} - R \cos \left[\tan^{-1} \left| \frac{dy}{dx} \right| \right] \quad (40b)$$

where R = Radius of the circle

$\frac{dy}{dx}$ = Surface slope at separation

This arc is then used from the point of separation to either the end of the body or to the maximum point on the arc, where $dy/dx = 0$, as shown in figure 10a. If the maximum point of the arc occurs before the trailing edge of the body is reached then a cylinder is defined which extends from the maximum point of the arc to the trailing edge.

If the surface slope is negative then the circular arc is defined such that the center is located above the body. The center is then defined by

$$x_c = x_{sep} + R \left[\sin \tan^{-1} \left| \frac{\partial y}{\partial x} \right| \right] \quad (41a)$$

$$y_c = y_{sep} + R \left[\cos \tan^{-1} \left| \frac{\partial y}{\partial x} \right| \right] \quad (41b)$$

This arc is then used from the point of separation to either the end of the body or to the minimum point on the arc, where $dy/dx = 0$, as shown in figure 10b. If the minimum point of the arc occurs before the trailing edge of the body then a cylinder is defined which extends from the minimum point of the arc to the trailing edge of the body.

The above separated wake model has been derived from intuitive considerations rather than from first principals. It does, however, provide reasonable results, as will be shown in the subsequent discussion.

The base drag coefficient for blunt axisymmetric bodies is calculated using the method of Hoerner, reference 35. This approach is based on the assumption that the flow field behind a blunt base is basically a jet pump, in that, air flowing around the body leaves the trailing edge forming a cylindrical jet which attempts to pump away the stagnated air in the base region. However, since there is no air to replace this stagnated air, the pumping mechanism can only reduce the static pressure acting on the base. The effectiveness of this jet pump mechanism is controlled by the boundary layer thickness at the base since this region of lower momentum flow acts as a buffer between the stagnated air behind the base and the flow in the jet. Since the boundary layer thickness is directly related to the skin friction on the body, C_f , Hoerner used C_f to correlate with the base drag to develop an empirical approach to determine base drag. Figure 11 shows the correlation obtained by Hoerner for bodies whose base area is the same as the maximum area. This curve is represented by

$$C_{D\text{BASE}} = .029/\sqrt{C_{f\text{Forebody}}} \quad (42)$$

where the coefficients are based on the base area. Thus, once the skin friction on the forebody has been calculated in the boundary layer programs, then the base drag can be determined by equation 42.

This equation must be modified for boat-tailed bodies, that is, bodies whose base area is less than their maximum area. The mechanics of the base drag for these configurations do not change, but the calculation must take into account the reduced base area. This effect is taken into account by the following relationship:

$$C_{D_{BASE}} = C_{D_{BASE}} \cdot \left(\frac{d_{BASE}}{D_{MAX}} \right)^2 \quad (42a)$$

and

$$C_{f_B} = C_{f_B} \cdot \left(\frac{D_{MAX}}{d_{BASE}} \right)^2 \quad (43b)$$

(BOAT TAIL)

so

$$C_{D_{BASE}} = \frac{.029}{\sqrt{C_{f_B}}} \cdot \left(\frac{d_{BASE}}{D_{MAX}} \right)^3 \quad (43c)$$

BOAT TAIL

A comparison of results calculated by the above method in ADAM with experimental force data from reference 35 is presented in figure 12. One of these cases is for a boat-tailed body and the other for a body whose base area is also the maximum area.

The experimental data used for this comparison as well as the configuration used for the analytical calculations are both subject to some discussion. The experimental base drag, taken from Figure 4 of Reference 35, originally came from an old German report which is not readily available. These base drag values were obtained from both force measurements and pressure measurements which unfortunately do not agree. Therefore, since it was felt that the force measurements were the more accurate, they were used in the comparison shown in Figure 12. In addition, no good definition of the configuration tested was available, therefore, the geometry used in the ADAM analysis was taken from the schematics shown in Reference 35. In light of these uncertainties the comparison presented in Figure 12 is fairly good in that even though the levels are different, the trends are the same. It should be noted that this comparison was used only because there is a singular lack of experimental data for blunt based axisymmetric bodies at low subsonic Mach numbers.

EXPERIMENTAL CORRELATIONS

Experimental results from three different configurations were selected to establish the extent of validity of the method presented in this report. These geometries consisted of a high fineness ratio body of revolution, and a sphere in both subcritical and supercritical flow regimes. These correlations, while limited to some extent by the scope of the present effort, do represent a wide range of axisymmetric flow conditions.

The body of revolution chosen was tested in the low speed wind tunnel at the Douglas Aircraft Company, (Reference 36), and is shown in figure 13. This model was composed of three sections; an elliptical nose section, a cylindrical control section, and a parabolic afterbody. The calculation done for this configuration used the wind tunnel flow properties, namely, $U_{\infty} = 71.628$ M/Sec (235 Ft/Sec), $T_{\infty} = 288.3^{\circ}\text{K}$ (519.0°R) and $R_L = 10.05 \times 10^6$. Boundary layer transition was fixed on the model and in the calculation at .03048 meters (1.2 inches) from the nose. This model was relatively large for the wind tunnel in which it was tested; wall effects, not accounted for in the original data reduction, were present. To correct for this, the model was run in the potential flow program in the presence of the wind tunnel walls as shown in figure 14. The effect of including the walls in the calculation is shown in the inviscid pressure distributions of figure 15. The final results for this configuration are shown in figure 16 where the calculated "viscous" results are compared to experimental data. The inviscid distribution is also shown for reference. In this particular case no separation occurred and so only one iteration, that is, two potential flow solutions and two boundary layer solutions, was necessary. The calculated "viscous" results agree very well with the experimental values except in the region of the nose. This discrepancy is not due to the calculation method, but rather is due to the model being too long for the wind tunnel test section resulting in the nose being in a different static pressure field than the rest of the body. The overall effect of viscosity on this configuration is seen to be small except in the region of the trailing edge. The body is so slender in this region that the boundary layer equations are no longer valid so the technique described in the calculation procedure was used to modify the viscous body. The results show a pressure oscillation

in this modified region which is due to an unsmooth curvature distribution. However, the level of these pressures agree quite well with the experimental values.

The second case considered was that of a sphere in the supercritical flow regime, i.e., $R_D = 1 \times 10^6$. Since the boundary layer transition was forced to occur at an $X/D = .65$, there were regions of both laminar and turbulent flow present. The experimental data for this case were taken from references 37 and 38. The freestream velocity assumed for this case was 47.85 M/Sec (157 Ft/Sec). Figure 17 shows the sphere with the "viscous" body superimposed and figure 18 presents a comparison between the calculated "viscous" solution and experimental data. Note that while the calculated pressure distribution is in reasonably good agreement with the experimental values, the calculated separation point is .07 diameters further downstream than the experimentally measured value. The inviscid and "viscous" solutions for the local skin friction coefficient, C_f , are presented in figure 19. The "viscous" solution shown is the fourth iteration, i.e., the fifth potential flow solution, and appears to be the best solution possible for this configuration with the technique being used in the present method to simulate flow separation.

The last correlation to be presented is for the flow about a sphere in the subcritical regime, i.e., $R_D = 1 \times 10^5$, which is a purely laminar case. The experimental data is again taken from Reference 37. The freestream velocity for this case was assumed to be 4.785 M/Sec (15.7 Ft/Sec). The calculated "viscous" body is shown in figure 20 while a comparison of the "viscous" pressure distribution to experimental data is shown in figure 21. The calculated "viscous" pressures are in close agreement with the experimental values with some slight over-prediction in the separated region. The calculated separation point is only .03 diameters further downstream than the experimental value which is excellent considering the large effect that viscosity has on this configuration. Figure 22 presents the inviscid and "viscous" solutions for the local skin friction coefficient for this case.

CONCLUDING REMARKS

A method has been presented for the computation of the viscous flow field about axisymmetric bodies at zero angle of attack in incompressible flow. This computing program requires only the specified body geometry and desired flow conditions as input. The appropriate theory has been discussed and correlations between theoretical and experimental results presented.

The flow field about axisymmetric bodies at zero angle of attack with no flow separation is well defined and can be computed accurately by the present method. When flow separation occurs, the flow field is no longer amenable to analytical treatment. Currently, methods do not exist to calculate the flow field within a separated region; it is therefore necessary to resort to empirical methods to account for flow separation. Since there is almost a complete lack of experimental data concerning the behavior of separated regions, any empirical methods must necessarily be somewhat crude. The most sophisticated model for separation currently available is due to Jacob (References 39 and 40) and is strictly for two-dimensional airfoils. An unsuccessful attempt was made in Reference 41 to adapt Jacob's approach to axisymmetric configurations. The conclusions of Reference 41 indicated that the assumed boundary conditions needed to be modified if this approach was to be used for axisymmetric flow. It is proposed that the Douglas-Neumann program be used to pursue this approach at modeling separation. This potential flow program is ideal for attempting to use Jacob's technique since it already has the ability to specify a non-uniform flow distribution over all or part of a configuration; therefore, only suitable boundary conditions would have to be added to the program. It is felt that this approach can be successful in modeling separation if care is taken in developing the distribution of non-uniform velocity as well as specifying the proper boundary considerations.

The further extension of this model to the calculation of flow about axisymmetric bodies at angle of attack is also possible. The potential flow routine contained in the present method has the capability of predicting the flow field about non-lifting bodies at angle of attack by combining the streamflow and the crossflow solutions. The boundary layer analysis would require the replacement of the routine in the present method by a three-dimensional

technique, which is currently not available. However, it is felt that a good approximation to the boundary layer calculations can be made by the small crossflow program of Reference 42.

One area of primary concern in extending the method to include an angle of attack capability is the determination of the separation line about the body. The present method of predicting separation for two-dimensional bodies and for axisymmetric bodies at zero angle of attack is to find the location where the skin friction goes to zero. It has been shown in several studies, including those reported in References 43 and 44, that this condition does not apply in three-dimensional flows because the skin friction along a separation line is not necessarily zero. Therefore, some method of determining the separation line for axisymmetric bodies at angle of attack must be developed. It is proposed that the present method could be extended to calculate the "viscous" flow about axisymmetric bodies at angle of attack when no flow separation is present. This method could then be used to assist in the development of a procedure for determining the separation line location. Once the location of the separation line is known then a model could be developed for analyzing the viscous flow about the separated body. The development of such procedures is not a simple task and considerable effort would have to be expended; but the reward for accomplishing this task is an advance in the ability to calculate the real flow about arbitrary three-dimensional bodies which is our ultimate goal.

APPENDIX A

INPUT INFORMATION FOR ADAM COMPUTER PROGRAM

This part of the report contains the necessary information to input data to the ADAM computer program. The input data is broken into three sections: smoothing, potential flow, and viscous flow. These sections can be used together in the iterative fashion described in the main text, or the potential flow and viscous flow sections may be used independently. A detailed card-by-card description of all input quantities is given followed by a set of input forms which can be used to facilitate the loading of the input data into the program.

Input Instructions

The Adam program requires one system control card followed by the required sets of data cards for each program option to be executed. The sets of data furnished must be in the same order as the options are specified on the system control card. If an iteration is desired the system control card is repeated along with the necessary other data cards.

The general scheme used in describing the input data is shown below:

<u>Column</u>	<u>Code</u>	<u>Routine Format</u>	<u>Explanation</u>
Column -	Column	indicates	the starting position on the card for each data field.
Code -	The "code"	gives the FORTRAN name used in the read statement by the program.	
Routine -	"Routine"	indicates the subroutine where the data is read.	
Format -	The parameter "FORMAT"	which is given right under the routine name, indicates the FORTRAN format of the data read statement field. The parameter I5 would indicate that the parameter is an integer in a field that is 5 columns wide. Integers should be punched on the right side of the field (right justified). The parameter F10.0 would indicate a fixed point number punched with a decimal point (i.e., -12.354). The number may be punched anywhere in the field indicated irrespective of the decimal point location indicated by the format. The parameter E12.6 would indicate a floating point number punched with a decimal point (i.e., 5.0×10^6). The number must be punched to the right of the field in the manner 5.0E+06.	
Explanation -	The description of the input data	is given under "explanation".	

SUSTEM CONTROL DATA CARD (This card must be the first card in the data deck)

<u>Column</u>	<u>Code</u>	<u>Routine Format</u>	<u>Explanation</u>
4	IGEOM	MAIN I1	Smoothing option flag =0 no smoothing is desired =1 smoothing is desired
8	INEUM	MAIN I1	Potential flow option flag =0 No potential flow solution is desired =1 Potential flow solution is desired
12	IBOUND	MAIN I1	Boundary layer option flag =0 No boundary layer solution is desired =1 Boundary layer solution is desired
16	ITER	MAIN I1	"Viscous" body formation flag =0 No "viscous" body is formed =1 "Viscous" body is formed
17-20	IFINSH	MAIN I4	Termination Flag =0 Another case expected =9999 Program will stop after exer- cising all options specified above

SMOOTHING SECTION

These cards required if IGEOM = 1 on system control card. This section is used to smooth body geometry data before it is input to the potential flow program.

Smoothing Control Card

<u>Column</u>	<u>Code</u>	<u>Routine Format</u>	<u>Explanation</u>
2	NPTS	SMOOTH I3	Number of input data points for this configuration. NPTS must be ≤ 100
8	ITAPE	SMOOTH I1	Data source flag =0 Data input on unit 5 (card input) ≠0 Data input on unit 1. This is used for a case where a "viscous" body generated by the iteration procedure is being read.

Geometry Data Input Cards

These cards are input only if ITAPE = 0.

<u>Column</u>	<u>Code</u>	<u>Routine Format</u>	<u>Explanation</u>
<u>x-coordinate cards</u>			
1-10	x(1)	SMOOTH	x-coordinates starting at the leading edge and proceeding along the upper surface to the trailing edge. Input 6 x-values on each card. The numbers of x-values must be equal to NPTS.
11-20	x(2)	6F10.0	
21-30	x(3)		
etc.			
<u>y-coordinate cards</u>			
1-10	y(1)	SMOOTH	y-coordinates to correspond to the above x-locations. y-values must be positive. Input 6 values per card.
11-20	y(2)	6F10.0	
21-30	y(3)		
etc.			

POTENTIAL FLOW SECTION

These cards required if INEUM = 1 on system control card. The input geometry for this program may be obtained from the geometry storage unit (10) as generated by the smoothing section, or it may be input directly on unit 5. Thus, this program may be operated as a separate entry if so desired. The program saves the geometry data element midpoints with the corresponding pressure coefficients on unit 3 for input to the boundary layer routine and it saves the basic non-dimensional input Neumann coordinates on unit 1 for use if a "viscous" body is desired.

Title Card

<u>Column</u>	<u>Code</u>	<u>Routine Format</u>	<u>Explanation</u>
1	HEDR	PART1 10A6	Title of case. May be any characters input in the first 60 columns of card.
63	CASE	PART1 I6	Case number
77	PSF	PART1 I6	Additional identifier for this case.

Flag Card

Card columns 1-30 when punched with any non-zero integer, activate flags that indicate the following:

<u>Column</u>	<u>Code</u>	<u>Routine Format</u>	<u>Explanation</u>
1	NB	PART1 I1	The number of bodies input. Normally set equal to 1. $1 \leq NB \leq 5$
2	NNU	PART1 I1	The number of non-uniform onset flows. Normally set equal to 0.
3	FLG03	PART1 I1	Axisymmetric flow flag. =0 No axisymmetric stream-flow solution calculated. =1 Axisymmetric streamflow solution is calculated Normally set equal to 1

Flag Card (Continued)

<u>Column</u>	<u>Code</u>	<u>Routine Format</u>	<u>Explanation</u>
4	FLG04	PART1 I1	Cross flow flag. =0 No cross flow solution is calculated =1 Cross flow solution is calculated Normally set equal to 0
5	FLG05	PART1 I1	Off-body point flag =0 No off body points input =1 Off body points are input This flag allows the velocity at points off the body surface to be determined.
6	FLG06	PART1 I1	Basic data formation flag =0 A full case will be done =1 The basic data, i.e., midpoints, normals, etc. will be formed and printed. No velocities will be calculated.
7	FLG07	PART1 I1	Ellipse generator option =0 Body coordinates will be input =1 An ellipse is generated using data input later. No body coordinates are input
8	FLG08	PART1 I1	Matrix print flag =0 Coefficient matrices are not printed. =1 Coefficient matrices will be printed. Normally set equal to 0
11	FLG11	PART1 I1	Perturbation velocity flag =0 Normal case =1 No onset flow used. Only per- turbation velocities are calculated.
12	FLG12	PART1 I1	Potential matrix solution * =0 Normal case =1 A potential matrix is solved

Flag Card (Continued)

<u>Column</u>	<u>Code</u>	<u>Routine Format</u>	<u>Explanation</u>
13	FLG13	PART1 I1	Matrix solution flag =0 No matrix solution done =1 Matrix solution performed Normally set equal to 1.
14	FLG14	PART1 I1	Prescribed tangential velocity flag * =0 Normal case =1 Tangential velocities are specified
15	FLG15	PART1 I1	Strip ring vorticity flag * =0 Normal case =1 A vorticity distribution is formulated.
16	FLG16	PART1 I1	Axisymmetric uniform flow flag =0 Normal case =1 Axisymmetric uniform flow solution is omitted Normally set equal to 0.
17	FLG17	PART1 I1	Crossflow uniform flow flag =0 Normal case =1 Crossflow uniform flow solution is omitted. Since FLG04 is normally = 0 then so is FLG17 normally set equal to 0.
18	FLG18	PART1 I1	Surface vorticity flag * =0 Normal case =1 Surface vorticity is generated.
19	FLG19	PART1 I1	Prescribed vorticity Flag * =0 Normal case =1 A prescribed vorticity is input
20	FLG20	PART1 I1	Total vorticity flag * =0 Normal case =1 Total vorticity calculated

Flag Card (Continued)

<u>Column</u>	<u>Code</u>	<u>Routine Format</u>	<u>Explanation</u>
21	FLG21	PART1 I1	Extra crossflow flag * =0 Normal case =1 Extra crossflow option used
22	FLG22	PART1 I1	Generated boundary condition flag * =0 Normal case =1 Boundary conditions generated
23	FLG23	PART1 I1	Ring wing option flag * =0 Normal case =1 Ring wing option used
28-29	NIN	PART1 I2	Tape input flag =0, 10 Data input on unit 10 from smoothing program =5 Data input from unit 5 (card input)
30	ITER	PART1 I1	Iteration tape flag =0 x/c, y/c transformed data saved on unit 15 =1 x/c, y/c transformed data not saved. This flag is necessary because for a "viscous" body to be formed, the coordinates of the original unmodified body must be saved. Therefore, for the first case set ITER = 0. For subsequent iterations we do not want to use the modified bodies to form new bodies so set ITER = 1.

* These flags are for special options which are discussed in the main text. They are never used for a normal axisymmetric calculation. Therefore, set them equal to zero.

Chord Card

<u>Column</u>	<u>Code</u>	<u>Routine Format</u>	<u>Explanation</u>
1	CHORD	PART1 F10.0	Reference chord length used to non-dimensionalize x and y coordinates
11	MN	PART1 F10.0	Mach number (MN < 1.0) use to approximate effect of compressibility (Gothert's rule)
21	TCNST	PART1 F10.0	This is a constant which is used for the value of the tangential velocity if this option is desired.

Body Transformation Card

<u>Column</u>	<u>Code</u>	<u>Routine Format</u>	<u>Explanation</u>
8	NN	BASIC1 I3	The number of input points on this body. $NN \leq 100$
11	MX	BASIC1 F10.0	A factor used to multiply all x-coordinates. MX is assumed equal to 1 if no value is input.
21	MY	BASIC1 F10.0	A factor used to multiply all y-coordinates. MY is assumed equal to 1 if no value is input.
31	THETA	BASIC1 F10.0	An angle (in degrees) through which all points of a body are to be rotated about the origin in the clockwise direction.
41	ADDX	BASIC1 F10.0	A constant to be added to all x-coordinates
51	ADDY	BASIC1 F10.0	A constant to be added to all y-coordinates

Body Control Card

<u>Column</u>	<u>Code</u>	<u>Routine Format</u>	<u>Explanation</u>
10	BDN	BASIC1 I1	Body sequence number. This program will handle up to 5 bodies.
20	SUBKS	BASIC1 I1	Subcase Flag. =0 Normal case =1 Use unmodified coordinates of the previous case.
30	NLF	BASIC1 I1	Non-lifting flag =0 Body is non-lifting (normal case) =1 Body is lifting (this is used in special option)
31	XE	BASIC1 F10.0	Value of major semi-axis for use by ellipse generation option.
41	YE	BASIC1 F10.0	Value of minor semi-axis for use by ellipse generation option Note: if XE = YE a sphere will be formed.

Geometry Data Cards

The body geometry data cards are included only if the input parameters NIN = 5 and FLG07 = 0 on the flag card. If NIN = 0 or 10 then the data is read from unit 10. If NIN = 5 and BDN = 0, then the following cards contain the x-y coordinates of off-body points instead of x-y geometry data. The number of either geometry data point or off-body points must be equal to NN.

x-Coordinate cards (six values per card)

<u>Column</u>	<u>Code</u>	<u>Routine Format</u>	<u>Explanation</u>
1	TX1(1)	BASIC1 6F10.0	x-coordinates of body input from leading to trailing edge.
11	TX1(2)		
21	TX1(3)		

y-Coordinate cards (six values per card)

<u>Column</u>	<u>Code</u>	<u>Routine Format</u>	<u>Explanation</u>
1	TY1(1)	BASIC1 6F10.0	y-Coordinates of body which correspond to the x-values above. y values must be positive.
11	TY1(2)		
21	TY1(3)		
	etc.		

NOTE: Each body input, including the off body points, requires the body transformation card, the body control card, and may also require the geometry data cards depending on the input flags. This is the stopping place for a normal axisymmetric case. The following cards are input only if one of the special options is required.

Tangential Velocity Data (six values per card)

These cards are input only if FLG14 \neq 0 and TCNST = 0.0

<u>Column</u>	<u>Code</u>	<u>Routine Format</u>	<u>Explanation</u>
1	TG(1)	BASIC1 6F10.0	Specified tangential velocities at element midpoints.
11	TG(2)		
21	TG(3)		
	etc.		

Non-uniform Flow Cards (six values per card)

These cards are input only if NNU \neq 0.

<u>Column</u>	<u>Code</u>	<u>Routine Format</u>	<u>Explanation</u>
6	NUM	BASIC2 I5	Non-uniform flow identification number.

Non-uniform Flow Cards (Continued)

<u>Column</u>	<u>Code</u>	<u>Routine Format</u>	<u>Explanation</u>
19	MSF	BASIC2 I2	<p>If MSF = 0 the flow velocities N_o, T_o will be used for the axisymmetric case only.</p> <p>If MSF = 1 the flow velocities N_o, T_o will be used for the cross flow case only.</p> <p>If MSF > 1 the flow velocities will be used for both axisymmetric and cross flow cases.</p>
21	TYPE	BASIC2 F10.0	<p>Flag which specifies the type of input flow velocities at each mid-point. If TYPE > 0.0, the velocities are input as x & y components.</p> <p>If TYPE = 0.0 the velocities are input as normal & tangential components.</p> <p>If TYPE < 0.0 the automatic generation of the flow due to a rotating body is used.</p>
31	FG	BASIC2 F10.0	<p>Constant used by the flow generator. Type must be less than 0.0.</p>

The following cards are input only if NNU \neq 0 and TYPE \neq -1.0.

Normal velocity cards (six values per card)

<u>Column</u>	<u>Code</u>	<u>Routine Format</u>	<u>Explanation</u>
1	NO(1)	BASIC2	<p>This is either the x or normal velocity component depending on the value of type above. These values must be in sequence with the coordinate data. If the x component is input it is defined as positive to the right. If the normal velocity is input it is positive if it is to the interior of the body.</p> <p>NN-1 values are input.</p>

Tangential Velocity Cards (six values per card)

<u>Column</u>	<u>Code</u>	<u>Routine Format</u>	<u>Explanation</u>
1	TO(1)	BASIC2 6F10.0	This is either the y or tangential velocity component depending on the value of type above. These values must correspond to the NO values above. If the y component is input it is defined as positive if it is orientated upwards. If the tangential velocity is input it is positive if the flow field is to the left of the vector representing the tangential velocity.

VISCOUS FLOW SECTION

These cards required if IBOUND = 1.

BOUNDARY LAYER PROGRAM

The geometry and pressure distribution data required by this program may be input directly on cards (Unit 5), or read from the data save unit (Unit 3) as generated by the Neumann program.

HEADER CARD

This card is supplied purely for description purposes.

<u>Column</u>	<u>Code</u>	<u>Routine Format</u>	<u>Explanation</u>
1-60	TITLE	INPT 15A4	Description of input
61	CASE	INPT A4	Case number

Flag Control Card

This card contains flags which control the type of flow to be considered and the form of the input.

<u>Column</u>	<u>Code</u>	<u>Routine Format</u>	<u>Explanation</u>
1	NXT	INPT I4	The number of the x-station where the flow goes turbulent measured from the stagnation point (i.e., the leading edge for axisymmetric bodies at zero angle of attack) if transition is to be calculated by the program set NXT to be one greater than the number of points input.
5	LG16	INPT I1	Transition flag =0 Boundary layer transition point is input =1 Boundary layer transition point is computed. Set NXT to be greater than number of points input.

Flag Control Card (Continued)

<u>Column</u>	<u>Code</u>	<u>Routine Format</u>	<u>Explanation</u>
6	LG17	INPT I1	Transition control flag =0 Transition is instantaneous =1 Transition is gradual (transitional region used)
7	LG18	INPT I1	Transverse curvature flag =0 No transverse curvature correction used. =1 Transverse curvature corrections applied.
8	LG32	INPT I1	Print control flag =0 Print using long format (with velocity profiles) =1 Use short printout (no velocity profiles)
9	LG26	INPT I1	Velocity input control flag =2 Velocity ratio (U_e/U_∞) is input =3 Pressure coefficient (c_p) is input.
10	LG40	INPT I1	Unit input flag for geometry and velocity data. =0 Data read from unit 3 as generated by the potential flow program. #0 Data read from cards (unit 5)
11	LG41	INPT I1	System of units FLAG =0 English system of units =1 International system of units

Flow Condition Card

<u>Column</u>	<u>Code</u>	<u>Routine Format</u>	<u>Explanation</u>
1	TI	INPT F10.0	Reference static temperature used to compute the reference fluid properties. If TI is input as zero then TI is set equal to either 288.33°K or 519°R depending on FLAG LG41

Flow Condition Card (Continued)

<u>Column</u>	<u>Code</u>	<u>Routine Format</u>	<u>Explanation</u>
11	RMI	INPT F10.0	Reference or free-stream Mach number. =0.0 UI is input next ≠0.0 UI is computed from RMI.
21	UI	INPT F10.0	Reference or free-stream velocity =0.0 M_∞ is input above ≠0.0 M_∞ input as zero above.
31	FK	INPT F10.0	Flow index =0.0 2-D flow assumed =1.0 Axisymmetric flow assumed
41	RL	INPT F10.0	Chord or reference length
51	RI	INPT E12.0	Reynolds number/foot

$$R_c / \ell = \frac{U_\infty}{\nu}$$

If CHORD = 1.0 then RI must be Reynolds number based on CHORD.

NOTE: The input of either Mach number or freestream velocity is for convenience only. This program is entirely incompressible.

Radius card

<u>Column</u>	<u>Code</u>	<u>Routine Format</u>	<u>Explanation</u>
1	ROMAX	INPT F10.0	Maximum radius of body. This is used to obtain frontal area for skin friction calculation.
11	DETA1	INPT F10.0	Initial step size of boundary layer velocity profile grid. For a case which contains turbulent flow set DETA1 = .005.

Radius card (continued)

<u>Column</u>	<u>Code</u>	<u>Routine Format</u>	<u>Explanation</u>
21	VGP	INPUT F10.0	VGP is the growth factor for the boundary layer velocity profile grid; for cases with turbulent flow set equal to 1.14. NOTE: For laminar cases the boundary layer velocity profile grid may be made constant if VGP = 1.0 is input. However, if this is done the minimum value of DETAI that can be input is approximately .10. This can be calculated if the value of the transformed boundary layer thickness, ETAINF, is known. Then DETAI becomes $DETAI = \frac{ETAINF}{100}$

Geometry-Pressure Distribution Cards

These cards input only if LG40 \neq 0.

Point Number Card

<u>Column</u>	<u>Code</u>	<u>Routine Format</u>	<u>Explanation</u>
1	NXM	INPT I4	Number of data points to be input. Maximum of 100 points allowed.

x-Coordinate Data Cards

<u>Column</u>	<u>Code</u>	<u>Routine Format</u>	<u>Explanation</u>
1	XS(1)	INPT	x-coordinate points input from leading to trailing edge input 6 points per card. Number of points = NXM
11	XS(2)	6F10.0	
21	XS(3)		

etc.

y-Coordinate Data Cards

<u>Column</u>	<u>Code</u>	<u>Routine Format</u>	<u>Explanation</u>
1	YS(1)	INPT 6F10.0	y-coordinate points corresponding to x-coordinates above input 6 points per card.

y-Coordinate Data Cards (continued)

<u>Column</u>	<u>Code</u>	<u>Routine Format</u>	<u>Explanation</u>
11	YS(2)		
21	YS(3)		
etc.			

Pressure Distribution Cards

<u>Column</u>	<u>Code</u>	<u>Routine Format</u>	<u>Explanation</u>
1	UE(1)	INPT 6F10.0	Velocity-pressure-distribution points corresponding to x-points input above input 6 points per card.
11	UE(2)		
21	UE(3)		If LG26 = 2 u_e/U_∞ input LG26 = 3 c_p input
etc.			

A D A M

AXISYMMETRIC DESIGN AND ANALYSIS METHOD

IGEOM		INEUM		IBOUND		ITER		IFINSH	
cc	4	4	8	12	16	20			

SYSTEM CONTROL DATA GARD

cc	4	IGEOM	=	0	NO SMOOTHING REQUIRED	=	1	FIVE-POINT SMOOTHING USED
cc	8	INEUM	=	0	NO POTENTIAL FLOW	=	1	NEUMANN ROUTINE USED
cc	12	IBOUND	=	0	NO BOUNDARY LAYER SOLUTION DESIRED	=	1	BOUNDARY LAYER SOLUTION WILL BE DONE
cc	16	ITER	=	0	NO "VISCOUS" SOLUTION IS DESIRED	=	1	A "VISCOUS" BODY WILL BE CREATED
cc	17	IFINSH	=	0000	ANOTHER CASE IS EXPECTED	=	9999	THIS IS THE LAST CASE

Instructions to Keypunch:
Do not punch blank columns

ENGINEER	PHONE
DATE	PAGE OF

SMOOTHING PROGRAM

SMOOTHING CONTROL CARD

NPTS ITAPE

NPIS
ITAPE

8422

4

ENGINEER _____ **PHONE** _____

PHONE

DATE _____ PAGE _____ OF _____

PAGE

FO

Instructions. to Keypunch
Do not punch blank columns

HEADER - DESCRIPTION

HEADER - DESCRIPTION	CASE	ID
	60	68
	63	77

cc 1 11 23 28

CHORD	MN	TCNST
-------	----	-------

NN	MX	MY	THETA	ADDX	ADDY
----	----	----	-------	------	------

	BDN	SUBKS	NLF	XE	YE
--	-----	-------	-----	----	----

ENGINEER PHONE

Instructions to Keypunch
Do not punch blank columns

DATE PAGE OF

A D A M

BOUNDARY LAYER PROGRAM

TITLE																																																												CASE
																																																											61	

cc 1

FLAG CONTROL CARD

N										2									

cc 2

TI	RMI	UI	FK	RL	RI
11	21	31	41	51	E

cc 1

RADIUS CARD

ROMAX	DETAL	VGP
11	21	

cc 1

ENGINEER _____ PHONE _____

DATE _____ PAGE _____ OF _____

Instructions to Keypunch
Do not punch blank columns

COORDINATE DATA OR VELOCITY CARDS

[illegible]

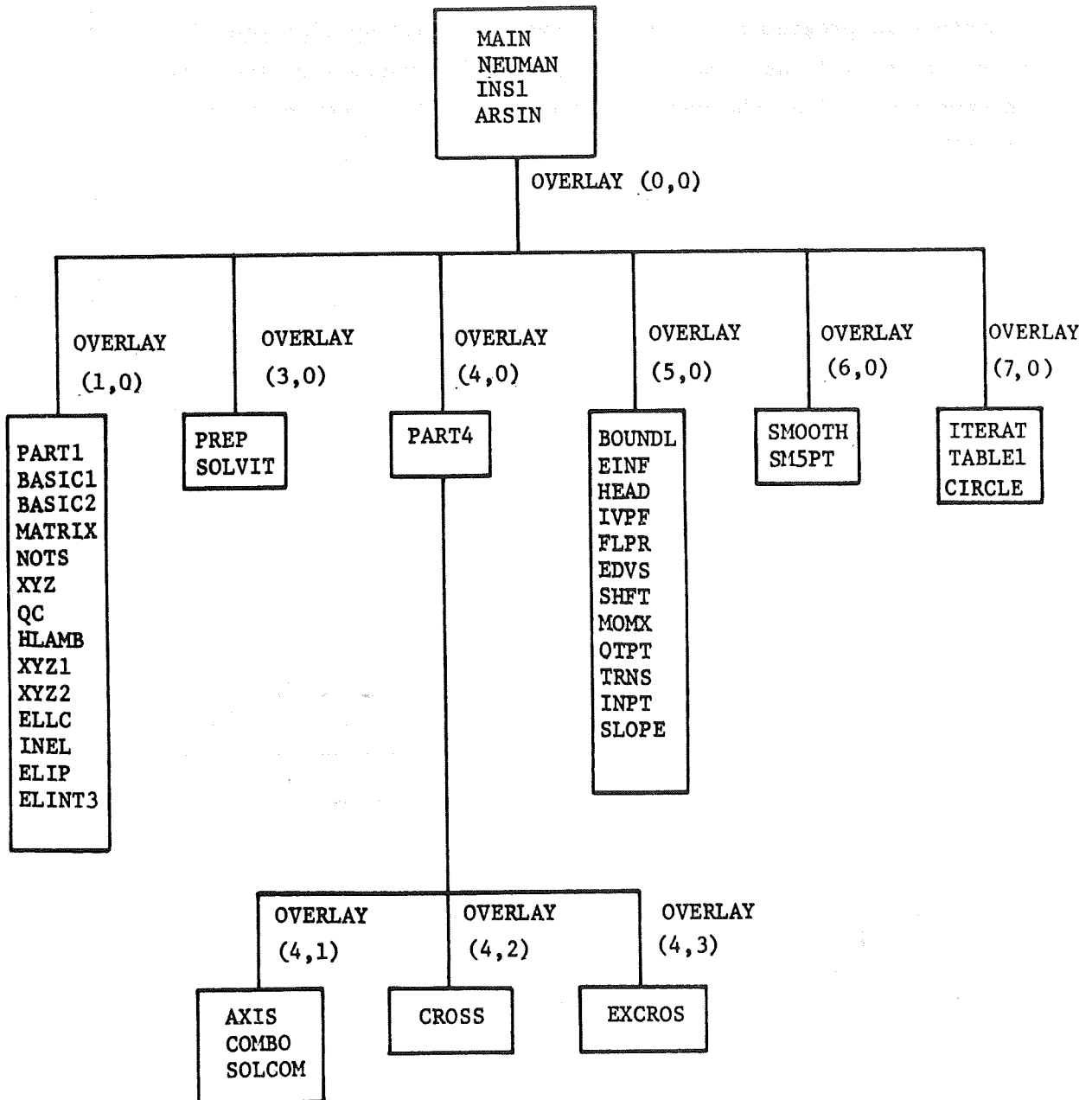
THIS INPUT FORM IS THE SAME FOR GEOMETRY DATA INPUT TO THE SMOOTHING ROUTINE, THE POTENTIAL FLOW PROGRAM, AND THE BOUNDARY LAYER ROUTINE. THIS FORM IS ALSO USED FOR VELOCITY DATA INPUT TO THE BOUNDARY LAYER PROGRAM AND FOR THE NON-UNIFORM VELOCITY DATA WHICH CAN BE INPUT TO THE POTENTIAL FLOW ROUTINE.

APPENDIX B

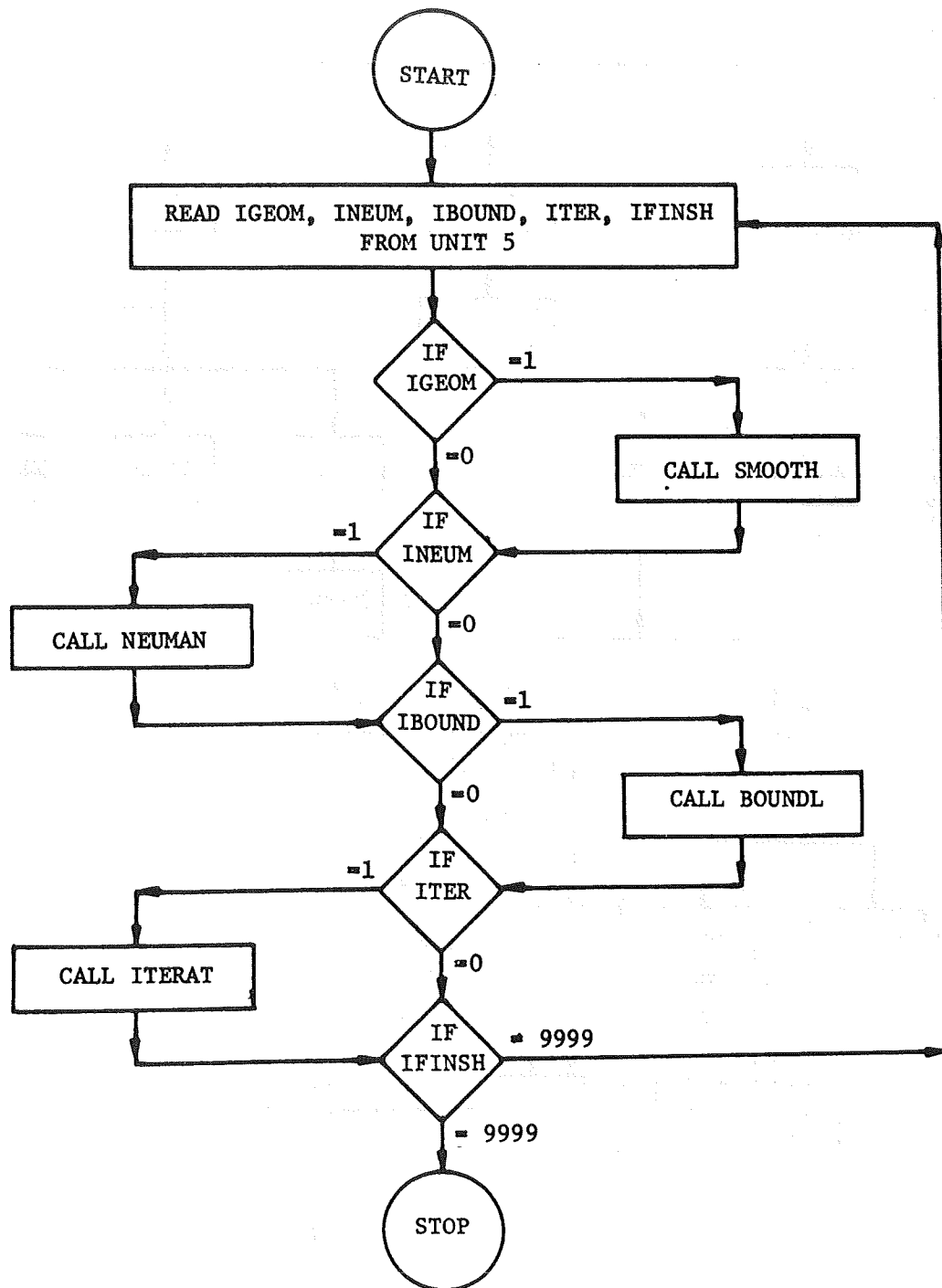
CONTROL INFORMATION FOR ADAM COMPUTER PROGRAM

This part of the report contains the necessary control information to operate this program on a computer system. This section contains the overlay structure as well as flow charts of the main subroutines including input flow information. Also, the various data sets used between main programs are described.

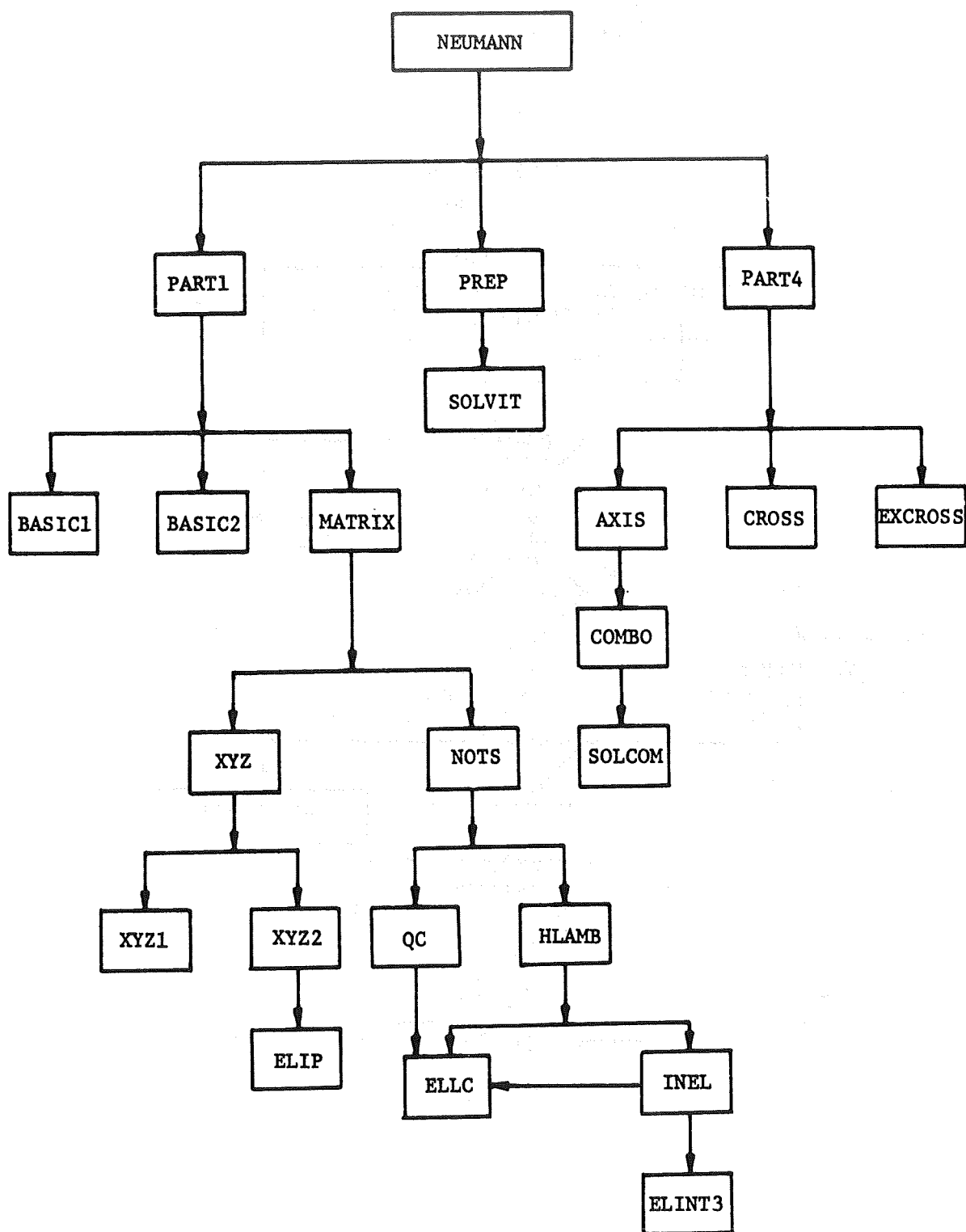
OVERLAY STRUCTURE OF ADAM



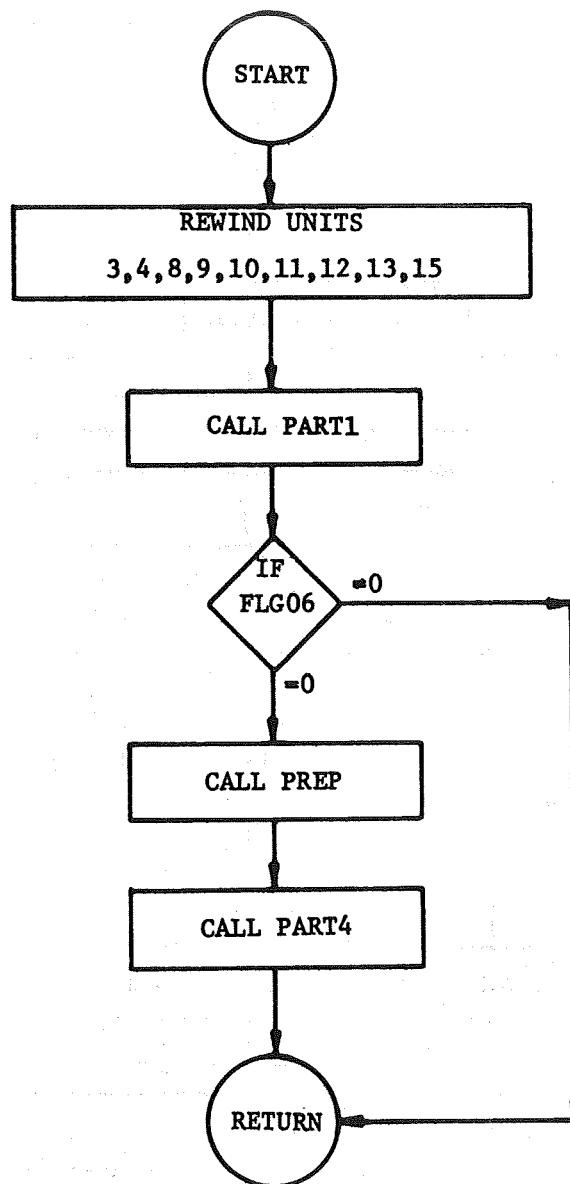
MAIN PROGRAM



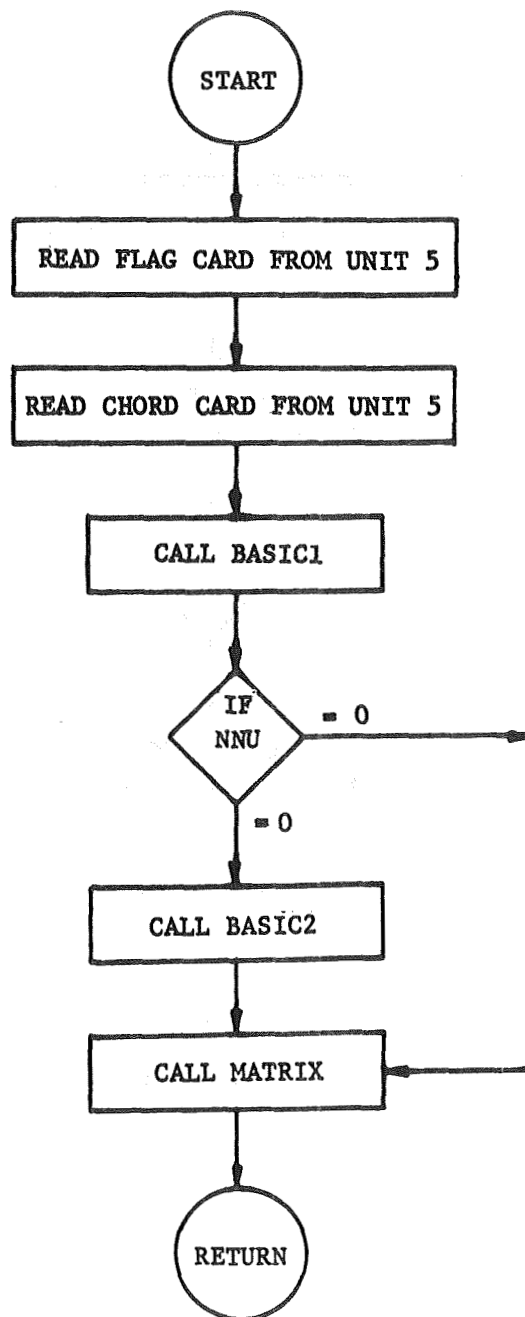
FUNCTIONAL ORGANIZATION OF NEUMANN PROGRAM



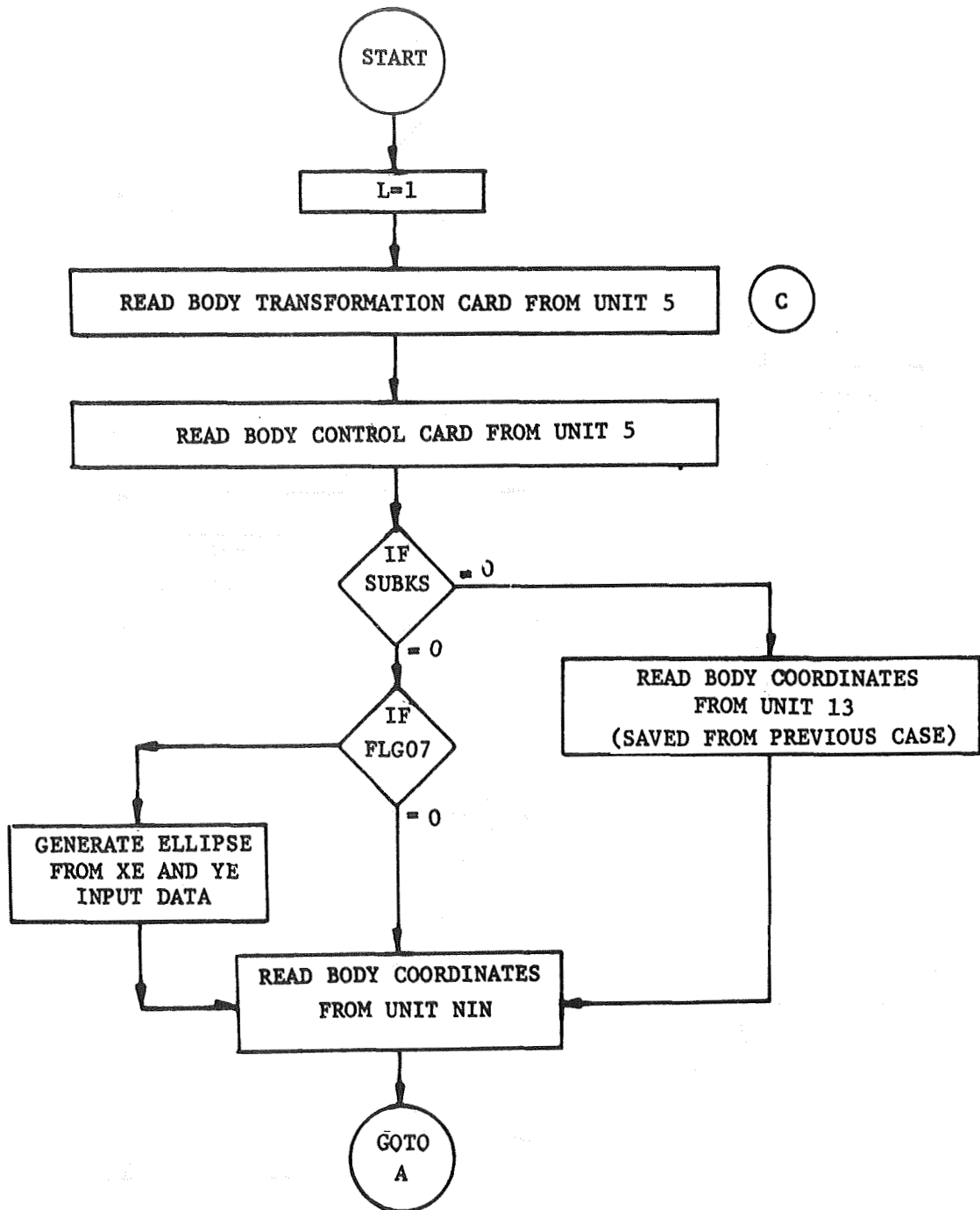
BASIC FLOW CHART FOR SUBROUTINE NEUMANN



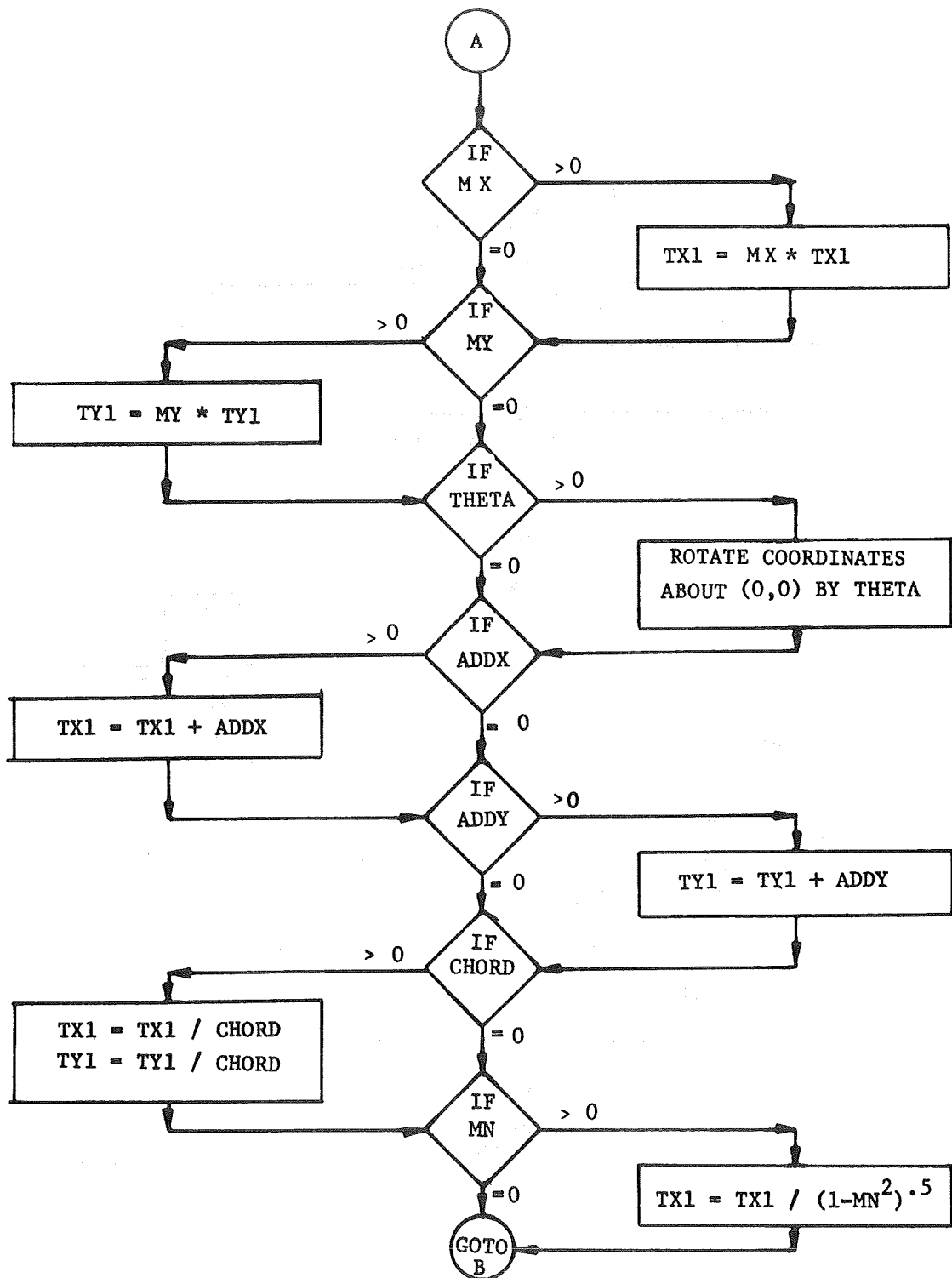
BASIC FLOW CHART FOR SUBROUTINE PART1



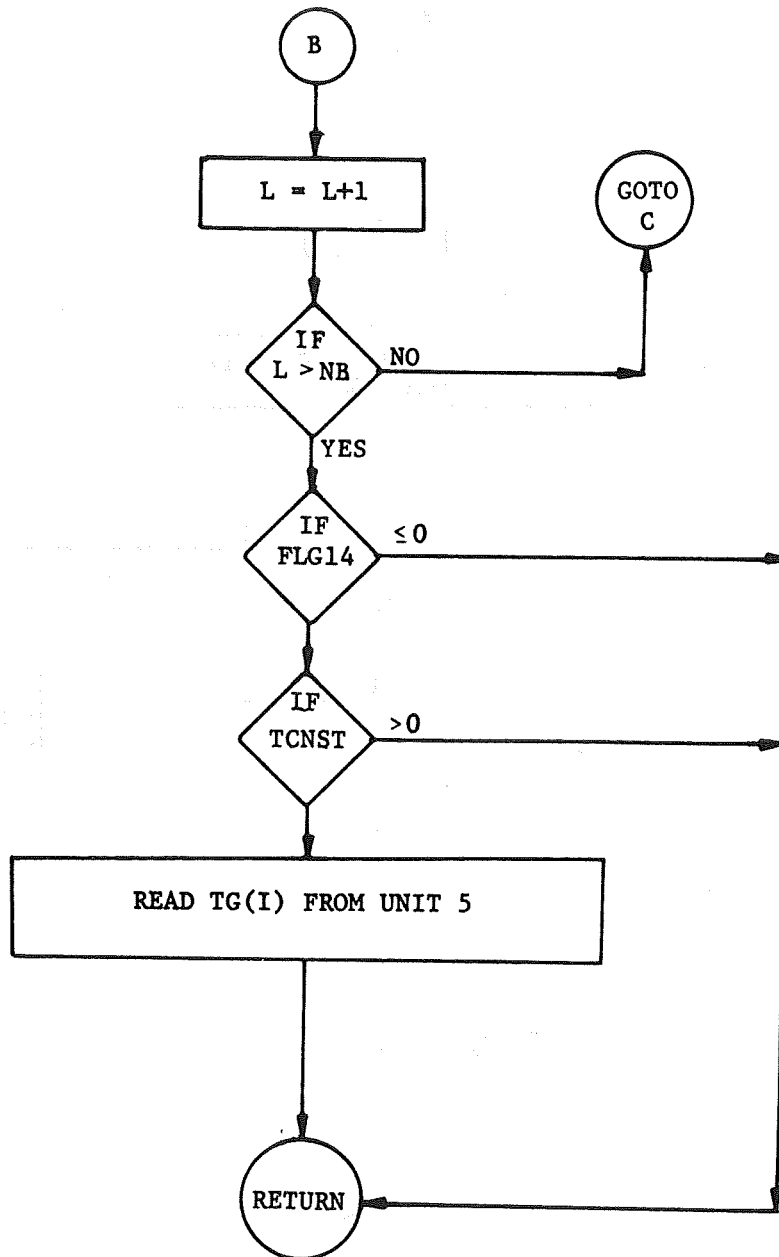
BASIC FLOW CHART FOR SUBROUTINE BASIC1



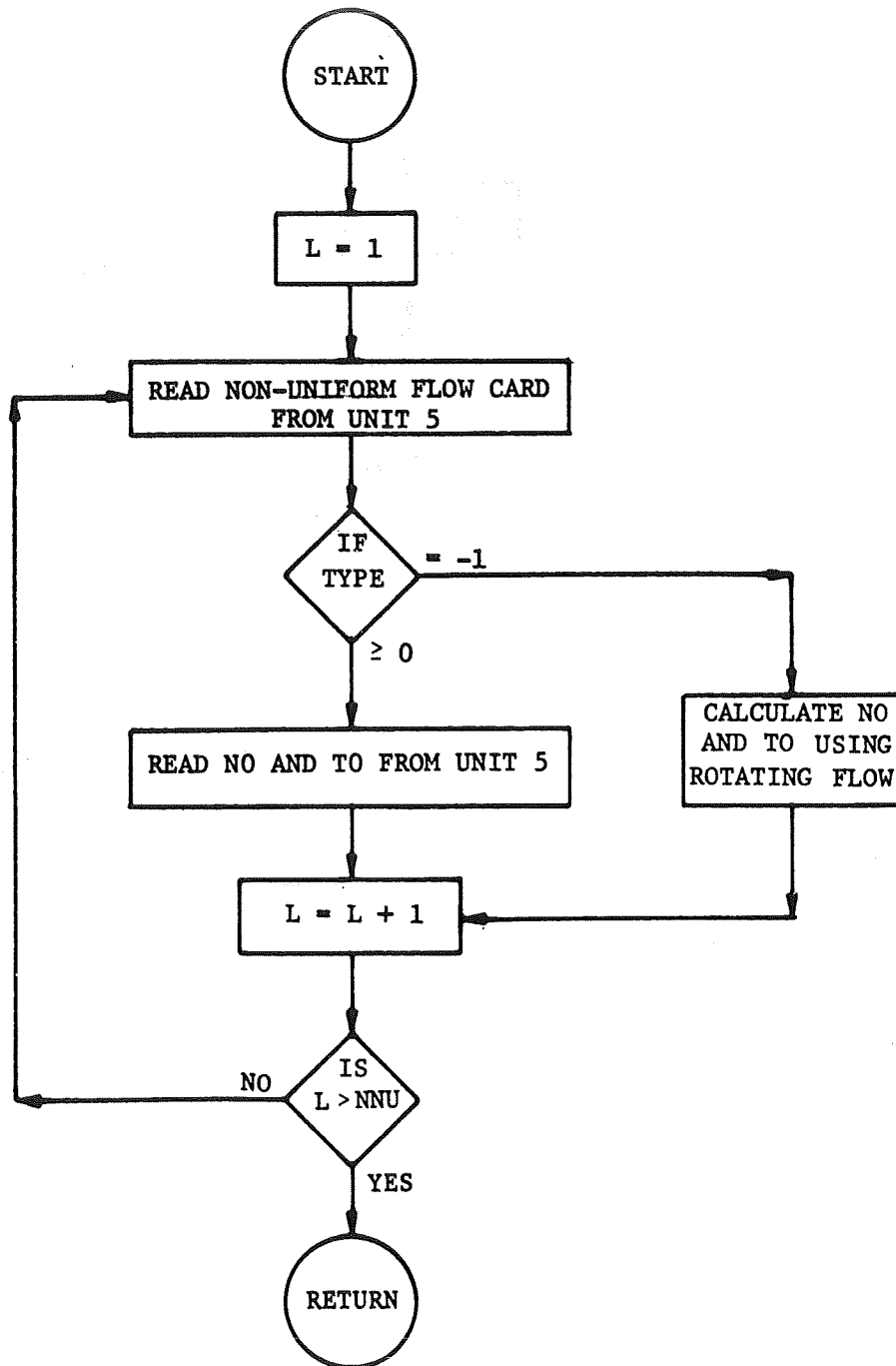
BASIC FLOW CHART FOR SUBROUTINE BASIC1 (CONTINUED)



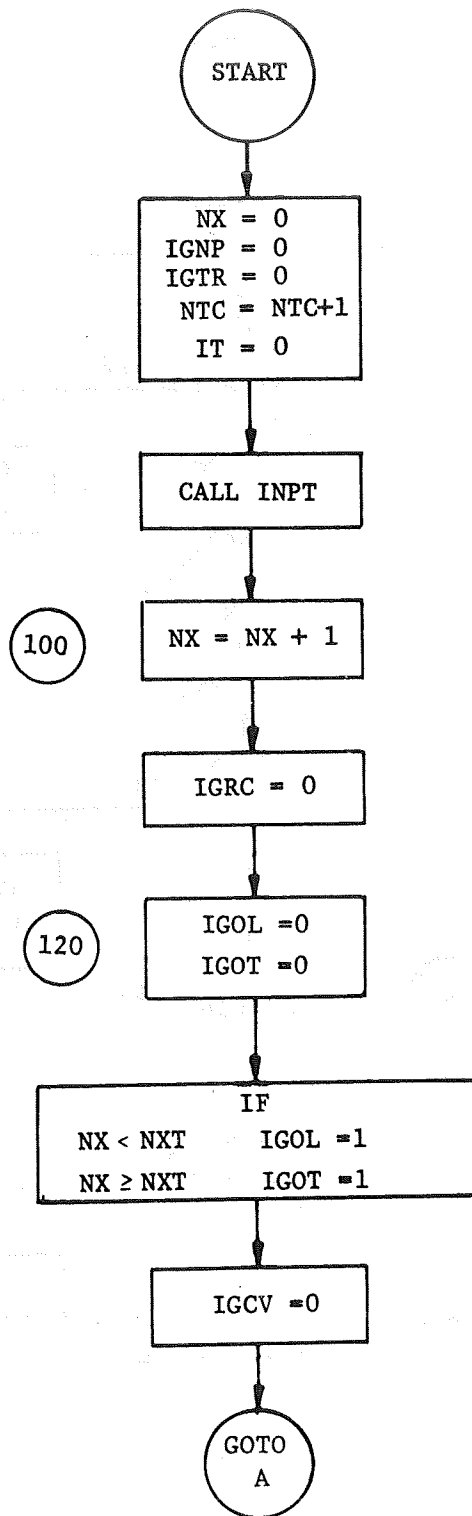
BASIC FLOW CHART FOR SUBROUTINE BASIC1 (CONTINUED)



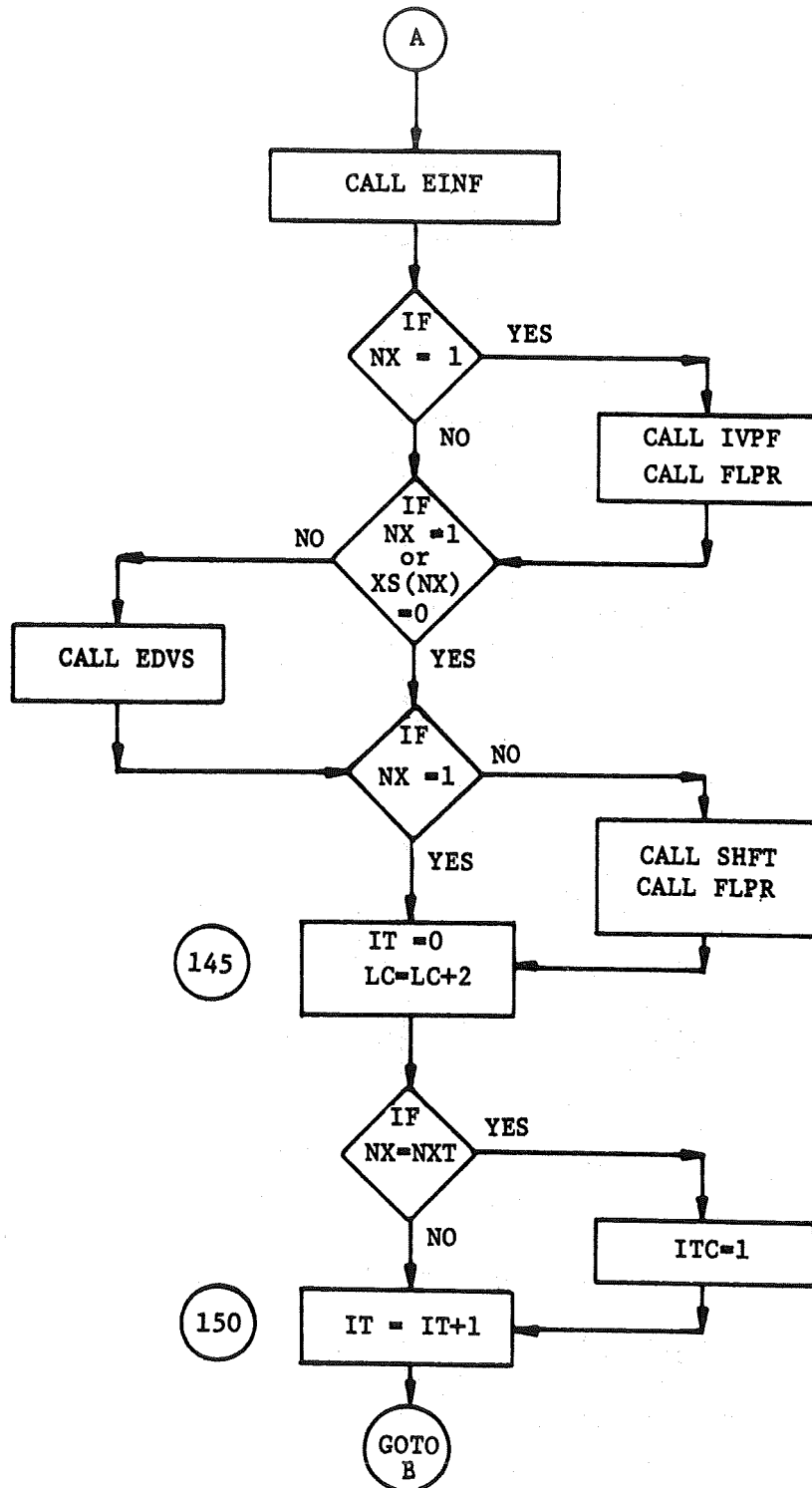
BASIC FLOW CHART FOR SUBROUTINE BASIC2



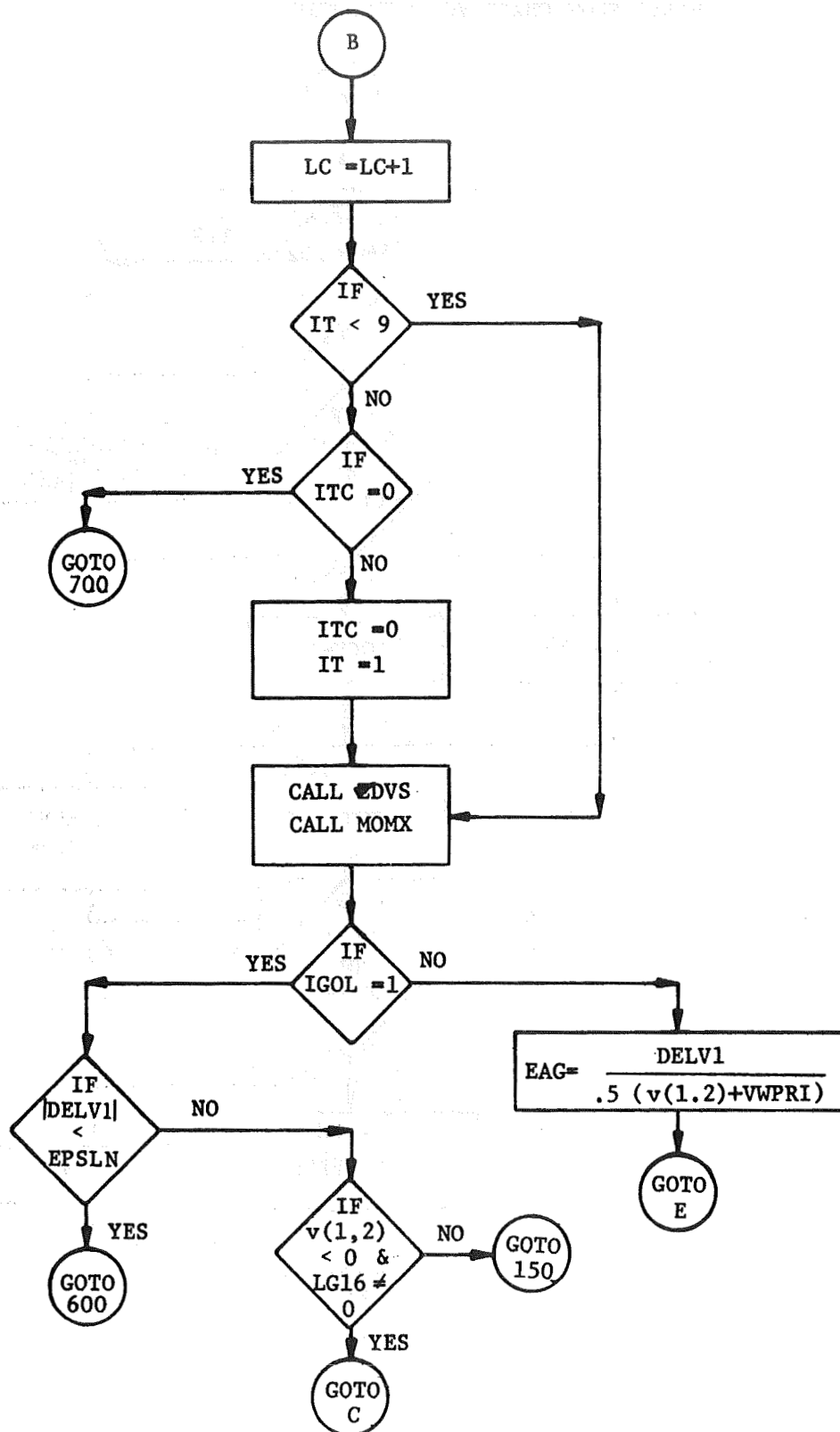
BASIC FLOW CHART FOR SUBROUTINE BOUNDL



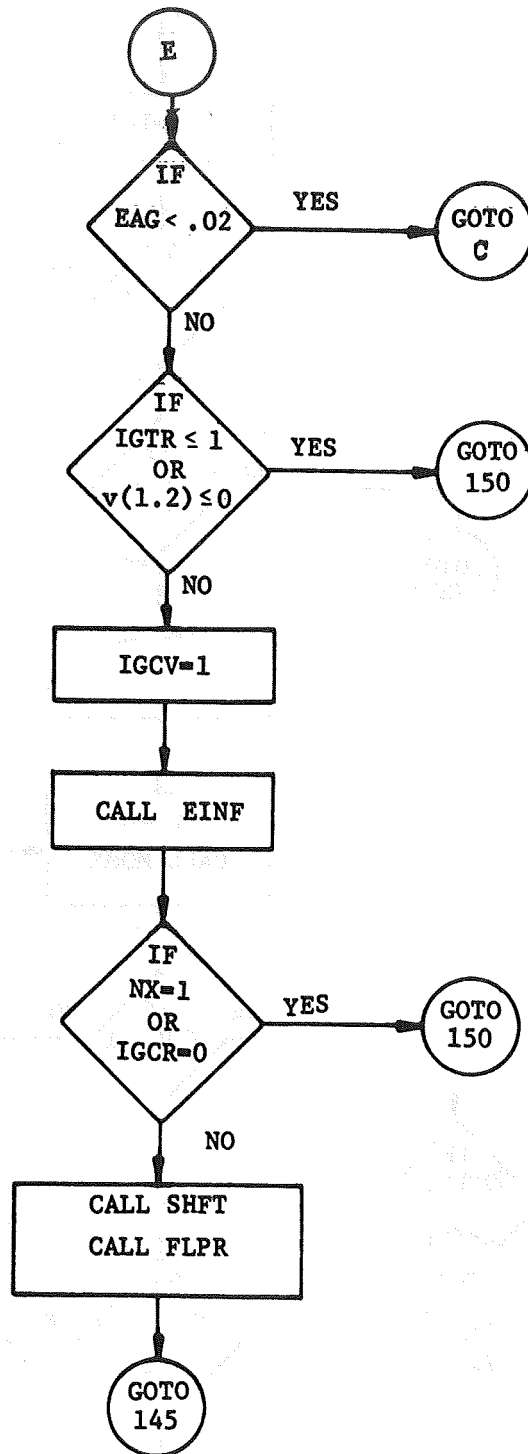
BASIC FLOW CHART FOR SUBROUTINE BOUNDL (CONTINUED)



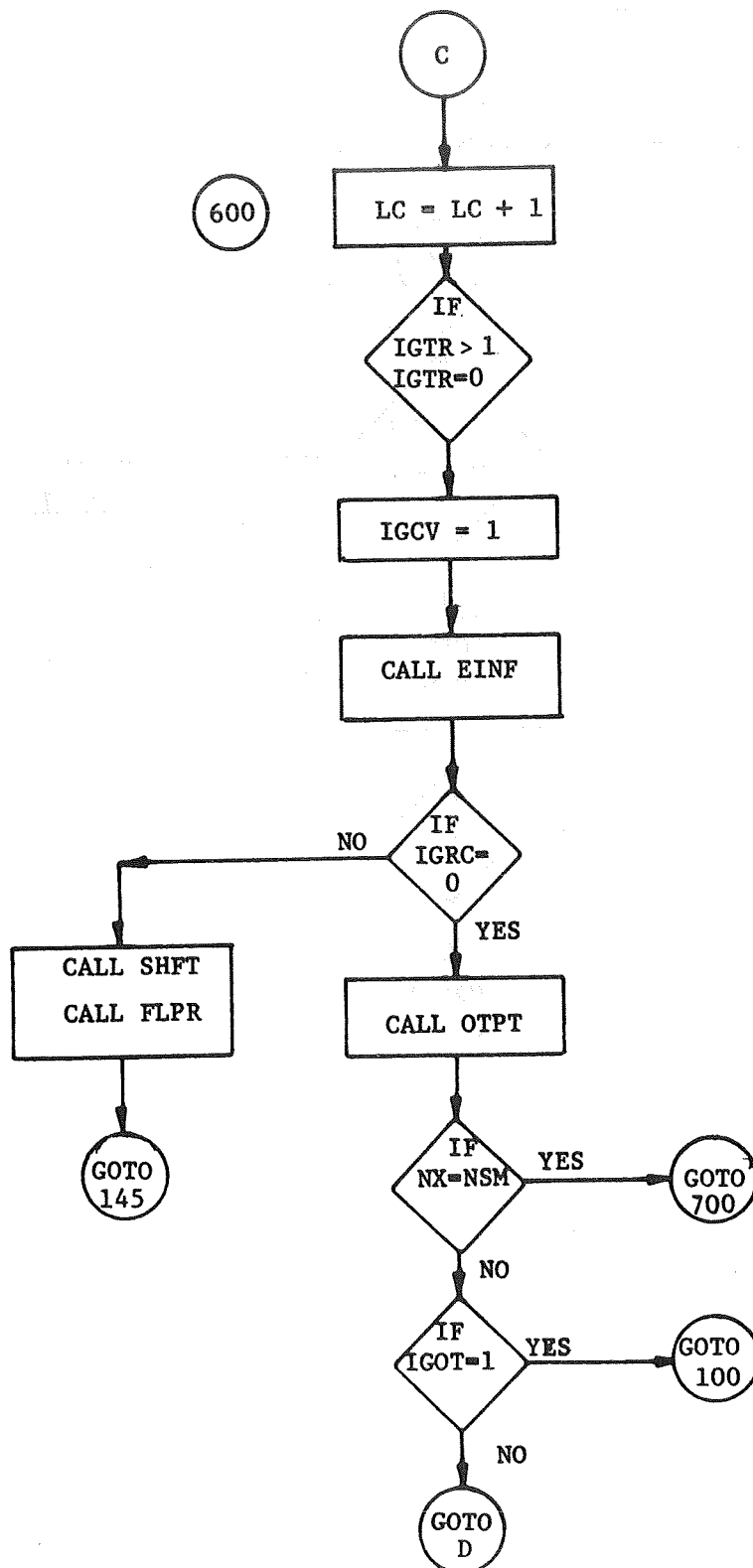
BASIC FLOW CHART FOR SUBROUTINE BOUNDL (CONTINUED)



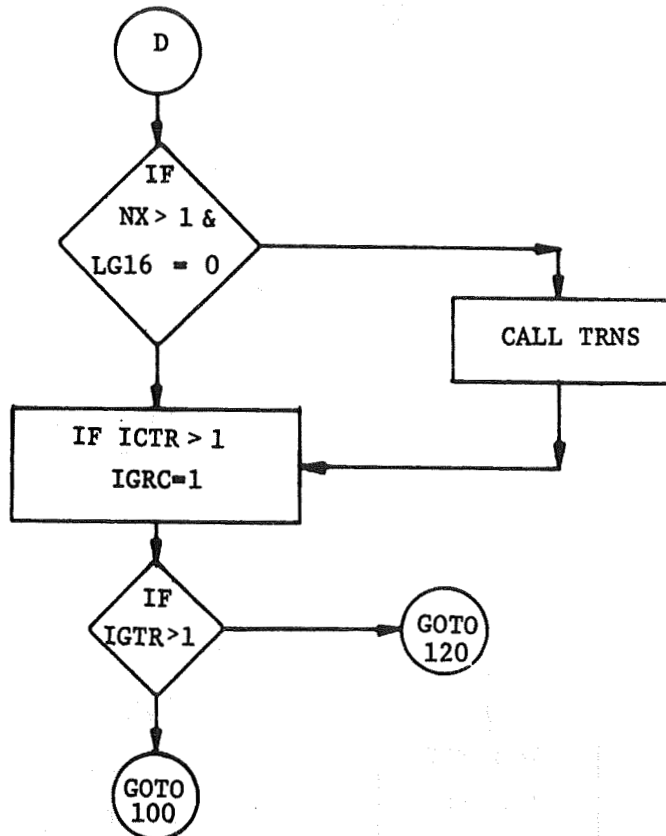
BASIC FLOW CHART FOR SUBROUTINE BOUNDL (CONTINUED)



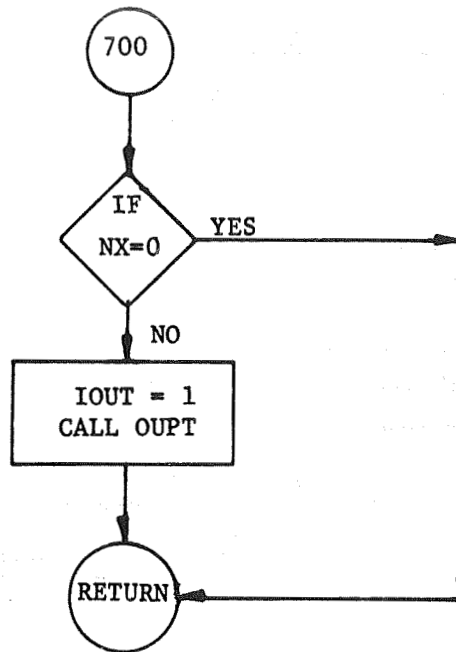
BASIC FLOW CHART FOR SUBROUTINE BOUNDL (CONTINUED)



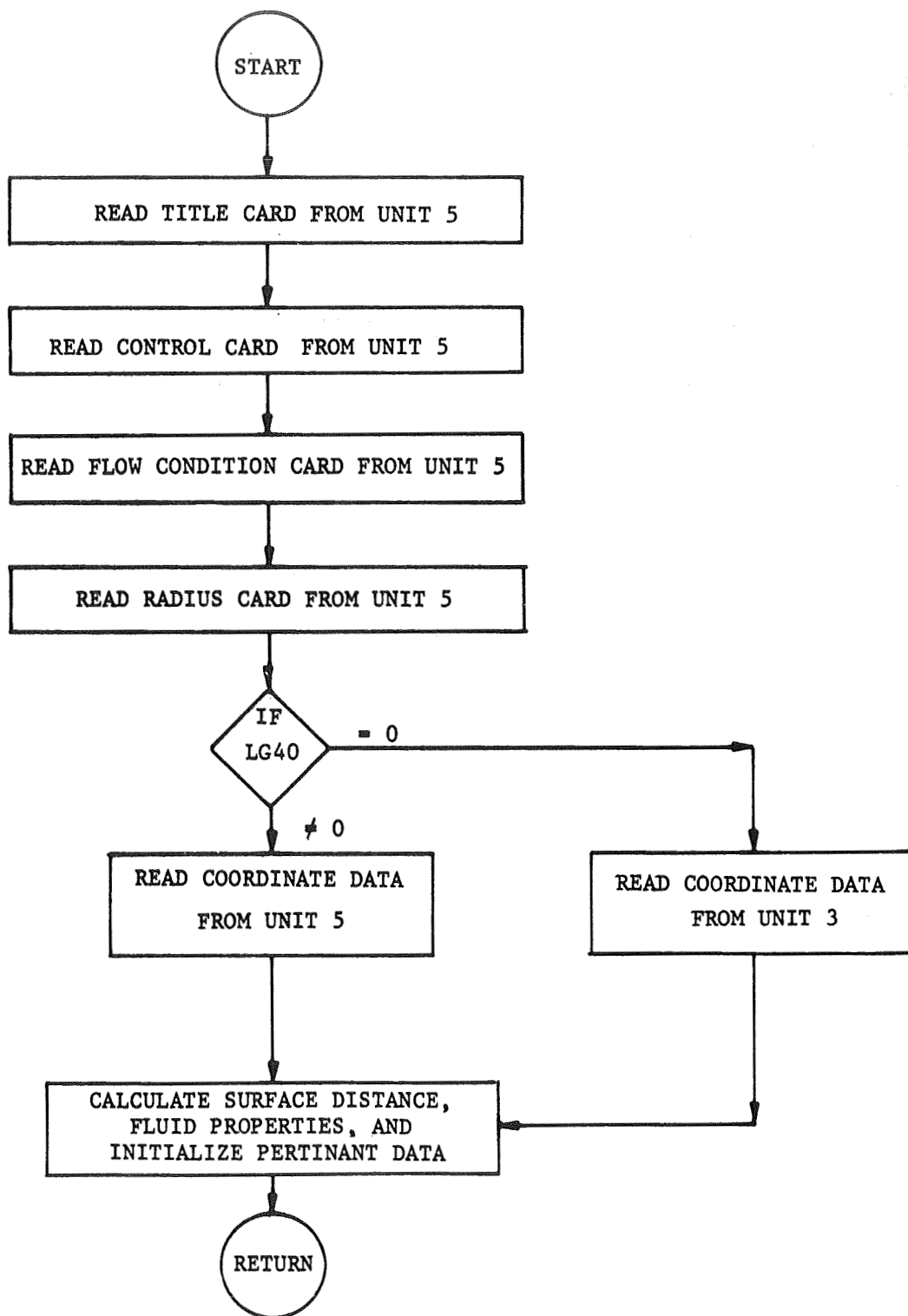
BASIC FLOW CHART FOR SUBROUTINE BOUNDL (CONTINUED)



BASIC FLOW CHART FOR SUBROUTINE BOUNDL (CONTINUED)



BASIC FLOW CHART FOR SUBROUTINE INPT



The following is a description of the output symbols from the various sections of the ADAM computer program:

NEUMANN POTENTIAL FLOW SUBPROGRAM

<u>SYMBOL</u>	<u>DESCRIPTION</u>
ADDED MASS	$\Sigma 2\pi \cdot \Phi_i \cdot V_n \cdot ds$
AJK	Influence coefficients W_{jk} resolved parallel to the outward normal of the element. Output only if $FLG08 = 1$.
ADDX	Constant which is added to all X-coordinates of a particular body. Value printed out for each body.
ADDY	Constant which is added to all Y-coordinates of a particular body. Value printed out for each body.
BJK	Influence coefficient W_{jk} resolved parallel to the tangent direction of the element.
BODIES	Number of bodies in system, same as NB input on flag card.
BODY NO.	Number of this particular body. This parameter input on body control card.
CHORD	The reference chord for the system.
COSA	The cosine of DALPHA
CP	The pressure coefficient on a body element.
DALPHA	The change in angle between consecutive elements of a body. (degrees)
DELTAS	The length of a body element.
MACH NO.	Mach number used in Gothert's transformation.
MX	The factor by which all X-coordinates are multiplied for one body. Input on body transformation card.
MY	The factor by which all Y-coordinates are multiplied for one body. Input on body transformation card.

<u>SYMBOL</u>	<u>DESCRIPTION</u>
N	Velocity normal to a surface element, this is a measure of how well the boundary condition of zero normal velocity is satisfied.
NN	The number of geometry data points for a given body. This is input on the body transformation card.
NNU	The number of non-uniform onset flows to be considered.
PHI	Value of potential on each surface element.
PSF NO.	Identification for this case..
SIGMA	Source density on each surface element.
SINA	Sin of DALPHA
SUM(T) DELTA(S)	This is the summation of T multiplied by Deltas up to each element midpoint.
SUMDS	Summation of Deltas, surface distance around the body.
TCNST	Constant value of tangential velocity used in special option.
THETA	The angle through which a body is to be rotated about the origin in a clockwise direction.
TI	The velocity at each midpoint.
VOLUME	The volume of the body being analyzed. (calculated by Neumann)
X	The input X-coordinate defining the body surface, or off-body X-coordinates.
XE	The value of semi-major axis used in ellipse generation option.
Y	The input Y-coordinates defining the body surface, or off-body Y-coordinates.
YE	The value of semi-minor axis used in ellipse generation option.

OUTPUT DATA SYMBOLS

Finite Difference Boundary Layer Subprogram

Output of this routine consists of CASE DATA and STATION DATA inputs as well as the computed STATION DATA. Body geometry data, flags and counters, and reference quantities are printed out under the heading of CASE DATA. Values of parameters at the outer edge of the boundary layer as well as the boundary condition inputs are printed out under the heading of STATION DATA. These are followed by iteration results, velocity profiles for each x-station (if FLG32 = 0), and a summary of the computed boundary-layer parameters as functions of streamwise or x-distance.

Error messages generated by the program are printed out at the end of the STATION DATA printout if they are generated by input errors. Other error messages are issued at different locations in the profile printout if errors are detected during the computations.

<u>SYMBOL</u>	<u>DESCRIPTION</u>
ALPH1	Local body slope dy/dx .
ALPH2	Not used in this program.
BETA	$\beta = (2\xi/u_e)(du_e/d\xi)$
C	CHORD
CDBASE	Base drag coefficient.
CF	$c_f = \tau_w / (1/2 u_e^2)$, value of local skin friction coefficient.
CFA	Total integrated skin friction to each point.
C_p	Pressure coefficient
DELS	Boundary layer displacement thickness.
DELVW	Delta V(1,2) used in iteration for V(1,2).
EPS	ϵ^+ , eddy viscosity parameter for outer region.
EPS1	ϵ_1 , eddy viscosity parameter for inner region.
ETA	η , non-dimensionalized boundary layer thickness to each point in the boundary layer.

<u>SYMBOL</u>	<u>DESCRIPTION</u>
ETA _E	η_{∞} value of η which corresponds to δ .
ETA _{INF}	Non-dimensional boundary layer thickness used as maximum. value in forming numerical solution grid.
F,FP,FPP	f, f', f'' , respectively.
FPPW	f'' at the wall.
FPW	$f' = U/U_e$ at the wall.
FW	f_w , this is the transformed stream function at the wall.
	$f_w = - \frac{1}{(2\xi)^{1/2}} \int_0^{\xi} \frac{v_w}{\mu_e u_e} d\xi$
GW	Not used in this method.
GPW	Not used in this method.
H	Boundary layer form factor, $H = \delta^*/\theta$
HE	Enthalpy
H1	Initial step size, same as DETAL in input.
IMAX	Number of points taken through the boundary layer.
K	Initial step size of the variable grid system.
KK	Variable grid parameter chosen internally.
ME	Local Mach number.
MUE	Local dynamic viscosity, μ_e , at edge of boundary layer.
MREF	Free stream Mach number.
MUREF	Free stream dynamic viscosity, μ_{∞} .
PE	Pressure at edge of boundary layer, P_e .
PRO	Laminar Prandtl number.
QW	Not used in this program.
REY	Reynolds number based on reference conditions (see input)

<u>SYMBOL</u>	<u>DESCRIPTION</u>
RHOREF	Freestream reference density.
R_o/C	R_o/L axisymmetric radius.
RR	Not used by this program.
RTHETA	Momentum thickness Reynolds number, R_θ .
R_x	Reynolds number based on local conditions. $R_x = \frac{u_e x}{\nu}$
S	Surface distance.
S/C	Nondimensionalized surface distance.
SHORTP	Flag which tells program to print velocity profiles. Same as FLG32 in input.
SQUIG	Transformed x-coordinate, ξ $\xi = \int_0^x \rho_e \mu_e u_e \left(\frac{r_o}{L} \right)^{2k} dx$
ST	Not used in this program.
SWEEP	Not used in this program.
TE	Temperature through boundary layer. Not needed for this program.
THETA	Momentum thickness, θ .
TREF	Reference temperature, T_∞ .
TRFLAG	Flag which determines transition (input).
TRINT	Flag which determines instantaneous transition or use of transitional region option (input).
TW	Temperature at the wall. Not used in this program.
TVC	Transverse curvature flag (input).
UE	Velocity at edge of boundary layer.
UPLUS	Non-dimensionlized velocity in the boundary layer.

<u>SYMBOL</u>	<u>DESCRIPTION</u>
X	X-coordinate
X/C	Non-dimensionalized x-coordinate
XI	Transformed x-coordinate - same as SQUIG
Y	Y-coordinate
Y/C	Non-dimensionalized y-coordinate
YPLUS	Non-dimensionalized y-coordinate in boundary layer.
VREF	Reference velocity (input)

Iteration Subprogram

XNEW and YNEW These are the coordinates of the equivalent viscous body. The original coordinates modified by the addition of the boundary layer displacement thickness δ^* .

DESCRIPTION OF STORAGE UNITS

The following is a description of all disk storage units used in ADAM:

<u>TAPE</u>	<u>DESCRIPTION</u>
TAPE1	This unit used in subroutine SOLVIT as a scratch unit and also used to transfer the "viscous" coordinates from subroutine iterat to subroutine smooth or subroutine BASIC1.
TAPE2	This unit used in subroutine SOLVIT as a scratch unit and also used to transfer the boundary layer displacement thickness's from subroutine OTPT to subroutine ITERAT.
TAPE3	This unit used to store source densities in subroutine SOLVIT and used to transfer body geometry and pressures from subroutine AXIS to subroutine INPT.
TAPE4	$\sin \alpha$, $\cos \alpha$, TCNST, TG(I), $\cos R^2$, $2 (\sin \alpha) (\cos \alpha) $, N_o , T_o , V_N , T_T , A(J), B(J), etc. Used exclusively in Neumann subprogram to store and transfer data.
TAPE5	This tape used for card input.
TAPE6	This tape used for printed output.
TAPE8	This tape used to store extra cross flow matrices, EC , ECY, ECZ, in subroutine MATRIX.
TAPE9	This tape used to store axisymmetric flow matrices AS, AY, AZ, in subroutine MATRIX.
TAPE10	This tape used to store cross flow matrices CX, CY, CZ in subroutine matrix and also used to transfer smoothed

<u>TAPE</u>	<u>DESCRIPTION</u>
TAPE10 (Continued)	coordinate data from subroutine smooth to subroutine BASIC1.
TAPE11	This tape used as a scratch unit in subroutine SOLVIT.
TAPE12	This tape used to store transformed parameters $X1$, $Y1$, $X2$, $Y2$, and ΔS_1 .
TAPE13	This tape used to store untransformed coordinates (TX1, TY1) for use in SUBCASE option.
TAPE15	This tape used to store transformed coordinates, (X1, Y1) for use in subroutine ITERAT.

APPENDIX C

PROGRAM LISTINGS

This part of the report contains the source card listings for the axisymmetric design and analysis method (ADAM) computer program. This program may be run either on a CDC or an IBM computer. The listing as presented here is for the CDC version of the program. This program has been run on the CDC 6600 computer. The program is written in FORTRAN for the CDC run compiler and has been run under the scope 3.1 and 3.4 operating systems. In this listing all cards that are peculiar to the CDC version of FORTRAN are identified by a C in card column 80. All cards that are peculiar to the IBM FORTRAN IV compiler are identified by an I in card column 80 and a C in card column 1. In other words, the code for both CDC and IBM machines is in the deck but the IBM cards are made inactive by converting them to comment statements (C in card column 1). Since all of the machine dependent cards are identified by an I or C in card column 80 it is a simple matter to convert the deck from one version to the other with a small conversion program. When converting from CDC to IBM code this conversion program reads and copies each card to a storage unit. If a card has a C in card column 80, then a C is written into card column 1 to make the CDC peculiar card inactive. If a card has an I in card column 80, then the C is removed from card column 1 and the card image written to the storage unit as an active FORTRAN statement. The conversion from IBM back to CDC is made in a similar manner. The conversion program to convert the deck from CDC to IBM FORTRAN is listed below (for use on an IBM machine):

```

      DIMENSION DATA(22)
      DATA CB,CC,CI/IH, IHC,IHI/
      REWIND 19
      DO 100 I=1,20000
        READ (5,20,END=300) DATA
20      FORMAT (1A1,19A4,1A2,1A1)
        IF (DATA(22) .EQ. CI) DATA(1) = CB
        IF (DATA(22) .EQ. CC) DATA(1) = CC
        WRITE (19,20) DATA
100    CONTINUE
300    STOP
      END
```


This program places the new deck with IBM cards made active, and CDC cards inactive, on to unit 19. The references to unit 19 above can be changed to unit 7 to punch the deck out.

MAIN

```

OVERLAY(AXSY,0,0)
PROGRAM MAIN(INPUT=201,OUTPUT,
1      TAPE1=201,TAPE2=201,TAPE3=201,TAPE4=201,TAPE8=201,
2      TAPE9=201,TAPE10=201,TAPE11=201,TAPE12=201,TAPE13=201,TAPE15=201)
B8AC MAIN PROGRAM

THIS IS THE AXISYMMETRIC DESIGN AND ANALYSIS METHOD ,ADAM,
COMPUTER PROGRAM. THIS COMPUTER PROGRAM WILL CALCULATE THE
AERODYNAMIC FORCES ACTING ON AN AXISYMMETRIC BODY OPERATING
IN A VISCOUS INCOMPRESSIBLE FLOW FIELD

1 FORMAT(5I4)
2 READ(5,1) IGEOM,INEUM,IBOUND,ITER,IFINSH

THESE FOUR FLAGS DETERMINE WHICH ROUTINES WILL BE USED

IGEOM CONTROLS THE GEOMETRY DEFINITION
IF IGEOM = 0 NO SMOOTHING IS USED
IF IGEOM = 1 SMOOTHING IS USED

INEUM INDICATES WHETHER OR NOT A POTENTIAL FLOW SOLUTION WILL
BE GENERATED
IF INEUM = 0 NO POTENTIAL FLOW SOLUTION IS USED
IF INEUM = 1 A POTENTIAL FLOW SOLUTION IS USED

IBOUND INDICATES WHETHER OR NOT A BOUNDARY LAYER SOLUTION IS
DESIRED
IF IBOUND = 0 NO BOUNDARY LAYER SOLUTION IS NEEDED
IF IBOUND = 1 A BOUNDARY LAYER SOLUTION IS NEEDED

ITER CONTROLS THE ITERATION CYCLE
IF ITER = 0 NO ITERATION IS NEEDED
IF ITER = 1 AN ITERATION IS NEEDED

```

MAIN 001C
 MAIN 002C
 MAIN 003C
 MAIN 004C
 MAIN 005
 MAIN 006
 MAIN 007
 MAIN 008
 MAIN 009
 MAIN 010
 MAIN 011
 MAIN 012
 MAIN 013
 MAIN 014
 MAIN 015
 MAIN 016
 MAIN 017
 MAIN 018
 MAIN 019
 MAIN 020
 MAIN 021
 MAIN 022
 MAIN 023
 MAIN 024
 MAIN 025
 MAIN 026
 MAIN 027
 MAIN 028
 MAIN 029
 MAIN 030
 MAIN 031
 MAIN 032
 MAIN 033
 MAIN 034
 MAIN 035

MAIN

MAIN

```

C      IGEOM = IGEOM + 1
      INFUM = INFUM + 1
      IBOUND = IBOUND + 1
      ITER = ITER + 1
C
C      GO TO (30,20), IGEOM
C
C      20 CALL SMOOTH
      20 CALL OVERLAY(4HAXSY,6,0,6HRECALL)
C
C      30 GO TO (60,50), INEUM
C
C      50 CALL NEUMAN
C
C      60 GO TO (90,80), IBOUND
C
C      80 CALL BOUNDL
      80 CALL OVERLAY(4HAXSY,5,0,6HRECALL)
C
C      90 GO TO (120,110), ITER
C
C      110 CALL ITERAT
      110 CALL OVERLAY(4HAXSY,7,0,6HRECALL)
C
C      120 IF (IFINSH .NE. 9999) GO TO 2
C
C      STOP
      200 CONTINUE
      FND

```

MAIN 036
 MAIN 037
 MAIN 038
 MAIN 039
 MAIN 040
 MAIN 041
 MAIN 042
 MAIN 043I
 MAIN 044C
 MAIN 045
 MAIN 046
 MAIN 047
 MAIN 048
 MAIN 049
 MAIN 050
 MAIN 051
 MAIN 052I
 MAIN 053C
 MAIN 054
 MAIN 055
 MAIN 056
 MAIN 057I
 MAIN 058C
 MAIN 059
 MAIN 060
 MAIN 061
 MAIN 062I
 MAIN 063C
 MAIN 064

MAIN


```

      REWIND 10
      REWIND 11
      REWIND 12
      REWIND 13
      REWIND 15
      CALL PART1
      CALL OVERLAY (4HAXSY,1,0,6HRECALL )
      IF (FLG06, NE. 0) GO TO 50
      30 CALL PREP
      30 CALL OVERLAY (4HAXSY,3,0,6HRECALL )
      40 CALL PART4
      40 CALL OVERLAY (4HAXSY,4,0,6HRECALL )
      50 RETURN
      FND

```

```

NEUM 036
NEUM 037
NEUM 038
NEUM 039
NEUM 040
NEUM 041I
NEUM 042C
NEUM 043
NEUM 044I
NEUM 045C
NEUM 046I
NEUM 047C
NEUM 048
NEUM 049

```

NEUM

NEUM

INS1

SUBROUTINE INS1 (ARG, TABLE, OTPT , NLQ, NFR)
 INS1 - SINGLE LINEAR OR QUADRATIC INTERPOLATION
 ONE OR TWO FUNCTIONS OF ONE VARIABLE

THIS SUBROUTINE WILL INTERPOLATE FOR EITHER

- 1) F(X) FROM A TABLE OF X VRS F(X), OR
 - 2) F(X) AND G(X) FROM A TABLE OF X VRS F(X), G(X).
- THE TABLE MAY HAVE UNEQUAL SPACING IN X. EITHER LINEAR
 OR QUADRATIC LAGRANGE INTERPOLATION MAY BE USED.

ARG = INPUT = X ARGUMENT

TABLE = INPUT = IS A LINEAR ARRAY. THE FIRST WORD IS AN
 INTEGER CODE (EITHER INTEGER FORM OR REAL*4
 FORM). IF THIS CODE IS POSITIVE, THE CODE
 SPECIFIES THE NUMBER OF X,F(X) PAIRS
 IMMEDIATELY FOLLOWING THE CODE IN SUCCESSIVE
 WORDS. IF THE CODE IS NEGATIVE,
 ABSOLUTE VALUE OF THE CODE SPECIFIES THE
 NUMBER OF X,F(X),G(X) TRIPLES IMMEDIATELY
 FOLLOWING THE CODE IN SUCCESSIVE WORDS.
 THE X=VALUES MUST BE IN ASCENDING ORDER.
 EXCEPT FOR THE CODE. THE INPUT TABLE VALUES
 MUST BE IN REAL*4 FORM

OTPT = OTPT = INTERPOLATED VALUE OF F(X) IF TABLE(1) IS
 POSITIVE
 = A TWO WORD ARRAY (IF TABLE(1) IS NEGATIVE)
 CONTAINING THE INTERPOLATED VALUES
 FOR F(X) AND G(X)

NLQ = INPUT = INTERPOLATION FLAG (INTEGER)
 = 1 FOR LINEAR INTERPOLATION
 = 2 FOR QUADRATIC INTERPOLATION

INS1 001
 INS1 002
 INS1 003
 INS1 004
 INS1 005
 INS1 006
 INS1 007
 INS1 008
 INS1 009
 INS1 010
 INS1 011
 INS1 012
 INS1 013
 INS1 014
 INS1 015
 INS1 016
 INS1 017
 INS1 018
 INS1 019
 INS1 020
 INS1 021
 INS1 022
 INS1 023
 INS1 024
 INS1 025
 INS1 026
 INS1 027
 INS1 028
 INS1 029
 INS1 030
 INS1 031
 INS1 032
 INS1 033
 INS1 034
 INS1 035

INS1

1521

```

C      GO TO 130
C      SEARCH FOR ENTRY WITHIN TABLE
C
60  NOS = M * NOFNTR
    IST = 2 + M
    DO 90 I = IST, NOS, M
        J = I + 1
        IF ( TABLE(I) - TABLE(I-M) ) 70,70,80
70  NER = 5
    GO TO 140
80  IF ( TABLE(I) - ARG ) 90,50,100
90  CONTINUE
    NER = 3
    GO TO 130
C
C      SEARCH SUCCESSFUL, TEST INTERPOLATION TYPE
C
100 IF ( NLO .GT. 1 ) GO TO 110
C
C      USE LINEAR INTERPOLATION
C
    NER = 1
    OTPT (1) = TABLE(I+1) * ( ARG - TABLE(I-M) ) / ( TABLE(I) -
1      TABLE(I-M) ) + TABLE(I-M+1) * ( ARG - TABLE(I) ) /
2      ( TABLE(I-M) - TABLE(I) )
    IF ( M .NE. 3 ) GO TO 140
    OTPT (2) = TABLE(I+2) * ( ARG - TABLE(I-7) ) / ( TABLE(I) -
1      TABLE(I-7) ) + TABLE(I-1) * ( ARG - TABLE(I) ) /
2      ( TABLE(I-M) - TABLE(I) )
    GO TO 140
C
C      USE QUADRATIC INTERPOLATION
C
110 I = I - M

```

```

INS1 071
INS1 072
INS1 073
INS1 074
INS1 075
INS1 076
INS1 077
INS1 078
INS1 079
INS1 080
INS1 081
INS1 082
INS1 083
INS1 084
INS1 085
INS1 086
INS1 087
INS1 088
INS1 089
INS1 090
INS1 091
INS1 092
INS1 093
INS1 094
INS1 095
INS1 096
INS1 097
INS1 098
INS1 099
INS1 100
INS1 101
INS1 102
INS1 103
INS1 104
INS1 105

```


INS1

```

IF ( I .GE. 2*M ) GO TO 120
I = I + M
120 XA1 = ARG - TABLE(I)
XA0 = ARG - TABLE(I-M)
XA2 = ARG - TABLE(I+M)
X01 = TABLE(I-M) - TABLE(I)
X02 = TABLE(J-M) - TABLE(I+M)
X12 = TABLE(I) - TABLE(I+M)
NER = 1
OTPT (1) = TABLE(I-M*M1) * ( XA1 / X01 ) * ( XA2 / X02 ) -
1      TABLE(I+1) * ( XA0 / X01 ) * ( XA2 / X12 ) +
2      TABLE(I+M*1) * ( XA0 / X02 ) * ( XA1 / X12 )
IF ( M .NE. 3 ) GO TO 140
OTPT (2) = TABLE(I-1) * ( XA1 / X01 ) * ( XA2 / X02 ) -
1      TABLE(I+2) * ( XA0 / X01 ) * ( XA2 / X12 ) +
2      TABLE(I+5) * ( XA0 / X02 ) * ( XA1 / X12 )
GO TO 140
C
C
C      ERROR EXIT - SET OUTPUT VALUE
C
130 OTPT (1) = TABLE(J)
IF ( M .EQ. 3 ) OTPT (2) = TABLE(J+1)
C
C
C      NORMAL EXIT
C
140 RETURN
END

```

INS1

ARSN

```
FUNCTION ARSIN(X)
C THIS ROUTINE IS REQUIRED BECAUSE OF DIFFERENCES BETWEEN CDC AND IBM
C FORTRAN.
  ARSIN = ASIN(X)
  RETURN
END
```

ARSN 001C
ARSN 002
ARSN 003
ARSN 004C
ARSN 005C
ARSN 006C

ARSN

PAR1

OVERLAY(AXSY,1,0)
 PROGRAM PART1
 SUBROUTINE PART1

C
 C
 C
 C

* CONTROL FOR BASIC DATA AND FORM MATRIX

COMMON / NBSAVE / NBOLD, MIN
 COMMON / RNGWG/ VA(100,2), VR(100,2), VAN(100), VAT(100)
 COMMON / ECF/ ECX(100), ECY(100), ECZ(100)
 COMMON / D/ D1, D3, XMJ, YMJ, XMXJPI, YMYJPI, S
 COMMON HEDR(10), CASE, NB, NNU

1 ,FLG03 ,FLG04 ,FLG05 ,FLG06 ,FLG07
 2 ,FLG08 ,FLG09 ,FLG10 ,FLG11 ,FLG12
 3 ,FLG13 ,FLG14 ,FLG15 ,FLG16 ,FLG17
 4 ,FLG18 ,FLG19 ,FLG20 ,FLG21 ,FLG22
 5 ,FLG23 ,FLG24 ,FLG25 ,FLG26 ,FLG27

COMMON NT, ND(11), MN, NUNA(5), TYPEA(5),
 NER1, NER2, NMA, NSIGA, NSIGC,
 NUNC(5), TYPEC(5), NLF(11), IFC, NSIGEC,
 TYPEEC(5), NUNEC(5)

C DOUBLE PRECISION HEDR, CASE

INTEGER FLG03 ,FLG04 ,FLG05 ,FLG06 ,FLG07
 1 ,FLG08 ,FLG09 ,FLG10 ,FLG11 ,FLG12
 2 ,FLG13 ,FLG14 ,FLG15 ,FLG16 ,FLG17
 3 ,FLG18 ,FLG19 ,FLG20 ,FLG21 ,FLG22
 4 ,FLG23 ,FLG24 ,FLG25 ,FLG26 ,FLG27

COMMON / IPSF/ PSF
 REAL MN

C

COMMON / CL/ X1(100), Y1(100), X2(100), Y2(100), DELS(100),
 1 SINA(100), COSA(100), XP(100), YP(100)
 2 ,XWAKE(11), YWAKE(11)
 COMMON / TL/ TX1(100), TY1(100), NG(100), TG(100), ALFA(100),
 1 RSDS(100), DALF(100), CHORD, TCNST, DUMMY(1315)
 COMMON/ITERF/ ITER

PAR1 001C
 PAR1 002C
 PAR1 003I
 PAR1 004
 PAR1 005
 PAR1 006
 PAR1 007
 PAR1 008
 PAR1 009
 PAR1 010
 PAR1 011
 PAR1 012
 PAR1 013
 PAR1 014
 PAR1 015
 PAR1 016
 PAR1 017
 PAR1 018
 PAR1 019
 PAR1 020
 PAR1 021I
 PAR1 022
 PAR1 023
 PAR1 024
 PAR1 025
 PAR1 026
 PAR1 027
 PAR1 028
 PAR1 029
 PAR1 030
 PAR1 031
 PAR1 032
 PAR1 033
 PAR1 034
 PAR1 035

PAR1

```

C      INTEGER      RDN      ,SUBKS      ,NG
C      REAL      MX      ,MY
C
C      * START
C      * READ INPUT DATA
100 READ (5,4) HEDR, CASE, PSF, NR, NNU, FLG03, FLG04, FLG05, FLG06,
1 FLG07, FLG08, FLG09, FLG10, FLG11, FLG12, FLG13, FLG14,
2 FLG15, FLG16, FLG17, FLG18, FLG19, FLG20, FLG21, FLG22,
3 FLG23, FLG24, FLG25, FLG26, FLG27, NIN,ITER
C** **TRIANGULARIZATION OF THE MATRIX (SOLVIT) IS THE DEFAULT SOLUTION
IF (FLG09.EQ.0.AND.FLG10.EQ.0)FLG13=1
C** **FLG22 IS GENERATED (RESEP) BOUNDARY CONDITIONS
C** **FLG21 IS EXTRA CROSS FLOW
1 IF (FLG22.LE.0)GO TO 5
FLG21 = 1
FLG03 = 1
FLG04 = 1
C** **IF FLAG 18 IS NOT EQUAL TO FLAG 14 YOU MUST USE DIRECT MATRIX
5 IF (FLG18.NE.FLG14)GO TO 2
IF (FLG21.LE.0)GO TO 3
FLG12 = 1
2 FLG13 = 1
FLG09 = 0
FLG10 = 0
3 CONTINUE
IF (NBOLD.EQ.0) NBOLD = NB
C** **CARDS (UNIT 5) ARE THE DEFAULT METHOD OF INPUT
IF (NIN.EQ.0) NIN = 10
4 FORMAT (10A6, 2X A6, 8X A4/ 27I1, 12,I1)
READ (5,8) CHORD, MN, TCNST
8 FORMAT (3F10.0)
C** **THE DEFAULT CHORD LENGTH IS 1.0
IF (CHORD.GT.-1.0E-5.AND.CHORD.LT.1.0E+5)CHORD=1.0
WRITE (6,12) HEDR, CASE, NR, NNU, CHORD, MN, TCNST, PSF
12 FORMAT (1MI 25X, 26HDOUGLAS AIRCRAFT COMPANY /

```

```

1 28X, 21HLONG REACH DIVISION ///
2 6X, 43HPROGRAM EONA -- AXISYMMETRIC AND CROSSFLOW //
3 11X, 29H***** CASE CONTROL DATA ***** ///
4 6X, 10A6, 4X, 10HCASE NO. A6 //
5 6X 9HBODIES =I3/ 6X 9HNU =I3/ 6X 9HCWORD =F12.7/
6 6X 9HMACH NO.=F12.8/ 6X 9HTCNSY =F12.7/
7 6X 9HPSF NO. = A4///

    IF (FLG03.GT.0) WRITE (6,16)
16 FORMAT (13X 21HSURFACE OF REVOLUTION )
    IF (FLG04.GT.0) WRITE (6,20)
20 FORMAT (13X 9HCROSSFLOW)
    IF (FLG05.GT.0) WRITE (6,24)
24 FORMAT (13X 15HOFF-BODY POINTS )
    IF (FLG06.GT.0) WRITE (6,28)
28 FORMAT (13X 15HBASIC DATA ONLY )
    IF (FLG07.GT.0) WRITE (6,32)
32 FORMAT (13X 17HELIPSE GENERATOR )
    IF (FLG08.GT.0) WRITE (6,36)
36 FORMAT (13X 14HPRINT MATRICES )
    IF (FLG09.GT.0) WRITE (6,40)
40 FORMAT (13X 10HOLD SEIDEL )
    IF (FLG10.GT.0) WRITE (6,44)
44 FORMAT (13X,31HMODIFIED SEIDEL MATRIX SOLUTION)
    IF (FLG11.GT.0) WRITE (6,48)
48 FORMAT (13X 18HPERTURBATIONS ONLY )
    IF (FLG12.GT.0) WRITE (6,52)
52 FORMAT (13X 22HSOLVE POTENTIAL MATRIX )
    IF (FLG13.GT.0) WRITE (6,56)
56 FORMAT (13X 47HMATRIX SOLUTION BY TRIANGULARIZATION (SOLVIT))
    IF (FLG14.GT.0) WRITE (6,53)
53 FORMAT ( 13X 30HPRFSCRIBED TANGENTIAL VELOCITY )
    IF (FLG18.GT.0) WRITE (6,69)
69 FORMAT ( 15X 22HWITH SURFACE VORTICITY )
    IF (FLG15.GT.0) WRITE (6,54)
54 FORMAT (13X 12HSTRIP VORTEX )

```

```

      IF (FLG16.GT.0) WRITE (6,64)
64  FORMAT (13X 40HOMIT AXI-SYMMETRIC UNIFORM FLOW SOLUTION )
      IF (FLG17.GT.0) WRITE (6,68)
68  FORMAT (13X 36HOMIT CROSSFLOW UNIFORM FLOW SOLUTION )
      IF (FLG19.GT.0) WRITE (6,72)
72  FORMAT (13X 20HPREScribed VORTICITY)
      IF (FLG20.GT.0)WRITE(6,74)
74  FORMAT(13X 15HTOTAL VORTICITY )
      IF (FLG21.GT.0)WRITE(6,76)
76  FORMAT ( 13X 16HEXTRA CROSS FLOW )
      IF (FLG22.GT.0)WRITE(6,78)
78  FORMAT(13X 82HGENERATED BOUNDARY CONDITIONS FOR 3 AXISYMMETRIC, 1
      1CROSS, AND 1 EXTRA CROSS FLOW. )
      IF (FLG23.LF. 0)GO TO 81
      WRITE(6,79)
79  FORMAT(13X 16HRING WING OPTION )
      FLG03 = 1
      FLG13 = 1
      FLG15 = 1
      FLG19 = 1
81  IF (FLG19.GT. 0)FLG18 = 1
      IF (FLG22.GT.0.AND.NB.NE.2) GO TO 82
      GO TO 84
82  WRITE(6,83)
83  FORMAT (128H0 WHEN GENERATED RESEP BOUNDARY CONDITIONS ARE USED,NU
      1MBER OF BODIES MUST BE EXACTLY TWO. YOU GOOFED. EXECUTION TERM
      2INATING.)
      STOP
84  IF (FLG22.GT.0.AND.NNU.GT.0)GO TO 86
      GO TO 88
86  WRITE (6,87)
87  FORMAT (98H0 GENERATED RESEP BOUNDARY CONDITIONS CANNOT HAVE NON-U
      1NIFORM FLOW INPUT. EXECUTION TERMINATING.)
88  CONTINUE
      WRITE ( 6,75 ) NIN

```

PAR1

```

      IF (FLG18.LE.0.OR.FLG14.GT.0) GO TO 125
75  FORMAT( 13X,5HINPUT TAPE NO. FOR COORDINATES AND NON-UNIFORM FLO
      1W ONLY = , 15 )
      WRITE (6,70)
70  FORMAT (1H0//63H FLG14 MUST BE USED WITH FLG18 OR FLG19, EXECUTIO
      IN TERMINATED. )
      STOP
125 IF (NNU.LE.0.OR.FLG14.LE.0) GO TO 130
      WRITE (6,60)
60  FORMAT (1H0// 49H COLUMNS 2 AND 14 OF FLAG CARD ARE BOTH NON-ZERO,
      A / 43H ILLEGAL COMBINATION. EXECUTION TERMINATED. )
      STOP
      * READ DATA AND SETUP FOR UNIFORM FLOW
C 130 CALL BASIC1
C** **NSIGA AND NSIGC ULTIMATELY BECOME THE NUMBER OR RIGHT HAND SIDES
C** **IN AXISYMMETRIC FLOW AND CROSS FLOW RESPECTIVELY
133 NSIGA=0
      IF (FLG03.GT.0.AND.FLG16.LE.0) NSIGA=1
      NSIGC=0
      IF (FLG04.GT.0.AND.FLG17.LE.0) NSIGC=1
      IF (FLG22.GT.0) GO TO 136
      DO 135 I = 1,5
      NUNA(I) = 123456
135 TYPEA(I) = 100.
      IF(FLG23.GT. 0)GO TO 141
      GO TO 138
C** **PREPARE NUNA AND TYPEA FOR NON-UNIFORM AXISYMMETRIC FLOW,GENER
C** ** (RESEP) BOUNDARY CONDITIONS
136 DO 137 I = 1,3
      NUNA(I) = I
137 TYPEA(I) = 100.0
      GO TO 138
C
C
C ** RING WING OPTION

```

PAR1

```

C *** STRIP VORTEX FLOWS ALREADY HAVE NUNA(I) = 123456.
C *** MAKE PRESCRIBED VORTICITY FLOWS NUNA(J) = TO THEIR FLOW NO. J
C
141 ICNT = 0
    DO 142 I = 1,NB
      IF(NLF(I).GT.0) GO TO 142
      ICNT = ICNT + 1
142 CONTINUE
C
C *** ICNT IS THE NUMBER OF LIFTING BODIES
C *** NUMBER OF FLOWS IS 2 * ICNT + 1
C
      NFLWS = 2 * ICNT + 1
      ICNTP2 = ICNT + 2
      DO 143 I = ICNTP2,NFLWS
143 NUNA(I) = I
138 CONTINUE
C *** **IF FLG02 (NON-UNIFORM FLOW) IS NOT CHECKED INITIALLY, THE FLOW
C *** **OF CONTROL WILL NEVER REACH BASIC2
      IF (NNU) 140,150,140
C
C      * READ DATA AND SETUP FOR NON-UNIFORM FLOW
140 CALL BASIC2
150 CONTINUE
160 REWIND 4
      IF (NSIGA.LE.5) GO TO 180
170 WRITE(6,172)
172 FORMAT (1H1 75HAXI-SYMMETRIC OR CROSSFLOW NON-UNIFORM FLOWS EXCEED
      A 5. EXECUTION TERMINATED )
      STOP
180 IF (NSIGC.GT.5) GO TO 170
      IF (FLG15.LE.0.OR.FLG03.GT.0) GO TO 200
      WRITE (6,190)
190 FORMAT (64H1STRIP RING VORTEX OPTION MUST USE SURFACE OF REVOLUTIO
      IN OPTION. / 22H EXECUTION TERMINATED. )
      STOP

```


PARI

```

200 IF (FLG15.LE.0) GO TO 230
    J = 0
    DO 210 I = 1, NR
210 IF (NLF(I).LE.0) J=J+1
    IF (NSIGA + J .LE. 5 )GO TO 230
    WRITE (6,220)
220 FORMAT (68HGENERATED STRIP VORTEX UNSFT FLOWS (ONE FOR EACH LIFTI
    1NG BODY) PLUS / 34H INPUT NON-UNIFORM FLOWS EXCEED 5. /
    2 22HOF EXECUTION TERMINATED. )
    STOP
230 IF (FLG06.NE.0) GO TO 235
    CALL MATRIX
C 235 RETURN
235 CONTINUE
    END

```

```

PARI 211
PARI 212
PARI 213
PARI 214
PARI 215
PARI 216
PARI 217
PARI 218
PARI 219
PARI 220
PARI 221
PARI 222
PARI 223I
PARI 224C
PARI 225

```

PARI

SUBROUTINE BASIC1

C

* READ DATA AND SETUP FOR UNIFORM FLOW

C

COMMON / NBSAVE / NROLD, NIN

COMMON

1 HEDR(10), CASE

2 ,FLG03 ,FLG04

3 ,FLG08 ,FLG09

4 ,FLG13 ,FLG14

5 ,FLG18 ,FLG19

,FLG23 ,FLG24

COMMON NT, ND(11), MN,

1 NER1, NER2, NMA,

2 NUNC(5), TYPEC(5), NLF(11), IEC,

3 TYPEEC(5), NUNEC(5)

DOUBLE PRECISION HEDR, CASE

INTEGER

1 FLG03 ,FLG04

2 ,FLG08 ,FLG09

3 ,FLG13 ,FLG14

4 ,FLG18 ,FLG19

,FLG23 ,FLG24

DIMENSION COSSQR(100), RHS(100)

REAL MN

COMMON /CL/ X1(100), Y1(100),

1 X2(100), Y2(100), DELS(100),

2 SINA(100), COSA(100), XP(100),

, XWAKE(11), YWAKE(11)

COMMON /TL/ TX1(100), TY1(100),

1 NG(100), TG(100), ALFA(100),

RSDS(100), DALF(100), CHORD, TCNST, DUMMY(1315)

INTEGER BDN

REAL

SUBKS

MX MY NG

* START

NT=0

K=0

BAS1 001
 BAS1 002
 BAS1 003
 BAS1 004
 BAS1 005
 BAS1 006
 BAS1 007
 BAS1 008
 BAS1 009
 BAS1 010
 BAS1 011
 BAS1 012
 BAS1 013
 BAS1 014
 BAS1 015
 BAS1 016
 BAS1 017
 BAS1 018
 BAS1 019
 BAS1 020
 BAS1 021
 BAS1 022
 BAS1 023
 BAS1 024
 BAS1 025
 BAS1 026
 BAS1 027
 BAS1 028
 BAS1 029
 BAS1 030
 BAS1 031
 BAS1 032
 BAS1 033
 BAS1 034
 BAS1 035

BAS1

```

K2=NR
IF( NIN.EQ. 0 )      NIN = 10
IF (FLG05.NF.0) K2=NB+1
      * MAJOR LOUP * NU. OF BODIES + OFF BODY POINTS

C
LCNT = 0
DO 1000 L=1,K2
  READ (5,15) NN, MX, MY, THETA, ADDX, ADDY
  15 FORMAT ( 5X I5, 5F10.0)
  READ (5,16) RDN,SUBKS,NLF(L),XF,YE
  16 FORMAT (3(5X,I5),2F10.0)
C** *ND(L) IS THE NUMBER OF POINTS ON BODY L, OR THE NUMBER OF OFF
C** *BODY POINTS FOR L = NB + 1
ND(L)=NN
M=NN-1
IF (SUBKS) 140,150,140
  140 IF( L.NE. K2 )      GO TO 148
      NTIMES = NBOLD = NB
      IF( NTIMES .LF. 0 )      GO TO 148
      DO 145 NSKIPS = 1, NTIMES
        145 READ(13) ( TX1(I),I=1,NN), (TY1(I),I=1,NN)
        148 READ(13) ( TX1(I),I=1,NN), (TY1(I),I=1,NN)
      GO TO 220
  150 IF (RDN.EQ.0) GO TO 200
      IF (FLG07) 160,200,160
          * ELLIPSE GENERATOR FOR X1 AND Y1
  160 IF (XE.EQ.0.0) XE=1,
      IF (YE.EQ.0.0) YE=1,
      EN=1
      DGAM=3.141593 /FN
      GAM=3.141593
      DO 170 I=1,NN
        TX1(I)=XE*COS(GAM)
        TY1(I)=YE*SIN(GAM)
        170 GAM=GAM-DGAM
      GO TO 210

```

BAS1 036
 BAS1 037
 BAS1 038
 BAS1 039
 BAS1 040
 BAS1 041
 BAS1 042
 BAS1 043
 BAS1 044
 BAS1 045
 BAS1 046
 BAS1 047
 BAS1 048
 BAS1 049
 BAS1 050
 BAS1 051
 BAS1 052
 BAS1 053
 BAS1 054
 BAS1 055
 BAS1 056
 BAS1 057
 BAS1 058
 BAS1 059
 BAS1 060
 BAS1 061
 BAS1 062
 BAS1 063
 BAS1 064
 BAS1 065
 BAS1 066
 BAS1 067
 BAS1 068
 BAS1 069
 BAS1 070

BAS1

```

C      * READ X1 AND Y1 FROM INPUT CARDS
200 DO 204 I=1,NN,6
    READ(NIN,20)TX1(I),TX1(I+1),TX1(I+2),TX1(I+3),TX1(I+4),TX1(I+5)
20  FORMAT ( 6F10.0)
204 CONTINUE
DO 206 I=1,NN,6
    READ(NIN,20)TY1(I),TY1(I+1),TY1(I+2),TY1(I+3),TY1(I+4),TY1(I+5)
206 CONTINUE
C
C*** * NB = FLG14 + 1 TO NB ARE PRESCRIBED VORTICITY BODIES
C
IF ( FLG23 .IE. 0 .OR. (L.LE.NB-FLG14 .OR. L .GT. NB))GO TO 210
C
C*** * IF CONTROL REACHES THIS POINT, RING WING OPTION IS IN EFFECT AND
C*** * L IS A PRESCRIBED VORTICITY BODY
C *** LCNT IS THE RELATIVE NUMBER OF THE WAKE BODY STARTING WITH 1
C
LCNT = LCNT + 1
XWAKE(LCNT) = TX1(NN)
YWAKE(LCNT) = TY1(NN)
C
C      * SAVE X1 AND Y1 FOR SUBCASE
210 WRITE (13) (TX1(I),I=1,NN),(TY1(I),I=1,NN)
C
C      * BASIC DATA CALC. AND PRINT (UNTRANSFORMED COORDINATES)
220 WRITE (6,24) HEDR, NN, MX, MY, THETA, ADDX, ADDY, XE, YE
24  FORMAT ( 1H1 25X 26HDOUGLAS AIRCRAFT COMPANY /
1      28X 21HLONG BEACH DIVISION /// 5X 10A6 //
2      8X 4HNN = 14, 15X 4HMX = F13.7, 4X 4HMY = F13.7 /
3      5X 7HTHETA = F13.7, 4X 6HADDY = F13.7, 2X 6HADDY = F13.7 /
4      8X 4HXE = F13.7, 6X 4HYE = F13.7 )
IF (BDN) 240,230,240
230 WRITE (6,28) (I, TX1(I), TY1(I), I=1,NN)
28  FORMAT ( 1H0 4X 36HUFF-BODY COORDINATES (UNTRANSFORMED) //
1      10X 5HX-OFF 9X 5HY-OFF // (1H 13, 2F14.7))
GO TO 270
240 SUMS=0.0

```

BAS1 071
 BAS1 072
 BAS1 073
 BAS1 074
 BAS1 075
 BAS1 076
 BAS1 077
 BAS1 078
 BAS1 079
 BAS1 080
 BAS1 081
 BAS1 082
 BAS1 083
 BAS1 084
 BAS1 085
 BAS1 086
 BAS1 087
 BAS1 088
 BAS1 089
 BAS1 090
 BAS1 091
 BAS1 092
 BAS1 093
 BAS1 094
 BAS1 095
 BAS1 096
 BAS1 097
 BAS1 098
 BAS1 099
 BAS1 100
 BAS1 101
 BAS1 102
 BAS1 103
 BAS1 104
 BAS1 105

```

DO 250 I=1,M
  T1=TX1(I+1)-TX1(I)
  T2=TY1(I+1)-TY1(I)
  X2(I)=(TX1(I+1)+TX1(I))/2.
  Y2(I)=(TY1(I+1)+TY1(I))/2.
  DELS(I)=SQRT(T1*T1+T2*T2)
  SUMS=SUMS+DELS(I)
  RSDS(I)=SUMS
250 ALFA(I) = ATAN2( T2, T1 )
  MA=M-1
DO 260 I=1,MA
  260 DAlF(I) = ( ALFA(I+1)-ALFA(I) ) * 57.29578
  WRITE (6,36) BDN,TX1(I),TY1(I),X2(I),Y2(I),DELS(I),RSDS(I)
36 FORMAT ( 1H0 4X 35HON-RODY COORDINATES (UNTRANSFORMED) /
1      9H RODY NO. I3// 11X 2H X 13X 1HY 11X 7HDELTA S 7X
2      5HSUMDS 8X 7HD ALFA // 1H 3H 1,2F14.7 / 4X 4F14.7)
1  WRITE (6,40) (I, TX1(I), TY1(I), DAlF(I-1), X2(I), Y2(I),
1      DELS(I), RSDS(I), I=2,M) , NN, TX1(NN), TY1(NN)
40 FORMAT ( 1H I3, 2F14.7, 2HX F14.7 / 4X 4F14.7)
C      * ADJUST COORDINATES (TRANSFORMED)
270 IF (MX) 280,300,280
280 DO 290 I=1,NN
290 TX1(I)=TX1(I)*MX
300 IF (MY) 310,330,310
310 DO 320 I=1,NN
320 TY1(I)=TY1(I)*MY
330 IF (THETA) 340,360,340
340 THETA = THETA / 57.29578
  CSTHT = COS(THETA)
  SNTHT = SIN(THETA)
DO 350 I=1,NN
  T1=TX1(I)
  TX1(I)=T1*CSTHT+TY1(I)*SNTHT
  TY1(I)=TY1(I)*CSTHT-T1*SNTHT
350
360 IF (ADDX) 370,390,370

```

```

370 DO 380 I=1,NN
380 TX1(I)=TX1(I)+ADDX
390 IF (ADDY) 400,420,400
400 DO 410 I=1,NN
410 TY1(I)=TY1(I)+ADDY
420 IF (CHORD.EQ. 1.0 .OR. CHORD.EQ. 0.0) GO TO 450
430 DO 440 I=1,NN
440 TX1(I)=TX1(I)/CHORD
440 TY1(I)=TY1(I)/CHORD
450 IF (MN) 460,475,460
460 SRM=SQRT(1.-MN*MN)
470 DO 470 I=1,NN
470 TX1(I)=TX1(I)/SRM
C
C*** * SHIFT X1 AND Y1 TO COMMON /CL/
C*** **IF BDN  $\neq$  0.0, OFF BODY POINTS ARE BEING OPERATED ON
475 IF (BDN) 500,480,500
480 DO 490 I=1,NN
490 XP(I)=TX1(I)
490 YP(I)=TY1(I)
490 WRITE (12) (XP(I),I=1,NN),(YP(I),I=1,NN)
500 DO 510 I=1,NN
510 K=K+1
510 X1(K)=TX1(I)
510 Y1(K)=TY1(I)
510 NT=NT+M
1000 CONTINUE
1000 REWIND 13
1000 IF (FLG14.LE.0) GO TO 2000
1000 IF (FLG14.LE.NB) GO TO 1050
1000 WRITE (6,1025)
1025 FORMAT (45H1VALUE OF FLG14 EXCEEDS NO. OF BODIES. STOP. )
1050 IF (FLG14.NE.NB) GO TO 1075
1050 NMA=0

```

```

BAS1 141
BAS1 142
BAS1 143
BAS1 144
BAS1 145
BAS1 146
BAS1 147
BAS1 148
BAS1 149
BAS1 150
BAS1 151
BAS1 152
BAS1 153
BAS1 154
BAS1 155
BAS1 156
BAS1 157
BAS1 158
BAS1 159
BAS1 160
BAS1 161
BAS1 162
BAS1 163
BAS1 164
BAS1 165
BAS1 166
BAS1 167
BAS1 168
BAS1 169
BAS1 170
BAS1 171
BAS1 172
BAS1 173
BAS1 174
BAS1 175

```

```

GO TO 1150
1075 L = NR-FLG14
NMA = -L
DO 1100 I = 1, L
C*** **NMA BECOMES THE NUMBER OF ELEMENTS ON THE 1ST L BODIES (IE THOSE
C*** **NOT HAVING AN INPUT VORTICITY OR VELOCITY)
1100 NMA = NMA + ND(I)
C*** **NR BECOMES THE NUMBER OF ELEMENTS RECEIVING AN INPUT VORTICITY
C*** **OR VPLOCITY
1150 NR = NT-NMA
IF (TCNST.GT.0.)GO TO 2000
DO 1200 I = 1,NR,6
READ (5,20) TG(I),TG(I+1),TG(I+2),TG(I+3),TG(I+4),TG(I+5)
1200 CONTINUE
C
C * CALC. PARAMETERS WITH TRANSFORMED COORDINATES AND
C MACH NO. ADJUSTMENT
2000 N1=0
J1=0
DO 2500 K=1,NB
M1=N1+1
N1=N1+ND(K)-1
DO 2400 J=M1,N1
J1=J1+1
T1=X1(J1+1)-X1(J1)
T2=Y1(J1+1)-Y1(J1)
X2(J)=(X1(J1+1)+X1(J1))/2.
Y2(J)=(Y1(J1+1)+Y1(J1))/2.
DELS(J)=SQRT(T1*T1+T2*T2)
COSA(J)=T1/DELS(J)
SINA(J)=T2/DELS(J)
2400 J1=J1+1
2500 J1=J1+1
C
C * SAVE PARAMETERS
WRITE (12) (X1(I),I=1,J1),(Y1(I),I=1,J1),(X2(I),I=1,N1)
1
,(V2(I),I=1,NT),(DELS(I),I=1,NT)
REWIND 12

```

```

BAS1 176
BAS1 177
BAS1 178
BAS1 179
BAS1 180
BAS1 181
BAS1 182
BAS1 183
BAS1 184
BAS1 185
BAS1 186
BAS1 187
BAS1 188
BAS1 189
BAS1 190
BAS1 191
BAS1 192
BAS1 193
BAS1 194
BAS1 195
BAS1 196
BAS1 197
BAS1 198
BAS1 199
BAS1 200
BAS1 201
BAS1 202
BAS1 203
BAS1 204
BAS1 205
BAS1 206
BAS1 207
BAS1 208
BAS1 209
BAS1 210

```

```

C      * SAVE SINA AND COSA ON TAPE 4 FOR CALC. OF MATRIX
C      SOLUTION (RIGHT HAND MATRIX)
      WRITE (4) (SINA(I), I=1, NT), (COSA(I), I=1, NT)
      IF (FLG14) 2600, 2600, 2550
2550  IF (TCNST.GT.0.0) WRITE(4) (TCNST, I=1, NR)
      IF (TCNST.LE.0.) WRITE(4) (TG(I), I=1, NR)
2600  IF (FLG22.LE.0) RETURN
      NPR1 = ND(1) - 1
      DO 2700 I = 1, NPR1
        COSSQR(I) = COSA(I)*2
2700  RHS(I) = 2.0 * ABS( SINA(I) * COSA(I) )
      WRITE(4) ( COSSQR(I), I=1, NPR1), (RHS(I), I = 1, NPR1)
      RETURN
      END

```

```

BAS1 211
BAS1 212
BAS1 213
BAS1 214
BAS1 215
BAS1 216
BAS1 217
BAS1 218
BAS1 219
BAS1 220
BAS1 221
BAS1 222
BAS1 223
BAS1 224

```


SUBROUTINE BASIC2

* READ DATA AND SETUP FOR NON-UNIFORM FLOWS

COMMON / NBSAVE / NROLD, NIN

COMMON

1 HEDR(10), CASE, NB, NNU, FLG06, FLG07
 2 ,FLG03, FLG04, ,FLG05, ,FLG11, ,FLG12
 3 ,FLG08, FLG09, ,FLG10, ,FLG16, ,FLG17
 4 ,FLG13, FLG14, ,FLG15, ,FLG21, ,FLG22
 5 ,FLG18, FLG19, ,FLG20, ,FLG26, ,FLG27
 ,FLG23, FLG24, ,FLG25, ,FLG26, ,FLG27

COMMON

1 NT, ND(11), MN, NUNA(5), TYPEA(5),
 2 NER1, NER2, NMA, NSIGA, NSIGC,
 3 NUNC(5), TYPEC(5), NLF(11), IEC, NSIGEC,

DOUBLE PRECISION HEDR, CASE

INTEGER

1 FLG03, FLG04, ,FLG05, ,FLG06, ,FLG07
 2 ,FLG08, FLG09, ,FLG10, ,FLG11, ,FLG12
 3 ,FLG13, FLG14, ,FLG15, ,FLG16, ,FLG17
 4 ,FLG18, FLG19, ,FLG20, ,FLG21, ,FLG22
 ,FLG23, FLG24, ,FLG25, ,FLG26, ,FLG27

REAL MN

COMMON /CL/ X1(100), Y1(100), X2(100), Y2(100), DELS(100),

1 SINA(100), COSA(100), XP(100), YP(100)

2 ,XWAKE(11), YWAKE(11)

COMMON /TL/ TX1(100), TY1(100), NG(100), TG(100), ALFA(100),

1 RSPDS(100), DALF(100), CHORD, TCNST, DUMMY(1315)

INTEGER RDN

REAL MX, MY, NG

* START

* SETS OF NON-UNIFORM FLOW LOOP

NSIGEC = 0

KA=0

BAS2 001
 BAS2 002
 BAS2 003
 BAS2 004
 BAS2 005
 BAS2 006
 BAS2 007
 BAS2 008
 BAS2 009
 BAS2 010
 BAS2 011
 BAS2 012
 BAS2 013
 BAS2 014
 BAS2 015
 BAS2 016
 BAS2 017
 BAS2 018
 BAS2 019
 BAS2 020
 BAS2 021
 BAS2 022
 BAS2 023
 BAS2 024
 BAS2 025
 BAS2 026
 BAS2 027
 BAS2 028
 BAS2 029
 BAS2 030
 BAS2 031
 BAS2 032
 BAS2 033
 BAS2 034
 BAS2 035

BAS2 036
 BAS2 037
 BAS2 038
 BAS2 039
 BAS2 040
 BAS2 041
 BAS2 042
 BAS2 043
 BAS2 044
 BAS2 045
 BAS2 046
 BAS2 047
 BAS2 048
 BAS2 049
 BAS2 050
 BAS2 051
 BAS2 052
 BAS2 053
 BAS2 054
 BAS2 055
 BAS2 056
 BAS2 057
 BAS2 058
 BAS2 059
 BAS2 060
 BAS2 061
 BAS2 062
 BAS2 063
 BAS2 064
 BAS2 065
 BAS2 066
 BAS2 067
 BAS2 068
 BAS2 069
 BAS2 070

```

KC=0
KEC = 0
DO 1000 I=1,NN(I)
  READ(5,20) NUN,MSF,TYPE,FG
  FORMAT(2(SX I5),2F10.0)
  IF (MSF.EQ.1.OR.MSF.EQ.2.OR.MSF.EQ.5) GO TO 30
  KA=KA+1
  NSTGA=NSIGA+1
  NUNA(KA)=NUN
  TYPEA(KA)=TYPE
  30 IF (MSF.FG.0.OR.MSF.EQ.2.OR.MSF.EQ.4) GO TO 35
  KC=KC+1
  NSIGC=NSIGC+1
  NUNC(KC)=NUN
  TYPEC(KC)=TYPE
  35 IF (MSF.LT.2.OR.MSF.EQ.3) GO TO 40
  KEC = KEC + 1
  NSIGEC = NSIGEC + 1
  NUNEC(KEC) = NUN
  TYPEFC(KEC) = TYPE
  40 IF (TYPE) 50,70,70
      * COMPUTED TYPE
  50 DO 60 I=1,NT
    NG(I)=Y2(I)
    60 TG(I)=FG-X2(I)
    GO TO 110
      * (X,Y) OR (N,T) TYPE * READ INPUT
  70 DO 90 I=1,NT,6
    READ(5,80) NG(I),NG(I+1),NG(I+2),NG(I+3),NG(I+4),NG(I+5)
    80 FORMAT(6F10.0)
    90 CONTINUE
    DO 100 I=1,NT,6
      READ(5,80) TG(I),TG(I+1),TG(I+2),TG(I+3),TG(I+4),TG(I+5)
    100 CONTINUE
    110 IF (TYPE) 120,140,120

```

BAS2

```

120 DO 130 I = 1, NT
    TI=NG(I)
    NG(I)= TI*SINA(I)+TG(I)*COSA(I)
    130 TG(I)= TI*COSA(I)+TG(I)*SINA(I)
    * WRITE BASIC DATA OUTPUT
140 WRITE (6,150) HEDR,MSF,TYPE,FG,NUN,(NG(I),I=1,NT)
150 FORMAT ( 1H1 25X 26MDDOUGLAS AIRCRAFT COMPANY /
    1 2BX, 21HLONG BEACH DIVISION /// 5X 10A6 //
    2 6X 5HMSF = 14, 10X 6HTYPE = F10.4, 10X 4HFG = F13.7 /
    3 1H0, 4X, 20HNON=UNIFORM FLOW NO.16 /
    4 1H0, 4X, 10HLIST OF NG// (1H 6F14.7))
    WRITE (6,160) (TG(I), I = 1, NT)
160 FORMAT (1H0 4X 10HLIST OF TG // (1H 6F14.7))
    WRITE (4) MSF,(NG(I),I=1,NT),(TG(I),I=1,NT)
1000 CONTINUE
    RETURN
    END

```

BAS2 071
BAS2 072
BAS2 073
BAS2 074
BAS2 075
BAS2 076
BAS2 077
BAS2 078
BAS2 079
BAS2 080
BAS2 081
BAS2 082
BAS2 083
BAS2 084
BAS2 085
BAS2 086
BAS2 087

BAS2

```

C
C
C
SURROUTINE MATRIX
      * COMPUTE MATRIX A,R,Z OR X,Y,Z

COMMON HEDR(10) ,CASE ,NB ,NNU ,FLG06 ,FLG07
      ,FLG03 ,FLG04 ,FLG05 ,FLG11 ,FLG12
      ,FLG08 ,FLG09 ,FLG10 ,FLG16 ,FLG17
      ,FLG13 ,FLG14 ,FLG15 ,FLG21 ,FLG22
      ,FLG18 ,FLG19 ,FLG20 ,FLG25 ,FLG26 ,FLG27
      ,FLG23

COMMON NT, ND(11), MN, NUNA(5), TYPEA(5),
      NER1, NER2, NMA, NSIGA, NSIGC,
      NUNC(5), TYPEC(5), NLF(11), IEC, NSIGEC,
      TYPEEC(5), NUNEC(5)

C
DOUBLE PRECISION HEDR, CASE
INTEGER FLG03 ,FLG04 ,FLG05 ,FLG06 ,FLG07
      ,FLG08 ,FLG09 ,FLG10 ,FLG11 ,FLG12
      ,FLG13 ,FLG14 ,FLG15 ,FLG16 ,FLG17
      ,FLG18 ,FLG19 ,FLG20 ,FLG21 ,FLG22
      ,FLG23 ,FLG24 ,FLG25 ,FLG26 ,FLG27

REAL MN
LOGICAL PF

COMMON /FCF/ ECX(100), ECY(100), ECZ(100)
COMMON /RNGWG/ VA(100,2), VR(100,2),VAN(100), VAT(100)
COMMON /CL/ X1(100), Y1(100), X2(100), Y2(100), DELS(100),
      SINA(100), COSA(100), XP(100), YP(100)
      ,XWAKE(11),YWAKE(11)
COMMON /YL/ A(100), B(100), AX(100), AY(100), AZ(100),
      CX(100), CY(100), CZ(100), AXV(100),AVV(100),
      VN(100,5),VT(100,5),BON, IAC,
      I, J, J1, SJ, DS,
      DX, DY, NI, XJ, YJ,
      XK, EEK, EKK, K, PF

C

```

```

C
C
      * START
      * INITIALIZE

      LI=NT
      RON=0.0
      YZER0=0.0
      ***TEST TYPE OF FLOW AND SET INDICATORS IAC AND IEC
      ***CROSS FLOW ONLY          IAC = -1 IEC = -1
      ***AXISYMMETRIC FLOW ONLY   IAC = +1 IEC = 0
      ***EXTRA CROSS FLOW ONLY    IAC = 0 IEC = -1
      ***CROSS FLOW AND AXISYMMETRIC FLOW IAC = -1 IEC = +1
      ***CROSS FLOW AND EXTRA CROSS FLOW IAC = +1 IEC = +1
      ***AXISYMMETRIC AND EXTRA CROSS FLOW IAC = 0 IEC = +1
      ***AXISYMMETRIC, CROSS, AND EXTRA CROSS
      IF(FLG03)30,10,30
      10 IF(FLG04)25,15,25
      15 IAC = 0
      IEC = 0
      GO TO 55
      25 IAC = -1
      GO TO 45
      30 IF(FLG04)35,40,35
      35 IAC = 0
      GO TO 45
      40 IAC = 1
      45 IF(FLG21)50,53,50
      50 IEC = +1
      GO TO 55
      53 IEC = -1
      55 ASSIGN 110 TO K1
      IF (FLG15.GT.0) ASSIGN 102 TO K1
      60 DO 70 I=1,L1
      DO 65 J = 1,5
      VN(I,J) = 0.
      65 VT(I,J) = 0.
      VAN(I)=0.0

```

MATX 036
 MATX 037
 MATX 038
 MATX 039
 MATX 040
 MATX 041
 MATX 042
 MATX 043
 MATX 044
 MATX 045
 MATX 046
 MATX 047
 MATX 048
 MATX 049
 MATX 050
 MATX 051
 MATX 052
 MATX 053
 MATX 054
 MATX 055
 MATX 056
 MATX 057
 MATX 058
 MATX 059
 MATX 060
 MATX 061
 MATX 062
 MATX 063
 MATX 064
 MATX 065
 MATX 066
 MATX 067
 MATX 068
 MATX 069
 MATX 070

MATX

```

C
70 VAT(I)=0.0
C
C      * I MIDPOINT LOOP
DO 400 I=1,L1
C
C      * J ELEMENT LOOP
J1 IS THE COORDINATE COUNTER
J IS THE ELEMENT COUNTER
J1=0
N1=0
IF (FLG23.GT. 0)CALL NOTS
DO 110 K=1,NB
M1=N1+1
N1=N1+ND(K)=1
DO 100 J=M1,N1
J1=J1+1
PF = FLG18.GT.0.AND.J.GT.NMA.OR.FLG20.GT.0
C      * COMPUTE X,Y,Z MATRICES
CALL XYZ
100 CONTINUE
GO TO K1, (102,110)
102 IF (NLF(K).GT.0) GO TO 110
IF (RON.EQ.0.) GO TO 105
DO 103 J = M1, N1
VN(I,K) = VN(I,K)+AXV(J)
103 VT(I,K) = VT(I,K)+AYV(J)
GO TO 110
105 DO 106 J = M1, N1
VN(I,K) = VN(I,K) +AXV(J)*SINA(I) - AYV(J)*COSA(I)
106 VT(I,K) = VT(I,K) +AXV(J)*COSA(I) + AYV(J)*SINA(I)
110 J1=J1+1
IF( FLG08.LE.0 .OR. FLG15.LE. 0 )GO TO 118
C
C*** * PRINT STRIP VORTEX MATRICES
C
IF( I.EQ. 1 .AND. RON.EQ. 0. )WRITE(6,111)
IF( I.EQ. 1 .AND. RON.EQ. 1. )WRITE(6,112)

```

MATX

MATX

```

111 FORMAT(1H1,31H STRIP VORTEX MATRICES ON BODY //)
112 FORMAT(1H1,31H STRIP VORTEX MATRICES OFF BODY //)
WRITE(6,114)I,( AXV(J),J=1,NT)
WRITE(6,115) ( AVV(J),J=1,NT)
114 FORMAT(1H0,5H ROW,14/9H X MATRIX / (6E20.7) )
115 FORMAT(9H Y MATRIX / (6E20.7) )
118 IF (RON)120,210,120
      * SAVE X,Y,Z ON TAPE *OFF BODY POINTS
C**   **SAVE X,Y,Z ON TAPE * OFF BODY POINTS
C**   **AXISYMMETRIC FLOW * TAPE 9
C**   **CROSS FLOW * TAPE 10
C**   **EXTRA CROSS FLOW * TAPE 8
120 IF(IEC.EQ.,1)GO TO 125
122 WRITE(8) (ECX(J),J=1,NT), (ECY(J),J=1,NT), (ECZ(J),J=1,NT)
      IF (IEC) 125,400,125
125 IF(IAC) 140,130,130
130 WRITE (9) (AX(J),J=1,NT),(AY(J),J=1,NT),(AZ(J),J=1,NT)
      IF (IAC) 400,140,400
140 WRITE (10)(CX(J),J=1,NT),(CY(J),J=1,NT),(CZ(J),J=1,NT)
      GO TO 400
C**   **SAVE ON TAPE * ON BODY
C**   **AXISYMMETRIC FLOW * TAPE 9
C**   **CROSS FLOW * TAPE 10
C**   **EXTRA CROSS FLOW * TAPE 8
C**   **IEC = 1 MEANS NO EXTRA CROSS FLOW
210 IF (IEC.EQ.,1) GO TO 240
220 DO 230 J = 1,NT
      A(J) = -ECX(J) * SINA(I) + ECY(J) * COSA(I)
230 B(J) = ECX(J) * COSA(I) + ECY(J) * SINA(I)
      WRITE (8) (A(J),J=1,NT), (B(J),J=1,NT), (ECZ(J),J=1,NT)
      IF ( IEC ) 240,400,240
240 IF (IAC) 310,250,250
250 DO 260 J=1,NT
      A(J)=-AX(J)*SINA(I)+AY(J)*COSA(I)
260 B(J)=AX(J)*COSA(I)+AY(J)*SINA(I)

```

MATX 106
MATX 107
MATX 108
MATX 109
MATX 110
MATX 111
MATX 112
MATX 113
MATX 114
MATX 115
MATX 116
MATX 117
MATX 118
MATX 119
MATX 120
MATX 121
MATX 122
MATX 123
MATX 124
MATX 125
MATX 126
MATX 127
MATX 128
MATX 129
MATX 130
MATX 131
MATX 132
MATX 133
MATX 134
MATX 135
MATX 136
MATX 137
MATX 138
MATX 139
MATX 140

MATX

MATX

```

WRITE (9) (A(J),J=1,NT),(B(J),J=1,NT),(AZ(J),J=1,NT)
270 IF (IAC) 400,310,400
310 DO 320 J=1,NT
    A(J)=-CX(J)*SINA(I)+CY(J)*COSA(I)
320 B(J)=CX(J)*COSA(I)+CY(J)*SINA(I)
    WRITE (10) (A(J),J=1,NT),(B(J),J=1,NT),(CZ(J),J=1,NT)
400 CONTINUE
    IF (FLG15.LE.0) GO TO 1400
    IF (RON.NE.0.) GO TO 1200
C*** **ON BODY
    READ (4)
C
C*** * IF FLG23 .GT. 0 INPUT NNU MUST BE NONE, HENCE NNU = 0 HERE
C
    IF (NNU.LE.0) GO TO 600
    DO 500 I = 1, NNU
        READ (4) MSF,(A(J),J=1,NT),(B(J),J=1,NT)
500 WRITE (3) MSF,(A(J),J=1,NT),(B(J),J=1,NT)
        REWIND 3
        REWIND 4
        READ (4)
600 NENSIGA=1
    IF (FLG16.GT.1) N=NSIGA
C*** **N = 0 MEANS 1 RHS ONLY NO NON-UNIFORM FLOW
C*** * IF FLG23 .GT. 0 INPUT NNU MUST BE NONE, HENCE N = 0 HERE
C
    IF (N.EQ.0) GO TO 800
    DO 700 I = 1, N
        READ (3) MSF,(A(J),J=1,NT),(B(J),J=1,NT)
700 WRITE (4) MSF,(A(J),J=1,NT),(B(J),J=1,NT)
800 M=0
C*** * SKIP PRESCRIED VORTEX INPUTS ON 4 SO THAT STRIP VORTEX
C*** * SUMMATIONS CAN GO BEHIND IT
C
    IF (FLG23 .GT. 0) READ (4)

```

MATX 141
 MATX 142
 MATX 143
 MATX 144
 MATX 145
 MATX 146
 MATX 147
 MATX 148
 MATX 149
 MATX 150
 MATX 151
 MATX 152
 MATX 153
 MATX 154
 MATX 155
 MATX 156
 MATX 157
 MATX 158
 MATX 159
 MATX 160
 MATX 161
 MATX 162
 MATX 163
 MATX 164
 MATX 165
 MATX 166
 MATX 167
 MATX 168
 MATX 169
 MATX 170
 MATX 171
 MATX 172
 MATX 173
 MATX 174
 MATX 175

MATX


```

DO 900 J = 1, NB
  IF (NLF(J).GT.0) GO TO 900
  NSIGA=NSIGA+1
  NNU=NNU+1
  WRITE (4) M,(VN(I,J),I=1,NT),(V(I,J),J=1,NT)
900 CONTINUE
C
C*** * SINCE NO NNU IS INPUT WITH FLG23 GT 0, NSIGC IS MAX OF 1 AND M
C*** * SHOULD BE 0 IF FLG17 LE 0. DONT USE FLG17 WITH FLG23
C
  IF (FLG23.LE. 0) GO TO 975
C
C*** * RING WING OPTION = FORM COLUMN (PARTLY) FOR PRESCRIBED VORTICITY
C*** *RHS
C
  IBOD = 0
  DO 950 J=1,NB
    IF (NLF(J).GT. 0) GO TO 950
    IBOD = IBOD + 1
C
C*** * CONVERT (ON BODY) X,Y TO NORMAL, TANGENTIAL
C
    DO 925 I=1,NT
      VAN(I) = VAN(I) + VA(I,IBOD)*SINA(I) - VR(I,IBOD)*COSA(I)
      VAT(I) = VAT(I) + VA(I,IBOD)*COSA(I) + VR(I,IBOD)*SINA(I)
      WRITE(4)(VAN(I),I=1,NT),(VAT(I),I=1,NT)
950 CONTINUE
975 M = NSIGC - 1
    IF (FLG17.GT.0) M=NSIGC
    IF (M.LE.0) GO TO 1100
    DO 1000 I = 1, M
      READ (3) MSF,(A(J),J=1,NT),(B(J),J=1,NT)
      WRITE (4) MSF,(A(J),J=1,NT),(B(J),J=1,NT)
1000 REWIND 3
1100 GO TO 1400

```

MATX 176
 MATX 177
 MATX 178
 MATX 179
 MATX 180
 MATX 181
 MATX 182
 MATX 183
 MATX 184
 MATX 185
 MATX 186
 MATX 187
 MATX 188
 MATX 189
 MATX 190
 MATX 191
 MATX 192
 MATX 193
 MATX 194
 MATX 195
 MATX 196
 MATX 197
 MATX 198
 MATX 199
 MATX 200
 MATX 201
 MATX 202
 MATX 203
 MATX 204
 MATX 205
 MATX 206
 MATX 207
 MATX 208
 MATX 209
 MATX 210

MATX

MATX

```

C*** **OFF BODY
1200 DO 1300 J = 1, NB
      IF (NLF(J).GT.0) GO TO 1300
      WRITE(4) (VN(I,J), I = 1,L1), (VT(I,J), I = 1,L1)
1300 CONTINUE
      IF (FLG23.LE. 0) GO TO 1400
      IBOD = 0
      DO 1350 J=1,NB
        IF (NLF(J).GT. 0) GO TO 1350
        IBOD = IBOD + 1
        WRITE(4) ( VA(I,IBOD),I=1,L1 ), ( VR(I,IBOD),I=1,L1)
1350 CONTINUE
C      * TEST IF OFF BODY COMPLETED
C      * TEST IF OFF BODY
1400 IF (FLG05.EQ.0.OR,BON.NE.0.) GO TO 1600
C      * INITIAL FOR OFF BODY * THEN RE-ENTER I,J LOOPS
      BUN=1.
      LI=ND(NB+1)
      DO 1500 I = 1, L1
        X2(I) = XP(I)
        Y2(I) = YP(I)
        GO TO 60
1600 REWIND 9
      REWIND 8
      REWIND 10
      REWIND 4
      RETURN
      END

```

MATX 211
 MATX 212
 MATX 213
 MATX 214
 MATX 215
 MATX 216
 MATX 217
 MATX 218
 MATX 219
 MATX 220
 MATX 221
 MATX 222
 MATX 223
 MATX 224
 MATX 225
 MATX 226
 MATX 227
 MATX 228
 MATX 229
 MATX 230
 MATX 231
 MATX 232
 MATX 233
 MATX 234
 MATX 235
 MATX 236
 MATX 237
 MATX 238

XYZ

SUBROUTINE XYZ

C
C
C

* CONTROL FOR X,Y,Z MATRICES COMPUTATION

```

COMMON /D/ D1, D3, XMXJ, VMYJ, XMXJP1, VMYJP1, S
COMMON
COMMON
1  ,FLG03  ,CASE  ,NB  ,FLG05  ,FLG06  ,FLG07
2  ,FLG08  ,FLG04  ,FLG09  ,FLG10  ,FLG11  ,FLG12
3  ,FLG13  ,FLG14  ,FLG15  ,FLG16  ,FLG17
4  ,FLG18  ,FLG19  ,FLG20  ,FLG21  ,FLG22
5  ,FLG23  ,FLG24  ,FLG25  ,FLG26  ,FLG27

```

```

COMMON NT, ND(11), MN, NUNA(5), TYPEA(5),
1  NER1, NER2, NER3, NMA, NSIGA, NSIGC,
2  NUNC(5), TYPEC(5), NLP(11), IFC, NSIGEC,
3  TYPEFEC(5), NUNEC(5)

```

C DOUBLE PRECISION HEDR, CASE

```

INTEGER
1  ,FLG03  ,FLG04  ,FLG05  ,FLG06  ,FLG07
2  ,FLG08  ,FLG09  ,FLG10  ,FLG11  ,FLG12
3  ,FLG13  ,FLG14  ,FLG15  ,FLG16  ,FLG17
4  ,FLG18  ,FLG19  ,FLG20  ,FLG21  ,FLG22
5  ,FLG23  ,FLG24  ,FLG25  ,FLG26  ,FLG27

```

REAL MN

LOGICAL PF

C

```

COMMON /RNGWNG/ VA(100,2), VR(100,2), VAN(100), VAT(100)
COMMON /CL/ X1(100), Y1(100), X2(100), Y2(100), DELS(100),
1  SINA(100), COSA(100), XP(100), YP(100)
2  ,XWAKE(11),YWAKE(11)

```

```

COMMON /TL/ A(100), B(100), AX(100), AY(100), AZ(100),
1  CX(100), CY(100), CZ(100), AXV(100), AYV(100),
2  VN(100,5), VT(100,5), BUN, IAC,
3  I, J, J1, SJ, DS,
4  DX, DY, NI, XJ, YJ,
5  XK, EEK, EKK, K, XJ, YJ, PF

```

C

```

XYZ 001
XYZ 002
XYZ 003
XYZ 004
XYZ 005
XYZ 006
XYZ 007
XYZ 008
XYZ 009
XYZ 010
XYZ 011
XYZ 012
XYZ 013
XYZ 014
XYZ 015
XYZ 016
XYZ 017
XYZ 018
XYZ 019
XYZ 020
XYZ 021
XYZ 022
XYZ 023
XYZ 024
XYZ 025
XYZ 026
XYZ 027
XYZ 028
XYZ 029
XYZ 030
XYZ 031
XYZ 032
XYZ 033
XYZ 034
XYZ 035

```

XYZ

XYZ

```

C      * START
      IF (BON) 100,10,100
      10 IF (J-I) 110,20,110
C      * J EQUAL I PATH
      20 T1=.5*DELS(J)
      SJ=T1/Y2(J)
      IF (SJ=.08) 30,30,40
      30 CALL XYZ1
      GO TO 1000
      40 SJ=.08
      CALL XYZ1
      NI=33
      T2=.08*Y2(J)
      DS=(T1-T2)/32.
      DX=DS*COXA(J)
      DY=DS*SINA(J)
      XJ=X2(J)+T2*COXA(J)=DX
      YJ=Y2(J)+T2*SINA(J)=DY
      CALL XYZ2
      GO TO 300
C      * INITIAL Y COORDINATE MID-POINT FOR ZERO TEST
      100 YZERD=Y2(I)=.000001
C      * J NOT EQUAL I PATH
C      * COMPUTE MINIMUM DISTANCE TO I MIDPOINT
      110 J1P1 = J1 + 1
      XMJ = X2(I) - X1(J1)
      YMJ = Y2(I) - Y1(J1)
      XMJPI = X2(I) - X1(J1P1)
      YMJPI = Y2(I) - Y1(J1P1)
      D1 = XMJ**2 + YMJ**2
      D2 = (X2(I)-X2(J))**2 + (Y2(I)-Y2(J))**2
      D3 = XMJPI**2 + YMJPI**2
      S = SQRT( (X1(J1P1) - X1(J1))**2 + (Y1(J1P1) - Y1(J1))**2 )
      IF (D1=D2) 130,130,120
      120 IF (D2=D3) 150,150,140

```

XYZ

XYZ

```

130 IF (D1-D3) 160,160,140
140 DM=SQRT(D3)
    GO TO 170
150 DM=SQRT(D2)
    GO TO 170
160 DM=SQRT(D1)
    * COMPUTE NO. OF INTERVALS(NI) AND DELTA S (DS)
    FOR SIMPSON RULE INTEGRATION
170 IF (DM.EQ.0.0) GO TO 200
    NI=8.*DELS(J)/DM+.9
    IF (NI) 180,180,190
180 NI=3
    DS=DELS(J)/2.
    GO TO 220
190 NI=NI+NI
    IF (NI-128) 210,200,200
200 NI=129
    DS=DELS(J)/128.
    GO TO 220
210 XNI=NI
    DS=DELS(J)/XNI
    NI=NI+1
220 DX=DS*COSA(J)
    DY=DS*SINA(J)
300 XJ=X1(J1)-DX
    YJ=Y1(J1)-DY
    CALL XYZ2
1000 RETURN
    END

```

```

XYZ 071
XYZ 072
XYZ 073
XYZ 074
XYZ 075
XYZ 076
XYZ 077
XYZ 078
XYZ 079
XYZ 080
XYZ 081
XYZ 082
XYZ 083
XYZ 084
XYZ 085
XYZ 086
XYZ 087
XYZ 088
XYZ 089
XYZ 090
XYZ 091
XYZ 092
XYZ 093
XYZ 094
XYZ 095
XYZ 096
XYZ 097
XYZ 098
XYZ 099

```

XYZ

XYZI

SUBROUTINE XYZI

* COMPUTE X,Y,Z MATRICES FOR SJ LESS THAN OR EQUAL .08

```
COMMON HEDR(10) ,CASE ,NB ,NNU ,FLG07
1 ,FLG03 ,FLG04 ,FLG05 ,FLG06 ,FLG12
2 ,FLG08 ,FLG09 ,FLG10 ,FLG11 ,FLG12
3 ,FLG13 ,FLG14 ,FLG15 ,FLG16 ,FLG17
4 ,FLG18 ,FLG19 ,FLG20 ,FLG21 ,FLG22
5 ,FLG23 ,FLG24 ,FLG25 ,FLG26 ,FLG27
```

```
COMMON NT, ND(11), MN, NUNA(5), TYPEA(5),
1 NER1, NER2, NMA, NSIGA, NSIGC,
2 NUNC(5), TYPEC(5), NLF(11), IFC, NSIGEC,
```

```
C DOUBLE PRECISION HEDR, CASE
INTEGER FLG03 ,FLG04 ,FLG05 ,FLG06 ,FLG07
```

```
1 ,FLG08 ,FLG09 ,FLG10 ,FLG11 ,FLG12
2 ,FLG13 ,FLG14 ,FLG15 ,FLG16 ,FLG17
3 ,FLG18 ,FLG19 ,FLG20 ,FLG21 ,FLG22
4 ,FLG23 ,FLG24 ,FLG25 ,FLG26 ,FLG27
COMMON /RNGWNG/ VA(100,2), VR(100,2),VAN(100), VAT(100)
COMMON /ECF/ ECX(100), ECV(100), ECZ(100)
```

REAL MN

LOGICAL PF

```
COMMON /CL/ X1(100), Y1(100), X2(100), Y2(100), DELS(100),
1 SINA(100), COSA(100), XP(100), YP(100)
```

```
2 ,XWAKE(11),YWAKE(11)
```

```
COMMON /TL/ A(100), R(100), AX(100), AY(100), AZ(100),
1 CX(100), CY(100), CZ(100), AXV(100),AYV(100),
2 VN(100,5),VT(100,5),BUN,
```

```
3 I, J, J1, SJ, DS,
4 DX, DY, NI, XJ, YJ,
5 XK, FEK, EKK, K, PF
```

XYZI 001
XYZI 002
XYZI 003
XYZI 004
XYZI 005
XYZI 006
XYZI 007
XYZI 008
XYZI 009
XYZI 010
XYZI 011
XYZI 012
XYZI 013
XYZI 014
XYZI 015
XYZI 016
XYZI 017
XYZI 018
XYZI 019
XYZI 020
XYZI 021
XYZI 022
XYZI 023
XYZI 024
XYZI 025
XYZI 026
XYZI 027
XYZI 028
XYZI 029
XYZI 030
XYZI 031
XYZI 032
XYZI 033
XYZI 034
XYZI 035

XYZI

XYZ1

XYZ1

```

C
C
      * START
      * INITIALIZE

      T1=SJ*SJ
      T2=ALOG(SJ/8.)
      T3=SINA(J)*SINA(J)
      T4=T2+T3
      T5=.6666667 *T3
      T6=T5+T3
      T7=SJ+SJ
      T8=T7+T7
      T9=.283185 *COSA(J)
      T10=.6.283185 *SINA(J)
      T11=T1*SJ
      T14 = .3333333 * (16.0 + 6.0 * T3) + 2.0 * T2
      IF (IEC, EQ, 1) GO TO 15
      **FXTRA CROSS FLOW 1ST TERM OF X(I,I), Y(I,I), Z(I,I)
10 ECX(J) = 6.283185 * SINA(J) + 2.0 * SINA(J) * COSA(J) * SJ
   ECV(J) = 6.283185 * COSA(J) + SJ * T14
   ECZ(J) = 8.0 * (1.666667 + T2) * SJ
   IF (IEC) 15, 100, 15
15 IF (PF) GO TO 25
   IF (IAC) 30, 20, 20
      * AXIS FLOW
20 AX(J)=T10+SINA(J)*COSA(J)*(T7+(T4+2.166667 )+T11/12.)
   AY(J)=T7+T4+T9=(1.+T2-T3-T6)*T11/8.
   T12=T1+T1
   AZ(J)=Y2(J)*T8*(1.+T2+T1*(2.-T12+3.*T2*(1.+T12))/144.)
25 IF (IAC) 30, 30, 100
      * CROSS FLOW
30 T13=T1/16.
   CX(J)=T10+2.*SINA(J)*SJ+COSA(J)*(1.-T13*(3.-T5+T2+T2))
   CY(J)=T9+T7*(2.+T4+T13*(1.-4.777778 *T3+T6+T2*(3.-2.666667 *
1      T3)))
   CZ(J)=T8*(1.+T2-T13*(1.11111 *T3+T2*(T5-1.)))
100 IF (PF) GO TO 200

```

XYZ1 036
 XYZ1 037
 XYZ1 038
 XYZ1 039
 XYZ1 040
 XYZ1 041
 XYZ1 042
 XYZ1 043
 XYZ1 044
 XYZ1 045
 XYZ1 046
 XYZ1 047
 XYZ1 048
 XYZ1 049
 XYZ1 050
 XYZ1 051
 XYZ1 052
 XYZ1 053
 XYZ1 054
 XYZ1 055
 XYZ1 056
 XYZ1 057
 XYZ1 058
 XYZ1 059
 XYZ1 060
 XYZ1 061
 XYZ1 062
 XYZ1 063
 XYZ1 064
 XYZ1 065
 XYZ1 066
 XYZ1 067
 XYZ1 068
 XYZ1 069
 XYZ1 070

XYZ1

```

IF (FLG15.LE.0.OR.NLF(K).GT.0) GO TO 1000
200 AXV(J) = T9+T7*(T2-T3)+T11*(T2*(12.*T3-9.)
1      -9. + 23.*T3 - 6.*T3*T3) / 72.
      AVV(J) = T10 + 2.*COSA(J)*SINA(J)*(SJ-T11*(6.*T2+9.-2.*T3)/48. )
IF (.NOT.PF) GO TO 1000
AX(J) = AXV(J)
AY(J) = AVV(J)

C*** * RING WING OPTION PV EFFECTS ON ITSELF NEGLECTS 2*PI TERMS
C
IF(FLG23 .LE. 0)GO TO 1000
AX(J) = AX(J) - T9
AY(J) = AY(J) - T10
AVV(J)=AY(J)
AXV(J)=AX(J)
1000 CONTINUE
      RETURN
      END

```

```

XYZ1 071
XYZ1 072
XYZ1 073
XYZ1 074
XYZ1 075
XYZ1 076
XYZ1 077
XYZ1 078
XYZ1 079
XYZ1 080
XYZ1 081
XYZ1 082
XYZ1 083
XYZ1 084
XYZ1 085
XYZ1 086
XYZ1 087
XYZ1 088

```

XYZ1

XYZZ

```

C
C
C
      SURROUTINE XYZZ
      * COMPUTE X,Y,Z MATRICES USING SIMPSON RULE INTEGRATION

      REAL LIJ2D
      COMMON /D/ R1SOR, R2SOR, XMXJ, YMYJ, XMXJPI, YMYJPI, S
      COMMON
      1 HEDR(10) ,CASE ,NB ,NNU ,FLG06 ,FLG07
      2 ,FLG03 ,FLG04 ,FLG05 ,FLG11 ,FLG12
      3 ,FLG08 ,FLG09 ,FLG10 ,FLG16 ,FLG17
      4 ,FLG13 ,FLG14 ,FLG15 ,FLG21 ,FLG22
      5 ,FLG18 ,FLG19 ,FLG20 ,FLG25 ,FLG26 ,FLG27
      6 ,FLG23 ,FLG24 ,FLG25 ,NUNA(5) ,TYPEA(5) ,
      7 COMMON NT, ND(11) ,MN, NMA, NSIGA, NSIGC,
      8 NER1, NER2, TYPEC(5) ,NLF(11) ,IEC, NSIGEC,
      9 NUNC(5) ,TYPEEC(5) ,NUNEC(5)
      10 TYPEEC(5) ,NUNEC(5)
      11 DOUBLE PRECISION HEDR, CASE
      12 INTEGER
      13 ,FLG03 ,FLG04 ,FLG05 ,FLG06 ,FLG07
      14 ,FLG08 ,FLG09 ,FLG10 ,FLG11 ,FLG12
      15 ,FLG13 ,FLG14 ,FLG15 ,FLG16 ,FLG17
      16 ,FLG18 ,FLG19 ,FLG20 ,FLG21 ,FLG22
      17 ,FLG23 ,FLG24 ,FLG25 ,FLG26 ,FLG27
      18 COMMON /ECF/ ECX(100) ,ECY(100) ,ECZ(100)
      19 COMMON /RNGWNG/ VA(100,2) ,VR(100,2) ,VAN(100) ,VAT(100)
      20 DATA NSW /1/
      21 ***RSMALL WILL BE TRUE IF IS .LT. EPS AND THEREFORE SMALL EL
      22 LOGICAL RSMALL
      23 REAL
      24 LOGICAL PF
      25
      26 COMMON /CL/
      27 1 X1(100) ,Y1(100) ,X2(100) ,Y2(100) ,DELS(100) ,
      28 2 SINA(100) ,COSA(100) ,XP(100) ,VP(100)
      29 ,XWAKE(11) ,YWAKE(11)
      30 COMMON /TL/
      31 1 A(100) ,B(100) ,AX(100) ,AY(100) ,AZ(100) ,
      32 CX(100) ,CY(100) ,CZ(100) ,AXV(100) ,AVV(100) ,
      33

```

XYZZ

XYZZ

```

2      VN(100,5),VT(100,5),8UN,
3      I,      J,      SJ,      DS,
4      DX,      DY,      XJ,      YJ,
5      XK,      EKK,      K,      PF

C      * START
C      * INITIALIZE
C      EPS = 0.0
C      ASSIGN 570 TO K1
C      ***K5 = 80 FOR NON-SMALL ELEMENT AXISYMMETRIC
C      ASSIGN 80 TO K5
C      ***K6 = 295 FOR NON SMALL ELEMENT CROSS FLOW
C      ASSIGN 295 TO K6
C      IF (FLG15.LE.0.OR.NLF(K).GT.0) GO TO 15
10     ASSIGN 420 TO K1
15     S2=.6666667 *DS
      S1 = .3333333 * DS
      S3 = 8.0/3.0 * S1
      S5 = .3333333 * S1
      S4 = S2+S2
      T1=Y2(I)*Y2(I)
      ASSIGN 28 TO K2
      ASSIGN 410 TO K3
      ASSIGN 570 TO K4
      IF (.NOT. PF ) GO TO 12
      ASSIGN 110 TO K2
      ASSIGN 420 TO K3
      ASSIGN 560 TO K4
12     IF ( (I.NE. J) .OR. (RON .NE. 0.0) ) GO TO 16
C      ***I = J ** ON BODY
      R = DELS(I) / 2.0
      RSMALL = ( R / Y2(I) ) .LT. EPS
      NSW = 2
      GO TO 17
16     R = SQRT( AMAX1(R1SQ,R2SQR) )

```

```

XYZZ 036
XYZZ 037
XYZZ 038
XYZZ 039
XYZZ 040
XYZZ 041
XYZZ 042
XYZZ 043
XYZZ 044
XYZZ 045
XYZZ 046
XYZZ 047
XYZZ 048
XYZZ 049
XYZZ 050
XYZZ 051
XYZZ 052
XYZZ 053
XYZZ 054
XYZZ 055
XYZZ 056
XYZZ 057
XYZZ 058
XYZZ 059
XYZZ 060
XYZZ 061
XYZZ 062
XYZZ 063
XYZZ 064
XYZZ 065
XYZZ 066
XYZZ 067
XYZZ 068
XYZZ 069
XYZZ 070

```

XYZZ

XYZ2

```

IF( ABS(Y2(I) ) .LT. 10E-30)GO TO 13
RSMALL = ( R / Y2(I) ) .LT. EPS
GO TO 17
13 RSMALL = .FALSE.
17 IF( .NOT. RSMALL) GO TO 19
C** **SMALL ELEMENT == FORM XIJ2D, YIJ2D, LIJ
C
C** **K5 = 105 FOR SMALL ELEMENT AXISYMMETRIC
  ASSIGN 105 TO K5
C** **K6 = 320 FOR SMALL ELEMENT  CRUSS FLOW
  ASSIGN 320 TO K6
C** **NSW = 1 FOR I NE J
C** **NSW = 2 FOR I EQ J 1ST TIME THROUGH
C** **NSW = 3 FOR I EQ J 2ND TIME THROUGH
  GO TO (14, 21, 22), NSW
C
C** **I = J 1ST TIME THROUGH
21 XLEFT = XJ + DX
  YLEFT = YJ + DY
  JIP1 = J + 1
  XRIGHT = X1(JIP1)
  YRIGHT = Y1(JIP1)
C** **GET NSW READY FOR I = J 2ND TIME THROUGH
  NSW = 3
  GO TO 23
C** **I = J 2ND TIME THROUGH
22 XLEFT = X1(J1)
  YLEFT = Y1(J1)
  XRIGHT = XLEFT + 32.0 * DX
  YRIGHT = YLEFT + 32.0 * DY
  NSW = 1
C** **CALCULATE QUANTITIES WHICH HAVE NOT YET BEEN CALCULATED FOR I=4
23 XMXJ = X2(I) - XLEFT
  YMYJ = Y2(I) - YLEFT
  XMXJPI = X2(I) - XRIGHT

```

XYZ2

```

XYZ2 071
XYZ2 072
XYZ2 073
XYZ2 074
XYZ2 075
XYZ2 076
XYZ2 077
XYZ2 078
XYZ2 079
XYZ2 080
XYZ2 081
XYZ2 082
XYZ2 083
XYZ2 084
XYZ2 085
XYZ2 086
XYZ2 087
XYZ2 088
XYZ2 089
XYZ2 090
XYZ2 091
XYZ2 092
XYZ2 093
XYZ2 094
XYZ2 095
XYZ2 096
XYZ2 097
XYZ2 098
XYZ2 099
XYZ2 100
XYZ2 101
XYZ2 102
XYZ2 103
XYZ2 104
XYZ2 105

```

XYZZ

```

YMYJP1 = Y2(I) - YRIGHT
RLEFT = R
RRIGHT = R
S = SQRT( (XLEFT - XRIGHT)**2 + (YLEFT - YRIGHT)**2 )
GO TO 11
C** * * * J SMALL ELEMENT
14 RLEFT = R1SOR
RRIGHT = R2SOR
C** * * * NOW FORM XIJ2D, YIJ2D, LIJ
11 H = (-XMXJ * SINA(J)) + ( YMYJ * COSA(J) )
FL1 = (XMXJ * COSA(J)) + ( YMYJ * SINA(J) )
EL2 = (XMXJP1 * COSA(J)) + (YMYJP1 * SINA(J) )
DPHIDX = ALOG (RLEFT / RRIGHT)
IF(ABS(H/EL1) .LT. 10.0E-10) GO TO 7
DPHIDY = -2.0 * ( ATAN(EL1/H) - ATAN(EL2/H) )
GO TO 8
7 DPHIDY = 0.0
IF( (EL1 * EL2) .LT. 0.0) DPHIDY = -6.283186
8 XIJ2D = (COSA(J)*DPHIDX) - (SINA(J)*DPHIDY)
YIJ2D = (SINA(J)*DPHIDX) + (COSA(J)*DPHIDY)
LIJ2D = ( (-EL1 + EL2) / 4.0 ) * DPHIDX
1 + ( (S/4.0) * ALOG( (RLEFT * RRIGHT) / ( 4096.0 * T1**2) ) )
2 -S = ( (H/2.0) * DPHIDY )
* NO. OF INTERVAL LOOP
19 DO 1000 IS=1,NI
XJ=XJ+DX
YJ=YJ+DY
T2=YJ*YJ
T3=X2(I)-XJ
T4=T3*T3
T5=(Y2(I)+YJ)**2
T6=T4+T5
T7=SQRT(T6)
T8=T2+T4
T9A = Y2(I) - YJ

```

XYZZ 106
 XYZZ 107
 XYZZ 108
 XYZZ 109
 XYZZ 110
 XYZZ 111
 XYZZ 112
 XYZZ 113
 XYZZ 114
 XYZZ 115
 XYZZ 116
 XYZZ 117
 XYZZ 118
 XYZZ 119
 XYZZ 120
 XYZZ 121
 XYZZ 122
 XYZZ 123
 XYZZ 124
 XYZZ 125
 XYZZ 126
 XYZZ 127
 XYZZ 128
 XYZZ 129
 XYZZ 130
 XYZZ 131
 XYZZ 132
 XYZZ 133
 XYZZ 134
 XYZZ 135
 XYZZ 136
 XYZZ 137
 XYZZ 138
 XYZZ 139
 XYZZ 140

XYZZ

XYZZ

```

      T9 = T9A**2
      T10 = T9**T4
      T10A = SQRT(T10)

C      ***      IF DENOM (T8) IS ZERO THEN MAKE T21 FAIL ALL TESTS
C
C      IF( ABS(T8) .LT. 10.0E-30)GO TO 29
      T21 = SQRT( T1 / T8 )
      GO TO 27
29 T21 = 0.10
C      * COMPUTE ELLIPIC INTEGRAL
27 IF(RSMALL .AND. FLG21.EQ. 0)GO TO 1A
      XK=4.*YJ*Y2(I)/T6
      CALL ELIP
      IF ( IEC ) 10,575,18
1A IF (IAC) 200,20,20
      * AXIS FLOW
C      20 IF (RSMALL)GO TO 25
      T11 = YJ/T7
      IF ( T21.LT.0.01) GO TO 24
      T12 = YJ/Y2(I)
      FV2 = (EKK*EEK*(T1-T8)/T10)/T7
      FV3 = Y2(I)/T10 * T3/T7 * EEK
      F1 = FV3*T12
      F2 = FV2*T12
      FV4 = FV2*T3/Y2(I)
      F3=T11*EEK
      GO TO 26
24 FV2 = 0.
      FV3 = 0.
      FV4 = 0.
C      ***SMALL Y FORMULAS AXISYMMETRIC FLOW
      T23 = T1 / T8**2
      T24 = 2.0 * T4 * T2
      F1 = ( ( 1.570796 * YJ * T3 ) / ( T8**1.5 ) ) *

```

XYZZ

```

XYZZ 141
XYZZ 142
XYZZ 143
XYZZ 144
XYZZ 145
XYZZ 146
XYZZ 147
XYZZ 148
XYZZ 149
XYZZ 150
XYZZ 151
XYZZ 152
XYZZ 153
XYZZ 154
XYZZ 155
XYZZ 156
XYZZ 157
XYZZ 158
XYZZ 159
XYZZ 160
XYZZ 161
XYZZ 162
XYZZ 163
XYZZ 164
XYZZ 165
XYZZ 166
XYZZ 167
XYZZ 168
XYZZ 169
XYZZ 170
XYZZ 171
XYZZ 172
XYZZ 173
XYZZ 174
XYZZ 175

```

```

1  ( 1.0 + ( .75 * ( 3.0 * T2 - 2.0 * T4 ) * T23 ) )
F2 = ( 1.570796 * YJ * Y2(I) ) * ( T24 / (T8**2.5 ) )
F3 = 1.570796 * YJ * ( 1.0 + (.25 * T23 * (-T24) ) ) / SORT(T8 )
GO TO 26
25  T32 = T3 / T10A
T33 = T9A / T10A
T34 = T33**2
T35A = T10A / (8.0 * Y2(I) )
T35 = ALOG(T35A)
T36 = T9A/Y2(I)
T40 = T10A / Y2(I)
T37 = (T40**2)*0.125
T38 = 0.250*T36*T35
T39 = 0.125*T36
T34A = 2.0*T34
T34B = T34A + 3.0
F1 = ( -2.0 * T32 * ( (-T35A * T35) - (0.5 * T33) )
      - ( (T40/16.0) * T34B ) ) / Y2(I)
1  F2 = ( (0.25 * T36 * T35) - T34 - 1.0 - (T39 * T34B) ) / Y2(I)
F3 = ( T35 * ( T36 + (0.25 * T36**2) + T37 ) ) - T36 + T37
26  GO TO K2, (28,110)
C
28  IF (IS=1) 30,30,40
C
30  AXS=F1
AYS=F2
AZS=F3
IA=0
GO TO 110
40  IF (IS.EQ.NI)GO TO 75
50  IF (IA) 70,60,70
C
60  AXS=AXS+4.*F1
AYS=AYS+4.*F2
AZS=AZS+4.*F3

```

XYZZ

```

IA=1
GO TO 110 * ODD PASS
C
70 AXS=AXS+F1+F1
   AYS=AYS+F2+F2
   AZS=AZS+F3+F3
   IA=0
GO TO 110
75 GO TO K5, (80,105)
   * LAST PASS
C
80 IF (J-I) 100,90,100
90 IF (BON.NE.0.0) GO TO 100
   AX(J)=AX(J)-S4*(AXS+F1)
   AY(J)=AY(J)-S2*(AYS+F2)
   AZ(J)=AZ(J)+S4*(AZS+F3)
GO TO 110
100 AX(J)=-S4*(AXS+F1)
    AY(J)=-S2*(AYS+F2)
    AZ(J)=S4*(AZS+F3)
GO TO 110
C** **LAST PASS * SMALL ELEMENT
105 IF( (J.NE.I) .OR. (BON.NE. 0.0) )GO TO 107
C** **I = J ON BODY
   AX(J) = AX(J) + XIJ2D + (AXS + F1) * S1
   AY(J) = AY(J) + YIJ2D + (LIJ2D / Y2(I) ) + (AYS + F2) * S1
   AZ(J) = AZ(J) + ZIJ2D + (AZS + F3) * S1
GO TO 110
C** **I NE J ON OR OFF BODY
107 AX(J) = XIJ2D + (AXS + F1) * S1
   AY(J) = YIJ2D + (LIJ2D / Y2(I) ) + (AYS + F2) * S1
   AZ(J) = -2.0 * LIJ2D + (AZS + F3) * S1
110 IF (IAC) 200,200,400
   * CROSS FLOW
C
200 IF (RSMALL)GO TO 223
   IF (I21 .LT. 0.04)GO TO 220

```

```

XYZZ 211
XYZZ 212
XYZZ 213
XYZZ 214
XYZZ 215
XYZZ 216
XYZZ 217
XYZZ 218
XYZZ 219
XYZZ 220
XYZZ 221
XYZZ 222
XYZZ 223
XYZZ 224
XYZZ 225
XYZZ 226
XYZZ 227
XYZZ 228
XYZZ 229
XYZZ 230
XYZZ 231
XYZZ 232
XYZZ 233
XYZZ 234
XYZZ 235
XYZZ 236
XYZZ 237
XYZZ 238
XYZZ 239
XYZZ 240
XYZZ 241
XYZZ 242
XYZZ 243
XYZZ 244
XYZZ 245

```

XYZZ

XYZZ 246
 XYZZ 247
 XYZZ 248
 XYZZ 249
 XYZZ 250
 XYZZ 251
 XYZZ 252
 XYZZ 253
 XYZZ 254
 XYZZ 255
 XYZZ 256
 XYZZ 257
 XYZZ 258
 XYZZ 259
 XYZZ 260
 XYZZ 261
 XYZZ 262
 XYZZ 263
 XYZZ 264
 XYZZ 265
 XYZZ 266
 XYZZ 267
 XYZZ 268
 XYZZ 269
 XYZZ 270
 XYZZ 271
 XYZZ 272
 XYZZ 273
 XYZZ 274
 XYZZ 275
 XYZZ 276
 XYZZ 277
 XYZZ 278
 XYZZ 279
 XYZZ 280

```

T12 = T1 + T8
F1 = T3/Y2(I)*(EKK=EKK*T12/T10)/T7
F2 = (EKK*(T8*T8+T1*(T4-T2))/T10-EKK*T8)/T1/T7
F3 = T7*(EKK*T12/T6-EKK)/T1
GO TO 230

C** **SMALL Y FORMULAS * CROSS FLOW
220 T23 = T1 / T8**2
T29 = ( 1.570796 * T2 ) / ( T8**1.5 )
T26 = 4.0 * T4 = T2
T31 = T26 * T23
F1 = ( (-4.712389) * T2 * T3 * Y2(I) ) / ( T8**2.5 )
F2 = T29 * ( 1.0 * (1.125 * T31) )
F3 = T29 * ( 1.0 * (.375 * T31) )
GO TO 230

C** **IAC LT 0 MEANS NO AXISYMMETRIC FLOW
223 IF(IAC)225,227,227
C** **CALCULATE SMALL ELEMENT QUANTITIES THAT DID NOT GET CALCULATED
C** **BECAUSE THERE WAS NO AXISYMMETRIC FLOW
225 T32 = T3 / T10A
T33 = T9A / T10A
T34 = T33**2
T35A = T10A / (8.0 * Y2(I) )
T35 = ALOG(T35A)
T36 = T9A/Y2(I)
T40 = T10A / Y2(I)
T37 = (T40**2)*0.125
T38 = 0.250*T36*T35
C** **CALCULATE SMALL ELEMENT F1,F2,F3 CROSS FLOW
227 T38A = 5.0 * T38
T40A = T40**2
T36A = T36**2
F1 = (T32 / Y2(I)) * ( (-0.75 * T40 * T35) + T33
1 + (0.125 * T40 * (2.0 * T34 - 5.0) ) )
F2 = ( T38A + T34 + 3.0 + (0.25 * T36 * (T34 - 6.50) ) ) / Y2(I)
F3 = ( ( T36 * (0.375 * T40A) - (0.25 * T36A) ) * T35 - 4.0 + T36

```


XYZZ

```

1      -(0.50 * T36A) - T37 ) / Y2(I)
C      * SIMPSON RULE INTEGRATION
230 IF (IS-1) 240,240,250
C      * FIRST PASS
240 CXS=F1
    CYS=F2
    CZS=F3
    IC=0
    GO TO 400
250 IF (IS-NI) 260,290,260
260 IF (IC) 280,270,280
C      * EVEN PASS
270 CXS=CXS+4.*F1
    CYS=CYS+4.*F2
    CZS=CZS+4.*F3
    IC=1
    GO TO 400
C      * ODD PASS
280 CXS=CXS+F1+F1
    CYS=CYS+F2+F2
    CZS=CZS+F3+F3
    IC=0
    GO TO 400
290 GO TO K6,(295,320)
C      * LAST PASS
295 IF(J.NE.1)GO TO 310
300 IF (RON.NE.0.0) GO TO 310
    CX(J)=CX(J)+S2*(CXS+F1)
    CY(J)=CY(J)+S2*(CYS+F2)
    CZ(J)=CZ(J)+S2*(CZS+F3)
    GO TO 400
310 CX(J)=S2*(CXS+F1)
    CY(J)=S2*(CYS+F2)
    CZ(J)=S2*(CZS+F3)
    GO TO 400

```

```

XYZZ 281
XYZZ 282
XYZZ 283
XYZZ 284
XYZZ 285
XYZZ 286
XYZZ 287
XYZZ 288
XYZZ 289
XYZZ 290
XYZZ 291
XYZZ 292
XYZZ 293
XYZZ 294
XYZZ 295
XYZZ 296
XYZZ 297
XYZZ 298
XYZZ 299
XYZZ 300
XYZZ 301
XYZZ 302
XYZZ 303
XYZZ 304
XYZZ 305
XYZZ 306
XYZZ 307
XYZZ 308
XYZZ 309
XYZZ 310
XYZZ 311
XYZZ 312
XYZZ 313
XYZZ 314
XYZZ 315

```

XYZZ

```

320 IF ( (I,NE,J) .OR. (BON,NE,0,0) ) GO TO 340
C** ***(LAST PASS SMALL ELEMENT I=J ON BODY
CX(J) = CX(J) + XIJ2D + (CXS + F1) * S1
CY(J) = CY(J) + YIJ2D + (LIJ2D / Y2(I)) + (CYS + F2) * S1
CZ(J) = CZ(J) + (2,0 * LIJ2D / Y2(I)) + (CZS + F3) * S1
GO TO 400
C** ***(I NE J OR ANY OFF BODY
340 CX(J) = XIJ2D + (CXS + F1) * S1
CY(J) = YIJ2D + (LIJ2D / Y2(I)) + (CYS + F2) * S1
CZ(J) = (2,0 * LIJ2D / Y2(I)) + (CZS + F3) * S1
C** ***(K3 = 420 FOR SURFACE VORTICITY PF TRUE
400 GO TO K3,(410,420)
C** ***(K1 = 420 FOR STRIP VORTEX
410 GO TO K1,(570,420)
C** ***(FLOW OF CONTROL REACHES HERE FOR (PF=TRUE) OR ( (FLG15 GT 0 AND
C** ***(NLF LE 0 (LIFTING BODY)) AND (I NE J ON BODY OR ANY OFF BODY) )
420 IF (RSMALL)GO TO 542
FV1 = (T2-T1) / T7 * EEK / T10
IF (IS.GT.1) GO TO 440
C
* FIRST PASS
AX1 = FV1
AX2 = FV2
AY1 = FV3
AY2 = FV4
IV=0
GO TO 570
440 IF (IS.EQ.NI) GO TO 500
IF (IV) 460,450,460
C
* EVEN PASS
450 AX1 = AX1+4.*FV1
AX2 = AX2+4.*FV2
AY1 = AY1+4.*FV3
AY2 = AY2+4.*FV4
IV=1
GO TO 570

```

```

XYZZ 316
XYZZ 317
XYZZ 318
XYZZ 319
XYZZ 320
XYZZ 321
XYZZ 322
XYZZ 323
XYZZ 324
XYZZ 325
XYZZ 326
XYZZ 327
XYZZ 328
XYZZ 329
XYZZ 330
XYZZ 331
XYZZ 332
XYZZ 333
XYZZ 334
XYZZ 335
XYZZ 336
XYZZ 337
XYZZ 338
XYZZ 339
XYZZ 340
XYZZ 341
XYZZ 342
XYZZ 343
XYZZ 344
XYZZ 345
XYZZ 346
XYZZ 347
XYZZ 348
XYZZ 349
XYZZ 350

```

```

C      460 AX1 = AX1+FV1+FV1
      AX2 = AX2+FV2+FV2
      AY1 = AY1+FV3+FV3
      AY2 = AY2+FV4+FV4
      IV = 0
      GO TO 570
C      * LAST PASS
      500 IF (J=I) 540,520,540
      520 IF (BON,NE,0.) GO TO 540
      AXV(J) = AXV(J) - S4*(AX1+FV1) - S2*(AX2+FV2)
      AYV(J) = AYV(J) - S4*(AY1+FV3) + S2*(AY2+FV4)
      GO TO 550
      540 AXV(J) = -S4*(AX1+FV1) -S2*(AX2+FV2)
      AYV(J) = -S4*(AY1+FV3) +S2*(AY2+FV4)
      GO TO 550
      542 T34C = T34H = 8.0
      FV1 = ( T38 + (T32**2) - (T39 * T34C) ) / Y2(I)
      FV2 = ( T32 / Y2(I) ) * ( (-0.75 * T40 * T35) +T33
      1      + (0.125 * T40 * T34C) )
      IF (IS.GT.1)GO TO 544
C*** **FIRST PASS SMALL ELEMENT
      AX1 = FV1
      AY1 = FV2
      IV = 0
      GO TO 570
      544 IF (IS.EQ. NI)GO TO 548
      IF (IV.NE. 0 )GO TO 546
C*** **EVEN PASS SMALL ELEMENT
      AX1 = AX1 + 4.0* FV1
      AY1 = AY1 + 4.0* FV2
      IV = 1
      GO TO 570
C*** **ODD PASS SMALL ELEMENT
      546 AX1 = AX1 + FV1 + FV1

```

```

XYZZ 351
XYZZ 352
XYZZ 353
XYZZ 354
XYZZ 355
XYZZ 356
XYZZ 357
XYZZ 358
XYZZ 359
XYZZ 360
XYZZ 361
XYZZ 362
XYZZ 363
XYZZ 364
XYZZ 365
XYZZ 366
XYZZ 367
XYZZ 368
XYZZ 369
XYZZ 370
XYZZ 371
XYZZ 372
XYZZ 373
XYZZ 374
XYZZ 375
XYZZ 376
XYZZ 377
XYZZ 378
XYZZ 379
XYZZ 380
XYZZ 381
XYZZ 382
XYZZ 383
XYZZ 384
XYZZ 385

```

```

AY1 = AY1 + FV2 + FV2
IV = 0
GO TO 570
C*** **LAST PASS    SMALL ELEMENT
548 IF ( (I.NE. J).OR. (BON.NE. 0.0) )GO TO 549
C*** **I = J    ON BODY
AXV(J) = AXV(J) - YIJ2D + (LIJ2D / Y2(I)) + (AX1 + FV1)*S1
AYV(J) = AYV(J) + XIJ2D + (AY1 + FV2)*S1
GO TO 550
C*** **I NE J    OR ANY OFF BODY
549 AXV(J) = -YIJ2D + (LIJ2D / Y2(I)) + (AX1 + FV1)*S1
AYV(J) = XIJ2D + (AY1 + FV2)*S1
C*** **K4 = 560 FOR SURFACE VORTICITY    PF TRUE
550 GO TO K4,(560,570)
C*** **FLOW OF CONTROL REACHES HERE IF PF IS TRUE
560 AX(J) = AXV(J)
AY(J) = AYV(J)
570 IF (IEC.EQ.-1) GO TO 1000
575 IF (T21.LT.0.08)GO TO 595
580 T20 = SQRT( T2 / (T1 + T4) )
IF (T20.LT.0.01) GO TO 590
T13 = YJ * Y2(I)**3
T14 = T1 + TR
T15 = T2 * T1
T16 = T14 * T14
T17 = T1 * YJ
T18 = T1 * T1
T19 = TR * TR
F3 = ( T7/T13 ) * ( (-T14) * EFK + ( ( T16 - T15) * EKK) / T6 ) )
F1 = (T3 / (T17 * T7) ) * ( (EEK / T10) * (T16 - 3.0 * T15) -
1 (T14 * EKK) )
TEMP1 = ((-8.0*T8**3) - (12.0*T1*T19) + (26.0*T15*T8)
1 + (2.0*T18*(2.0*T1 - 5.0*T2) ))*EEK/T10
TEMP2 = EKK * ( (8.0*T19) + (4.0*T1*T8) - (2.0*T15) - (4.0*T18) )
F2 = (TEMP1 + TEMP2) / ( T13 * T7)

```

XYZZ 386
XYZZ 387
XYZZ 388
XYZZ 389
XYZZ 390
XYZZ 391
XYZZ 392
XYZZ 393
XYZZ 394
XYZZ 395
XYZZ 396
XYZZ 397
XYZZ 398
XYZZ 399
XYZZ 400
XYZZ 401
XYZZ 402
XYZZ 403
XYZZ 404
XYZZ 405
XYZZ 406
XYZZ 407
XYZZ 408
XYZZ 409
XYZZ 410
XYZZ 411
XYZZ 412
XYZZ 413
XYZZ 414
XYZZ 415
XYZZ 416
XYZZ 417
XYZZ 418
XYZZ 419
XYZZ 420

```

C***      GO TO 630
590      ***SMALL YJ FORMULAS *      EXTRA CROSS FLOW
      T25 = YJ**3
      T30 = T4 + T1
      T27 = T30**3.5
      T28 = T25 * Y2(I)
      F1 = ( 2.945243 * T25 * T3 * T1 ) / T27
      F2 = 7.068584 * T28 * ( 3.0 * T1 - 2.0 * T4 ) / T27
      F3 = 1.767146 * T28 / (T30**2.5 )
      GO TO 630
C***      ***SMALL Y FORMULAS *      EXTRA CROSS FLOW
595      T25 = YJ**3
      F1 = ( 2.945243 * T25 * T3 * T1 ) / ( T8**3.5 )
      F2 = ( (-14.13717) * T25 * Y2(I) ) / (T8**2.5)
      F3 = -F2 / 8.0
C***      ***SIMPSON'S RULE
630      IF (IS = 1) 640,640,650
C***      ***FIRST PASS
640      ECXS = F1
      ECYS = F2
      ECZS = F3
      IE = 0
      GO TO 1000
650      IF (IS = NI) 660,690,660
660      IF ( IE ) 680,670,680
C***      ***EVEN PASS
670      FCXS = ECXS + 4.0 * F1
      ECYS = ECYS + 4.0 * F2
      FCZS = ECZS + 4.0 * F3
      IE = 1
      GO TO 1000
C***      ***ODD PASS
680      ECXS = ECXS + F1 + F1
      ECYS = ECYS + F2 + F2
      FCZS = ECZS + F3 + F3

```

```

XYZZ 421
XYZZ 422
XYZZ 423
XYZZ 424
XYZZ 425
XYZZ 426
XYZZ 427
XYZZ 428
XYZZ 429
XYZZ 430
XYZZ 431
XYZZ 432
XYZZ 433
XYZZ 434
XYZZ 435
XYZZ 436
XYZZ 437
XYZZ 438
XYZZ 439
XYZZ 440
XYZZ 441
XYZZ 442
XYZZ 443
XYZZ 444
XYZZ 445
XYZZ 446
XYZZ 447
XYZZ 448
XYZZ 449
XYZZ 450
XYZZ 451
XYZZ 452
XYZZ 453
XYZZ 454
XYZZ 455

```

XYZZ

XYZZ

XYZZ

```

IE = 0
GO TO 1000
C*** **LAST PASS
690 IF (J - I) 710,700,710
C*** **T=J * ELEMENTS ON MAIN DIAGONAL
700 IF (BON,NE,0.0) GO TO 710
    FCX(J) = ECX(J) -S4 * ( ECXS + F1 )
    FCY(J) = ECY(J) -S5 * ( ECYS + F2 )
    ECZ(J) = ECZ(J) +S3 * ( ECZS + F3 )
GO TO 1000
C*** **OFF MAIN DIAGONAL OR OFF BODY POINTS
710 ECX(J) = -S4 * ( ECXS + F1 )
    ECY(J) = -S5 * ( ECYS + F2 )
    ECZ(J) = S3 * ( ECZS + F3 )
1000 CONTINUE
    RETURN
    END

```

XYZZ 456
 XYZZ 457
 XYZZ 458
 XYZZ 459
 XYZZ 460
 XYZZ 461
 XYZZ 462
 XYZZ 463
 XYZZ 464
 XYZZ 465
 XYZZ 466
 XYZZ 467
 XYZZ 468
 XYZZ 469
 XYZZ 470
 XYZZ 471
 XYZZ 472

XYZZ

ELIP

```

SUBROUTINE ELIP
C
C
C
      * HASTINGS APPROXIMATION FOR ELLIPTIC INTEGRALS

COMMON HEDR(10), CASE, NB, NNU,
      ,FLG03, ,FLG04, ,FLG05, ,FLG06, ,FLG07
      ,FLG08, ,FLG09, ,FLG10, ,FLG11, ,FLG12
      ,FLG13, ,FLG14, ,FLG15, ,FLG16, ,FLG17
      ,FLG18, ,FLG19, ,FLG20, ,FLG21, ,FLG22
      ,FLG23, ,FLG24, ,FLG25, ,FLG26, ,FLG27

COMMON NT, ND(11), MN, NUNA(5), TYPEA(5),
      NER1, NER2, NMA, NSIGA, NSIGC,
      NUNC(5), TYPEC(5), NLF(11), IFC, NSIGEC,

C DOUBLE PRECISION HEDR, CASE
INTEGER FLG03, FLG04
      ,FLG08, ,FLG09, ,FLG10, ,FLG11, ,FLG12
      ,FLG13, ,FLG14, ,FLG15, ,FLG16, ,FLG17
      ,FLG18, ,FLG19, ,FLG20, ,FLG21, ,FLG22
      ,FLG23, ,FLG24, ,FLG25, ,FLG26, ,FLG27

REAL MN
LOGICAL PF

COMMON /CL/ X1(100), Y1(100), X2(100), Y2(100), DELS(100),
      SINAC(100), COSAC(100), XP(100), YP(100)
COMMON /TL/ XWAKE(11), YWAKE(11)
      , A(100), B(100), AX(100), AY(100), AZ(100),
      CX(100), CY(100), CZ(100), AXV(100), AYV(100),
      VN(100,5), VT(100,5), BUN,
      I, J, J1, SJ, DS,
      DX, DY, NI, XJ, YJ,
      XK, EEK, EKK, K, PF

      * START
      ETA = 1, = XK

```

ELIP

ELIP

```

IF (FTA) 20,20,40
20 WRITE (6,30) ETA
30 FORMAT (1H0 36H *** ERROR IN SUBROUTINE ELIP * ETA= F15.8 )
WRITE (6,800) I,XJ,DX,YJ,DY,X2(I),Y2(I),XK
A00 FORMAT(1H ,15,7F15,6)
FTA = 0.000005
40 ELN=ALNG(ETA)
FKK = 1.386294F0 + FTA * (.9666344E-1 + ETA *
1 (.3590092E-1 + ETA * (.3742564E-1 + ETA *
2 .1451196F-1 ))) + FLN * (.5 + ETA * (.1249859E0 +
3 ETA * (.6880249E-1 + ETA * (.3328355E-1 + ETA *
4 .4417870E-2 )))
FEK = 1. + ETA * (.4432514F0 + ETA * (.6260601E-1 + ETA *
1 (.4757384E-1 + ETA * .1736506F-1 ))) + ELN * (ETA *
2 (.2499837E0 + ETA * (.9200180F-1 + ETA *
3 (.4069698E-1 + ETA * .52644496F-2 )))
RETURN
END

```

ELIP 036
 ELIP 037
 ELIP 038
 ELIP 039
 ELIP 040
 ELIP 041
 ELIP 042
 ELIP 043
 ELIP 044
 ELIP 045
 ELIP 046
 ELIP 047
 ELIP 048
 ELIP 049
 ELIP 050
 ELIP 051
 ELIP 052
 ELIP 053

ELIP


```

SURROUTINE NOTS
COMMON
1  HEDR(10) ,CASE ,NB ,NNU ,FLG07
2  ,FLG03 ,FLG04 ,FLG05 ,FLG06 ,FLG12
3  ,FLG08 ,FLG09 ,FLG10 ,FLG11 ,FLG17
4  ,FLG13 ,FLG14 ,FLG15 ,FLG16 ,FLG22
5  ,FLG18 ,FLG19 ,FLG20 ,FLG21 ,FLG27
   ,FLG23 ,FLG24 ,FLG25 ,FLG26 ,FLG27
C
COMMON NT, ND(11), MN, NUNA(5), TYPEA(5),
1  NER1, NER2, NMA, NSIGA, NSIGC,
2  NUNC(5), TYPEC(5), NLF(11), IEC, NSIGEC,
3  TYPEEC(5), NUNEC(5)
C DOUBLE PRECISION HEDR,CASE
C
COMMON /RNGWG/ VA(100,2), VR(100,2),VAN(100), VAT(100)
C
INTEGER
1  FLG03 ,FLG04 ,FLG05 ,FLG06 ,FLG07
2  ,FLG08 ,FLG09 ,FLG10 ,FLG11 ,FLG12
3  ,FLG13 ,FLG14 ,FLG15 ,FLG16 ,FLG17
4  ,FLG18 ,FLG19 ,FLG20 ,FLG21 ,FLG22
   ,FLG23 ,FLG24 ,FLG25 ,FLG26 ,FLG27
C
COMMON /CL/ X1(100), Y1(100), X2(100), Y2(100), DELS(100),
1  SINA(100), COSA(100), XP(100), YP(100)
2  ,XWAKE(11),YWAKE(11)
C
COMMON /TL/ A(100), B(100), AX(100), AY(100), AZ(100),
1  CX(100), CY(100), CZ(100), AXV(100), AVV(100),
2  VN(100,5), VT(100,5), BUN, IAC,
3  I, J, J1, SJ, DS,
4  DX, DY, NI, XJ, YJ,
5  XK, EKK, EER, K, PF
C
REAL MN,KAY
LOGICAL PF

```

NOTS 001
NOTS 002
NOTS 003
NOTS 004
NOTS 005
NOTS 006
NOTS 007
NOTS 008
NOTS 009
NOTS 010
NOTS 011
NOTS 012
NOTS 013
NOTS 014
NOTS 015
NOTS 016
NOTS 017
NOTS 018
NOTS 019
NOTS 020
NOTS 021
NOTS 022
NOTS 023
NOTS 024
NOTS 025
NOTS 026
NOTS 027
NOTS 028
NOTS 029
NOTS 030
NOTS 031
NOTS 032
NOTS 033
NOTS 034
NOTS 035

```

C*** * FOLLOWING ARE 3 ARITHMETIC FUNCTIONS
C
      OMEG(Z,SMALLR,BIGR) = 1.0 + ( ( Z**2 + (SMALLR-BIGR)**2 ) /
1      (2.0*SMALLR * BIGR) )
      BETAF(Z,SMALLR,BIGR)= ARSIN( Z / ( SQRT(Z**2 + (SMALLR-BIGR)**2)))
C
      AKAYF(Z,SMALLR,BIGR)= SQRT( (4.0 * SMALLR * BIGR) /
1      ( Z**2 + (SMALLR + BIGR)**2 ) )
C
      DO 100 IBOD =1,FLG14
      Z = X2(I) = XWAKE(IBOD)
      OMEGA = OMEG( Z, Y2(I), YWAKE(IBOD) )
      BETA = BETAF( Z, Y2(I), YWAKE(IBOD) )
      KAY = AKAYF( Z, Y2(I), YWAKE(IBOD) )
      CALL QC(OMEGA,QM,Q)
C
      *** SMALLR IS Y2(I)
      *** BIGR IS YWAKE(IBOD)
      IF( Y2(I) ,LE, YWAKE(IBOD) ) GO TO 30
C
      *** SMALLR GT BIGR
C
      BIGK = ( Z / ( SQRT( Y2(I) * YWAKE(IBOD) )**2.0 ) ) * QM =
1      ( 1.570796 * HLAMB(BETA,KAY) )
      GO TO 40
C
C*** * SMALLR LE BIGR
C
      30 BIGK = 3.141593 + ( Z / ( SQRT( Y2(I) * YWAKE(IBOD) )**2.0 ) ) * QM +
1      ( 1.570796 * HLAMB(BETA,KAY) )
C
C*** * NOTE THAT VA AND VR WILL NOT YET BE MULTIPLIED BY DGAMMA/DZ
C*** * WHICH IS REALLY THE INPUT PRESCRIBED VORTICITY

```

C

```

40  VA(I,IRQD) = RIGK / 6.283185
100 VR(I,IRQD) = -(Q * (SQRT(YWAKE(IRQD) / Y2(I) ) ) / 6.283185
      RETURN
      END

```

```

NOTS 071
NOTS 072
NOTS 073
NOTS 074
NOTS 075

```

NOTS

NOTS

HLAB

```

C THIS SUBROUTINE CALCULATES THE HEUMAN'S LAMBDA FUNCTION OF BETA AND K
C DOUBLE PRECISION A,F,E
  REAL K
  DATA TWOP/0.6366197724/
  CALL INEL (FI,EI,PI,BETA,BETA,1.0-K**2 ,0,1,1)
  A = 1.0 - K **2
  CALL ELLC (A ,F,E,1)
  CALL ELLC (A ,F,E,2)
  HLAMB = TWOP*(F*EI + (E-F)*FI)
  RETURN
END

```

HLAB 001
HLAB 002
HLAB 003I
HLAB 004
HLAB 005
HLAB 006
HLAB 007
HLAB 008
HLAB 009
HLAB 010
HLAB 011
HLAB 012

HLAB

```

C THIS SUBROUTINE CALCULATES THE LEGENDRE FUNCTIONS OF THE SECOND KIND
C AND HALF ORDER. THE ARGUMENTS ARE#
C OMEG ARGUMENT FOR WHICH LEGENDRE FUNCTIONS WILL BE FOUND
C QM VALUE OF LEGENDRE FUNCTION OF MINUS ONE HALF ORDER
C Q VALUE OF LEGENDRE FUNCTION OF PLUS ONE HALF ORDER
C DOUBLE PRECISION OMEGD,ARG,A,F,E,QMD,QD
OMEGD=OMEG
ARG=2.0/(OMEGD+1.0)
A=1.0-ARG
CALL ELLC (A,F,E,1)
CALL ELLC (A,F,E,2)
QMD=F*ARG**0.5
QD=-F*(2.0*(OMEGD+1.0))**0.5+OMEGD*QMD
QM=QMD
Q=QD
RETURN
END

```

```

QC 001
QC 002
QC 003
QC 004
QC 005
QC 006
QC 007
QC 008
QC 009
QC 010
QC 011
QC 012
QC 013
QC 014
QC 015
QC 016
QC 017
QC 018

```

QC

```

SUBROUTINE ELLC (A,K,E,I)
C THIS SUBROUTINE CALCULATES THE ASSOCIATED COMPLETE ELLIPTIC INTEGRALS
C OF THE FIRST OR SECOND KIND
C THE ARGUMENTS ARE#
C A ARGUMENT (K SQUARED) FOR WHICH E≠ OR K≠ WILL BE FOUND
C K VALUE OF ASSOCIATED COMPLETE ELLIPTIC INTEGRAL OF FIRST KIND
C E VALUE OF ASSOCIATED COMPLETE ELLIPTIC INTEGRAL OF SECOND KIND
C I IF EQ 1, COMPUTE K ; IF EQ 2, COMPUTE E
C DOUBLE PRECISION K,E,CON(32),A,LN4,CF(29),CL(3),DLOG
C DOUBLE PRECISION CON(32),CF(29),CL(3)
C EQUIVALENCE (CON,CF),(CON(30),CL)
DATA CF /9.6573590797589018D-2,3.0885573486752694D-2,1.4978988178
1704629D-2,9.6587579861753113D-3,1.120891855464092D-2,1.3855601247
215656D-2,6.6905509906897936D-3,6.499844332939018D-4,1.249999999411
37923D-1,7.0312426464627361D-2,4.8818058565403952D-2,3.706839893415
45422D-2,2.718986111678825D-2,1.4105380776158048D-2,3.1831309927862
5886D-3,1.5049181783601883D-4,4.4314718112155806D-1,5.6805657874695
6358D-2,2.1876220647186198D-2,1.251059241084644D-2,1.3034146073731
7432D-2,1.5377102528552019D-2,7.3356164974290365D-3,7.0980964089987
8229D-4,2.4999999993617622D-1,9.3749920249680113D-2,5.8582839536559
9024D-2,4.23828074569479D-2,3.0302747728412848D-2 /
DATA CL / 1.5525129948040721D-2,3.4838679435896492D-3,1.642721079
17048025D-4 /
LN4 = 1.38629436111989D0
IF (A.EQ.0.0) GO TO 4
GO TO (1,2),I
1 K = LN4 + (((((CON(8)*A+CON(7))*A+CON(6))*A+CON(5))*A+CON(4))*A
1+ CON(3))*A+CON(2))*A+CON(1))*A = DLOG(A)*(0.5+((((((CON(16))*A+
2CON(15))*A+CON(14))*A+CON(13))*A+CON(12))*A+CON(11))*A+CON(10))*A
3+ CON(9))*A)
GO TO 3
2 E = 1.00D+((((((CON(24)*A+CON(23))*A+CON(22))*A+CON(21))*A+CON(20
1))*A+CON(19))*A+CON(18))*A+CON(17))*A = DLOG(A)*((((((CON(32))*A
2+ CON(31))*A+CON(30))*A+CON(29))*A+CON(28))*A+CON(27))*A+CON(26))*A
3A+CON(25))*A)

```


1
2
3
4

```

001 SURROUTINE ELINT3(XKSQ,XN,PHI,PIE)
002 THIS SURROUTINE CALCULATES THE INCOMPLETE ELLIPTIC INTEGRAL OF THE
003 THIRD KIND. THE ARGUMENTS ARE#
004 XKSQ VALUE OF K SQUARED
005 XN VALUE OF MINUS ALPHA SQUARED
006 PHI VALUE OF PHI
007 PIE VALUE OF INCOMPLETE ELLIPTIC INTEGRAL OF THIRD KIND
008
009 101 FORMAT (7E16.8)
010 DATA HP /1.570796/
011 DATA ROUND /.0000050/
012 SK=XKSQ
013 FN=XN
014 P=PHI
015 IF (FN.EQ.-1.0.AND.SK.EQ.1.0) GO TO 50
016 IF (SK.GT.1.) GO TO 48
017 IF (FN.LT.(-1.)) GO TO 48
018 IF (P)1,48,2
019 NORMALIZE PHI
020 A=-1.
021 P=-P
022 GOTD3
023 A=1.
024 B=1.
025 BB=1.
026 IF (ABS(P-1.570796) .LE.10.0*(-7)) GO TO 10
027 IF (P-HP)11,10,4
028 J=P/(2.*HP)
029 XX=2*J
030 P1=P-XX*HP
031 P=HP
032 B=-1.
033 GOTD10
034 D=SUM
035 B=0.
036 Y5(P1-HP)4,7,8

```

139

IN


```

6  P=PI
   XXX=1.
   GOT011
7  PIE=(XX+1,)*A*D
   GOT047
8  XXX=1.
   XX=XX+2.
   P=P.*HP=P1
   GOT011
9  PIE=A*(XX*D+XXX*SUM)
   GOT047
10 IF(SK.EQ.1.) GOT048
   IF(FN.EQ.(=1.)) GO TO 48
11 IF(P.GT.10.E-4)GOTO13
   IF(FN.GT.0.)GOTO12
   SUM=P
   GOT045
12 RRT=SQRT(FN)
   SUM=ATAN(P*RRT)/RRT
   GOT045
13 S=SIN(P)
   S2=S**2
   C=COS(P)
   IF(SK.GT.0.64)GOTO20
   IF(ABS(FN).GE.0.6)GOTO15
   POWER SERIES IN N AND K SQUARED
   SA=1.
   SB=SK/2.
   CR=S*C
   CA=P
   FM=0.
   SUM=P
   X=SUM*1.E=8
   SA=SR-SA*FN
14 CA=(-CB/(2.*(FM+1.)))+(1.-.5/(FM+1.))*CA

```

ELNT

```

ELNT 036
ELNT 037
ELNT 038
ELNT 039
ELNT 040
ELNT 041
ELNT 042
ELNT 043
ELNT 044
ELNT 045
ELNT 046
ELNT 047
ELNT 048
ELNT 049
ELNT 050
ELNT 051
ELNT 052
ELNT 053
ELNT 054
ELNT 055
ELNT 056
ELNT 057
ELNT 058
ELNT 059
ELNT 060
ELNT 061
ELNT 062
ELNT 063
ELNT 064
ELNT 065
ELNT 066
ELNT 067
ELNT 068
ELNT 069
ELNT 070

```

ELNT

ELNT

```

Y=SA*CA
SUM=SUM+Y
IF((SB*CA).GT.X) GO TO 141
IF(ABS(Y).LT.X) GO TO 45
FM=FM+1.
CB=CB+S2
SB=(1.-.5/(FM+1.))*SK*SB
GOTO14
POWER SERIES IN K SQUARED
15 PK=SK
RT=SQRT(1.+FN)
IF(RT.NE.0.) GO TO 16
GM8/C
GOTO18
16 IF(C.GT.4.E-3)GOTO17
GM=(HP*(C/(RT*S)))/RT
GOTO18
17 GMATAN(RT*S/C)/RT
18 G1EG*1.E=0
EXP
FAS*C
H=1.
SUM=GM
FM=0.
19 GM=(E-G)/FN
H=H*(1.-.5/(FM+1.))
G2=H*G*PK
SUM=SUM+G2
IF(G2.LE.G1)GOTO45
FM=FM+1.
E=E/(2.*FM)+(1.-.5/FM)*E
F=FS2
PK=PK*SK
GOTO19
20 SKP=1.-SK

```

ELNT 071
 ELNT 072
 ELNT 073
 ELNT 074
 ELNT 075
 ELNT 076
 ELNT 077
 ELNT 078
 ELNT 079
 ELNT 080
 ELNT 081
 ELNT 082
 ELNT 083
 ELNT 084
 ELNT 085
 ELNT 086
 ELNT 087
 ELNT 088
 ELNT 089
 ELNT 090
 ELNT 091
 ELNT 092
 ELNT 093
 ELNT 094
 ELNT 095
 ELNT 096
 ELNT 097
 ELNT 098
 ELNT 099
 ELNT 100
 ELNT 101
 ELNT 102
 ELNT 103
 ELNT 104
 ELNT 105

ELNT

```

C      21      IF(S,LT,C) GO TO 32
            ADDITION FORMULA
            ZP=SQRT(1.-SK*S2)
            RT1=SQRT(ABS(FN*(FN+1.)*(FN+SK)))
            SST=(1.-ZP)/(SK*(C+1.))
            XP=(SST*SR1)/(1.+FN*S2-FN*SST*C*ZP)
            IF(FN)22,29,25
            IF(RT1,NE,0.) GO TO 24
            RS/(C+1.)
            IF(FN,NE,(-1.)) GO TO 23
            CF=(2.*R*SK*SST*S*(S/C)*ZP)/SKP
            GOT030
            CF=(SST*(S*(2./R))+S*C/ZP)*(SK/SKP)
            GOT030
            IF(FN*(FN+SK).LT,0.) GO TO 26
            CF=(FN/RT1)*ATAN(XP)
            GOT030
            IF(ABS(XP).GE,0.1)GOTO27
            YX=XP**2
            YX=2.*XP*(1.+YX*(1./3.+YX*(.2+YX/7.)))
            GOT028
            YX=ALOG((1.+XP)/(1.-XP))
            CF=(FN*YX)/(2.*RT1)
            GOT030
            CF=0.
            BB=-1.
            S=SQRT(SST)
            C=SQRT(1.-SST)
            GOT032
            SUM=2.*SUM+CF
            GOT045
            U=S/C
            V=1./C
            T=U*V
            W=U**2

```

```

ELNT 106
ELNT 107
ELNT 108
ELNT 109
ELNT 110
ELNT 111
ELNT 112
ELNT 113
ELNT 114
ELNT 115
ELNT 116
ELNT 117
ELNT 118
ELNT 119
ELNT 120
ELNT 121
ELNT 122
ELNT 123
ELNT 124
ELNT 125
ELNT 126
ELNT 127
ELNT 128
ELNT 129
ELNT 130
ELNT 131
ELNT 132
ELNT 133
ELNT 134
ELNT 135
ELNT 136
ELNT 137
ELNT 138
ELNT 139
ELNT 140

```

ELNT

ELNT

ELNT

141
 142
 143
 144
 145
 146
 147
 148
 149
 150
 151
 152
 153
 154
 155
 156
 157
 158
 159
 160
 161
 162
 163
 164
 165
 166
 167
 168
 169
 170
 171
 172
 173
 174
 175

```

IF(S.GT.0.1)GOTO33
R=S*(1.+S2*(1./3.+S2*(.2+S2/7.)))
GOTO34
R=ALOG(U+V)
D=1.+FN
IF(D.GT.SKP) GOTO37
POWER SERIES IN 1+N AND 1 - (K SQUARED)
CA=1.
CB=-0.5*SKP
AL=(T+R)/2.
RE=U+V**3
FM=0.
SUM=AL
T1=SUM*1.E=8
CA=D*CA+CB
AL=(BE-(2.*FM+1.)*AL)/(2.*(FM+2.))
X=CA*AL
SUM=SUM+X
IF(ABS(X).LT.T1)GOTO44
FM=FM+1.
CB=((2.*FM+1.)/(2.*(FM+1.)))*CB*SKP
IF(ABS(BE).LT.10.E=30) BE=0.
BE=BE*X
GOTO36
POWER SERIES IN 1 - (K SQUARED)
RT=SQRT(ABS(FN))
IF(FN)38,39,40
R=ALOG((1.+RT*S)/(1.-RT*S))/(2.*RT)
GOTO41
Q=S
GOTO41
Q=ATAN(RT*S)/RT
SUM=FN*Q+R
PKP=SKP
AP=-0.5
  
```

ELNT

ELNY

```

42      FM=1.
         T1=SUM*1.E-8
         Q=(R-Q)/D
         R=T/(2.*FM)-(1.*.5/FM)*R
         X=AP*(FN*Q+R)*PKP
         SUM=SUM+X
         IF(ABS(X).LT.T1)GOTO43
         Y=T*W
         PKP=PKP*SKP
         FM=FM+1.
         AP=AP*(1.*.5/FM)
         GOTO42
43      SUM=SUM/D
44      IF(RB.LT.0.)GOTO31
45      IF(8)5,9,46
46      PIF=AA*SUM
47      PIF=PIE+PIE*ROUND
         RETURN
C      ERROR RETURN
48      PIF=0.
         GOTO47
C      CASE OF PI(1,1,PHI)
50      PIE = 0.5*(TAN(P) / COS(P) +ALOG(TAN(HP+P )/2.0))
         GO TO 47
         END

```

ELNT

```

ELNT 176
ELNT 177
ELNT 178
ELNT 179
ELNT 180
ELNT 181
ELNT 182
ELNT 183
ELNT 184
ELNT 185
ELNT 186
ELNT 187
ELNT 188
ELNT 189
ELNT 190
ELNT 191
ELNT 192
ELNT 193
ELNT 194
ELNT 195
ELNT 196
ELNT 197
ELNT 198
ELNT 199
ELNT 200

```

INEL

```

C      SUBROUTINE INEL (F,E,PI,A,PHI,SKI,K3,K2,K1)
C      THIS SUBROUTINE CALCULATES THE INCOMPLETE ELLIPTIC INTEGRALS OF THE
C      FIRST, SECOND AND THIRD KINDS. THE ARGUMENTS ARE#
C      F      VALUE OF INCOMPLETE ELLIPTIC INTEGRAL OF THE FIRST KIND
C      F      VALUE OF INCOMPLETE ELLIPTIC INTEGRAL OF THE SECOND KIND
C      PI     VALUE OF INCOMPLETE ELLIPTIC INTEGRAL OF THE THIRD KIND
C      A      VALUE OF ALPHA SQUARED
C      PHI    VALUE OF PHI
C      SKI    VALUE OF K SQUARED
C      K3     IF EQ 0, DO NOT COMPUTE PI ; IF NE 0, COMPUTE PI
C      K2     IF EQ 0, DO NOT COMPUTE E ; IF NE 0, COMPUTE E
C      K1     IF EQ 0, DO NOT COMPUTE F ; IF NE 0, COMPUTE F
C      DOUBLE PRECISION ARG,FD,ED
C      DATA PIT/1.57079633/
C      F=0.0
C      F=0.0
C      IF (K3.EQ.0) GO TO 220
C      CALL ELINT3 (SKI,A,PHI,PI)
220  IF (K1.EQ.0) GO TO 240
C      IF (ABS(PHI-PI).GT.10.0*(-7)) GO TO 230
C      ARG=1.0-SKI
C      CALL ELLC (ARG,FD,ED,1)
C      F=FD
C      GO TO 240
230  CALL ELINT3 (SKI,0.0,PHI,F)
240  IF (K2.EQ.0) GO TO 260
C      IF (ABS(PHI-PI).GT.10.0*(-7)) GO TO 250
C      ARG=1.0-SKI
C      CALL ELLC (ARG,FD,ED,2)
C      E=ED
C      GO TO 260
250  CALL ELINT3 (SKI,-SKI,PHI,E)
C      E=(1.0-SKI)*F+0.5*SKI*SIN(2.0*PHI)/SQRT(1.0-SKI*SIN(PHI)**2)
260  RETURN
C      END

```

INEL 001
INEL 002
INEL 003
INEL 004
INEL 005
INEL 006
INEL 007
INEL 008
INEL 009
INEL 010
INEL 011
INEL 012
INEL 013
INEL 014
INEL 015
INEL 016
INEL 017
INEL 018
INEL 019
INEL 020
INEL 021
INEL 022
INEL 023
INEL 024
INEL 025
INEL 026
INEL 027
INEL 028
INEL 029
INEL 030
INEL 031
INEL 032
INEL 033
INEL 034
INEL 035

INEL

PREP

```

OVERLAY(AXSY,3,0)
PROGRAM PREP
SURROUTINE PREP
C **
C * PREPARE TAPES 3 AND 11 FOR USE BY LINK 5 (MATSOL)
COMMON/SPACER/WKAREA(5000)
DIMENSION TEMP(105), Y2(100)
COMMON
  HEDR(10), CASE,
  1 ,FLG03, ,FLG04, ,FLG05, ,NNU, ,FLG06, ,FLG07
  2 ,FLG08, ,FLG09, ,FLG10, ,FLG11, ,FLG12
  3 ,FLG13, ,FLG14, ,FLG15, ,FLG16, ,FLG17
  4 ,FLG18, ,FLG19, ,FLG20, ,FLG21, ,FLG22
  5 ,FLG23, ,FLG24, ,FLG25, ,FLG26, ,FLG27
COMMON
  NT, MN, ND(11), MN, NUNA(5), TYPEA(5),
  1 NER1, NER2, NMA, NSIGA, NSIGC,
  2 NUNC(5), TYPEC(5), NLF(11), IEC, NSIGEC,
  3 TYPEEC(5), NUNEC(5)
C DOUBLE PRECISION HEDR, CASE
INTEGER
  1 FLG03, ,FLG04, ,FLG05, ,FLG06, ,FLG07
  2 FLG08, ,FLG09, ,FLG10, ,FLG11, ,FLG12
  3 FLG13, ,FLG14, ,FLG15, ,FLG16, ,FLG17
  4 FLG18, ,FLG19, ,FLG20, ,FLG21, ,FLG22
  5 FLG23, ,FLG24, ,FLG25, ,FLG26, ,FLG27
REAL
  MN
DIMENSION COSSOR(100), RMS(100)
DIMENSION A(105), R(100,5), FF(100), T(100)
DATA FOURPI/12.5663706/
***AXISYMMETRIC FLOW ONLY
***CROSS FLOW ONLY
***EXTRA CROSS FLOW ONLY
***AXISYMMETRIC AND CROSS FLOW
***AXISYMMETRIC AND EXTRA CROSS FLOW
***CROSS AND EXTRA CROSS FLOW
***AXISYMMETRIC,CROSS, AND EXTRA CROSS FLOW MS = 6
NCK1=0
NCK2=0

```

PREP

```

NCK3=0
NCK4=0
NCK5=0
NCK6=0
IF (FLG12.EQ.0.OR.(FLG04.EQ.0.AND.FLG21.EQ.0)) GO TO 3
IF (FLG05.EQ.0) GO TO 4
C** **SKIP OFF BODY COORDINATES
    READ(12)
    4 NI=NT+NB
    READ(12) (TEMP(I), I = 1, NI), (TEMP(I), I = 1, NI),
    1 (TEMP(I), I = 1, NT), (Y2(I), I = 1, NT)
    3 REWIND 12
    IF (FLG03) 5,600,5
    C** * PREPARE AXISYMMETRIC MATRIX TAPE (3)
    5 IF (FLG19.GT.0) GO TO 2000
    IF (FLG22.GT.0) GO TO 255
    K = 0
    L = NT+NSIGA
    READ (4) (A(I), I=1, NT), (FF(I), I=1, NT)
    IF (FLG16.NE.0) GO TO 20
    K = K+1
    DO 10 I = 1, NT
    10 R(I,K) = A(I)
    20 IF (NNU) 60,60,30
    30 DO 50 J = 1, NNU
    READ (4) MS,(A(I), I=1, NT)
    IF (MS.EQ.1.OR.MS.FQ.2.OR.MS.EQ.5) GO TO 50
    K = K+1
    DO 40 I = 1, NT
    40 R(I,K) = A(I)
    50 CONTINUE
    60 IF (FLG14.LE.0) GO TO 290
    NR= NMA+1
    READ (4) (R(I,1), I=NR,NT)

```

```

PREP 036
PREP 037
PREP 038
PREP 039
PREP 040
PREP 041
PREP 042
PREP 043
PREP 044
PREP 045
PREP 046
PREP 047
PREP 048
PREP 049
PREP 050
PREP 051
PREP 052
PREP 053
PREP 054
PREP 055
PREP 056
PREP 057
PREP 058
PREP 059
PREP 060
PREP 061
PREP 062
PREP 063
PREP 064
PREP 065
PREP 066
PREP 067
PREP 068
PREP 069
PREP 070

```



```

REWIND 4
DO 220 I = NR, NT
  220 R(I,1) = R(I,1)-FF(I)
  IF (FLG14.EQ.NR) GO TO 245
  DO 240 I = 1, NMA
    READ (9) (A(J),J=1,NT)
    A(NT+1) = R(I,1)
  240 WRITE (3) (A(J),J=1,L)
  245 DO 250 I = NR, NT
    READ (9) (A(J),J=1,NT), (A(J),J=1,NT)
    A(NT+1) = R(I,1)
  250 WRITE (3) (A(J),J=1,L)
C   PRESCRIBED TANGENTIAL VELOCITY      INPUT TO SOLVIT ON TAPE 3
C                                         OUTPUT FROM SOLVIT ON TAPE 3
C   TAPES 1 AND 2 ARE SCRATCH TAPES
CALL SOLVIT(WKAREA,NT,NSIGA,5000,3,1,2,3,NCK1)
IF(NCK1.EQ.1) GO TO 9010
251 REWIND 9
GO TO 800
C***   ***AXISYMMETRIC FLOW *   GENERATED (RESEP) BOUNDARY CONDITIONS
C***   ***NPR1 = THE NUMBER OF ELEMENTS ON BODY 1
C***   ***NPR2 = THE NUMBER OF ELEMENTS ON BODY 2
255 NPR1 = ND(1) * 1
NPR2 = ND(2) * 1
NSIGA = 3
NSIGC = 1
NSIGFC = 1
L = NT + NSIGA
C***   ***L IS THE TOTAL WIDTH OF THE MATRIX FOR AXISYMMETRIC FLOW INCL
C***   ***RIGHT HAND SIDES
READ (4)
READ(4) ( COSSQR(I),I = 1,NPR1), (RHS(I),I = 1,NPR1 )
REWIND 4
DO 260 I = 1,NPR1
  R(T,1) = 0.0

```

```

R(I,2) = 1.0
260 R(I,3) = COSSQR(I)
    NREGIN = NPR1 + 1
    NEND = NPR1 + NPR2
    DO 265 I = NREGIN, NEND
        R(I,1) = 1.0
        R(I,2) = 0.0
        R(I,3) = 0.0
265 REWIND 4
290 ASSIGN 400 TO M
    IF (FLG12,NE.0) ASSIGN 300 TO M
    DO 700 I = 1, NT
        GO TO M, (300,400)
300 READ (9) (A(J),J=1,NT),(A(J),J=1,NT),(A(J),J=1,NT)
    GO TO 500
400 READ (9) (A(J),J=1,NT)
500 DO 600 J = 1, NSIGA
    K = NT+J
600 A(K) = R(I,J)
700 WRITE (3) (A(J),J=1,L)
C AXISYMMETRIC FLOW
C INPUT TO SOLVIT ON TAPE 3
C OUTPUT FROM SOLVIT ON TAPE 3
C TAPES 1 AND 2 ARE SCRATCH TAPES
    CALL SOLVIT(WKAREA,NT,NSIGA,5000,3,1,2,3,NCK2)
    IF(NCK2.EQ. 1) GO TO 9020
701 REWIND 9
C **
C **
    * PREPARE CROSSFLOW MATRIX TAPE (11)
    * SKIP SINA * READ COSA
800 IF (FLG04,EQ.0) GO TO 1610
    K = 0
    L = NT+NSIGC
    IF (FLG22,GT.0) GO TO 910
    READ (4) (A(I),I=1,NT),(A(I),I=1,NT)
    IF (FLG17,NE.0) GO TO 820
    K = K+1

```

```

PREP 106
PREP 107
PREP 108
PREP 109
PREP 110
PREP 111
PREP 112
PREP 113
PREP 114
PREP 115
PREP 116
PREP 117
PREP 118
PREP 119
PREP 120
PREP 121
PREP 122
PREP 123
PREP 124
PREP 125
PREP 126
PREP 127
PREP 128
PREP 129
PREP 130
PREP 131
PREP 132
PREP 133
PREP 134
PREP 135
PREP 136
PREP 137
PREP 138
PREP 139
PREP 140

```

```

      DO 810 I = 1, NT
        810 R(I,K) = A(I)
      820 IF (NNU) 900,900,830
      830 DO 850 J = 1, NNU
        READ (4) MS,(A(I),I=1,NT)
      IF ( MS.EQ.0.OR.MS.EQ.2.OR.MS.EQ.4) GO TO 850
      K = K+1
      DO 840 I = 1, NT
        840 R(I,K) = -A(I)
      850 CONTINUE
      900 REWIND 4
      GO TO 1000
C*** **CROSS FLOW * GENERATED (RESEP) BOUNDARY CONDITIONS
      910 DO 920 I = 1,NPB1
      920 R(I,1) = -RHS(I)
      DO 930 I = NBEGIN,NEND
      930 R(I,1) = 0.0
      1000 ASSIGN 1300 TO M
      IF (FLG12.NE.0) ASSIGN 1200 TO M
      DO 1600 I = 1, NT
      GO TO M, (1200,1300)
      1200 READ (10) (A(J),J=1,NT),(A(J),J=1,NT),(A(J),J=1,NT)
C*** **FORM PHI MATRIX FROM THETA (CROSS FLOW) MATRIX
      DO 1250 J = 1,NT
      1250 A(J) = Y2(I) * A(J)
      GO TO 1400
      1300 READ (10) (A(J),J=1,NT)
      1400 DO 1500 J = 1, NSIGC
      K = NT+J
      1500 A(K) =-R(I,J)
      1600 WRITE (11) (A(J),J=1,L)
C CROSS FLOW      INPUT TO SOLVIT ON TAPE 11
C      OUTPUT FROM SOLVIT ON TAPE 3
C TAPES 1 AND 2 ARE SCRATCH TAPES
C      CALL SOLVIT(WKAREA,NT,NSIGC,5000,11,1,2,3,NCK3)

```

```

PREP 141
PREP 142
PREP 143
PREP 144
PREP 145
PREP 146
PREP 147
PREP 148
PREP 149
PREP 150
PREP 151
PREP 152
PREP 153
PREP 154
PREP 155
PREP 156
PREP 157
PREP 158
PREP 159
PREP 160
PREP 161
PREP 162
PREP 163
PREP 164
PREP 165
PREP 166
PREP 167
PREP 168
PREP 169
PREP 170
PREP 171
PREP 172
PREP 173
PREP 174
PREP 175

```

PREP

```

1605 IF(NCK3.EQ.1) GO TO 9030
1610 REWIND 10
1610 CONTINUE
C*** **EXTRA CROSS FLOW
REWIND 11
IF (FLG21.EQ.0.AND.FLG22.EQ.0)RETURN
K = 0
L = NT + NSIGEC
IF (FLG22.GT.0) GO TO 1800
C*** **EXTRA CROSS FLOW * NON-UNIFORM FLOW ONLY
C*** **SKIP RECORD WITH SINES AND COSINES
READ (4)
DO 1650 J=1, NNU
READ(4) MS, (A(I), I=1, NT)
IF (MS.LT.2.OR.MS.EQ.3) GO TO 1650
K = K + 1
DO 1640 I = 1, NT
1640 R(I,K) = A(I)
1650 CONTINUE
GO TO 1900
C*** **EXTRA CROSS FLOW * GENERATED (RESEP) BOUNDARY CONDITIONS
1800 DO 1820 I = 1, NPB1
1820 R(I,1) = COSSQR(I)
DO 1840 I = NBEGIN, NEND
1840 R(I,1) = 0.0
1900 REWIND 4
C*** **M IS 1920 * SOLVE A MATRIX
ASSIGN 1920 TO M
C*** **M IS 1940 * SOLVE POTENTIAL MATRIX
IF (FLG12.NE.0)ASSIGN 1940 TO M
DO 1980 I = 1, NT
GO TO M, (1920, 1940)
C*** **SOLVE A MATRIX
1920 READ (8) (A(J), J = 1, NT)
GO TO 1960

```

```

PREP 176
PREP 177
PREP 178
PREP 179
PREP 180
PREP 181
PREP 182
PREP 183
PREP 184
PREP 185
PREP 186
PREP 187
PREP 188
PREP 189
PREP 190
PREP 191
PREP 192
PREP 193
PREP 194
PREP 195
PREP 196
PREP 197
PREP 198
PREP 199
PREP 200
PREP 201
PREP 202
PREP 203
PREP 204
PREP 205
PREP 206
PREP 207
PREP 208
PREP 209
PREP 210

```

PREP

```

1940 READ (8) (A(J),J=1,NT),(A(J),J=1,NT),(A(J),J=1,NT) MATRIX
C**  **FORM PHI MATRIX FROM THETA (EXTRA CROSS FLOW)
DO 1950 J = 1,NT
1950 A(J) = Y2(I) * A(J) / 2.0
1960 DO 1970 J = 1,NSIGEC
K = NT + J
1970 A(K) = R(I,J)
1980 WRITE (11) (A(J),J=1,L) INPUT TO SOLVIT ON TAPE 11
C**  **EXTRA CROSS FLOW
C**  **OUTPUT FROM SOLVIT ON TAPE 3
C**  **TAPES 1 AND 2 ARE SCRATCH TAPES
CALL SOLVIT (WKAREA,NT,NSIGEC,5000,11,1,2,3,NCK4)
IF(NCK4.EQ. 1) GO TO 9040
1985 REWIND 8
REWIND 11
RETURN
GO TO 9070
2000 IF(FLG23.GT. 0)GO TO 3000
NR = NT - NMA
L = NMA+1
READ (4) (R(I,1),I=1,NMA)
READ (4) (FF(I),I=1,NR)
DO 2100 I = 1, NR
2100 FF(I) = FF(I)/FOURPI
BACKSPACE 4
WRITE (4) (FF(I),I=1,NR)
REWIND 4
DO 2300 I = 1, NMA
READ (9) (A(J),J=1,NMA),(T(J),J=1,NR)
DO 2200 J = 1, NR
2200 R(I,1) = R(I,1) - T(J)*FF(J)
A(L) = R(I,1)
2300 WRITE (3) (A(J),J=1,L) INPUT FOR SOLVIT ON TAPE 3
C PRESCRIBED VORTICITY OUTPUT FROM SOLVIT ON TAPE 3
C

```

PREP

```

C  TAPFS 1 AND 2 ARE SCRATCH TAPES
CALL SOLVIT(WKAREA,NMA,L - NMA,5000,3,1,2,3,NCK5)
IF(NCK5.EQ. 1) GO TO 9000
2500 REWIND 9
GO TO 800
3000 NR = NT - NMA
NMAP1 = NMA + 1
C*** * CALCULATE THE NUMBER OF RMS
C
LL = 0
DO 3100 I=1,NB
IF( NLF(I) .GT. 0 )GO TO 3100
LL = LL + 2
3100 CONTINUE
L = NMAP1 + LL
C
C*** * READ SINS FOR STREAMFLOW RMS
C
READ(4)( R(I,1),I=1,NMA )
C
C*** * READ INPUT PRESCRIBED VORTICITIES
C
READ(4)( FF(I),I=NMAP1,NT )
WRITE(6,8001) (FF(I),I=NMAP1,NT)
8001 FORMAT(1H1,*, THE INPUT PV ARE #/(6E20.7))
DO 3125 I = NMAP1,NT
3125 FF(I) = FF(I) / (-FOURPI)
C
C*** * READ STRIP VORTEX RMS
C
LLD2P1 = LL/2 + 1
DO 3150 J=2,LLD2P1
3150 READ(4)MS,( R(I,J),I=1,NMA )
C
C*** * IPV IS BODY NUMBER OF 1ST PRESCRIBED VORTICITY BODY

```

PREP

```

PREP 246
PREP 247
PREP 248
PREP 249
PREP 250
PREP 251
PREP 252
PREP 253
PREP 254
PREP 255
PREP 256
PREP 257
PREP 258
PREP 259
PREP 260
PREP 261
PREP 262
PREP 263
PREP 264
PREP 265
PREP 266
PREP 267
PREP 268
PREP 269
PREP 270
PREP 271
PREP 272
PREP 273
PREP 274
PREP 275
PREP 276
PREP 277
PREP 278
PREP 279
PREP 280

```

154

PREP

```

C *** ADDED TO FORM A COMPLETE RHS, BUT THEY ARE SUBTRACTED SINCE TH
C *** OF T(J) MUST BE CHANGED
C
3350 R(T,J80D) = R(I,J80D) - T(NCNT) * FF(NCNT)
C
C*** * ATTACH ALL RHS FOR ROW NUMBER I
C
      LRHS = 0
      DO 3375 ICNT=NMAP1,L
      LRHS = LRHS + 1
      3375 A(TCNT) = R(I,LRHS)
C
      3400 WRITE(3)(A(J),J=1,L)
C*** * RING WING OPTION
C*** *
C
      CALL SOLVIT(WKAREA,NMA,L=NMA,5000,3,1,2,3,NCK6)
      IF(NCK6.EQ. 1) GO TO 9050
3500 REWIND 9
      GO TO 800
9000 WRITE(6,9001)
9001 FORMAT(61H NOT ENOUGH SPACE RESERVED IN SOLVIT FOR PRESCRIBED VORT
      ICITY)
      GO TO 9080
9010 WRITE(6,9011)
9011 FORMAT(71H NOT ENOUGH SPACE RESERVED IN SOLVIT FOR PRESCRIBED TANG
      ENTIAL VELOCITY)
      GO TO 9080
9020 WRITE(6,9021)
9021 FORMAT(58H NOT ENOUGH SPACE RESERVED IN SOLVIT FOR AXISYMMETRIC FL
      OW)
      GO TO 9080
9030 WRITE(6,9031)
9031 FORMAT(51H NOT ENOUGH SPACE RESERVED IN SOLVIT FOR CROSS FLOW)
      GO TO 9080

```

```

PREP 316
PREP 317
PREP 318
PREP 319
PREP 320
PREP 321
PREP 322
PREP 323
PREP 324
PREP 325
PREP 326
PREP 327
PREP 328
PREP 329
PREP 330
PREP 331
PREP 332
PREP 333
PREP 334
PREP 335
PREP 336
PREP 337
PREP 338
PREP 339
PREP 340
PREP 341
PREP 342
PREP 343
PREP 344
PREP 345
PREP 346
PREP 347
PREP 348
PREP 349
PREP 350

```

PREP

PREP

```
9040 WRITE (6,9041)
9041 FORMAT (57H NOT ENOUGH SPACE RESERVED IN SOLVIT FOR EXTRA CROSS FL
10W)
GO TO 9080
9050 WRITE(6,9051)
9051 FORMAT(51H NOT ENOUGH SPACF RESERVED IN SOLVIT FOR RING WING )
9070 CONTINUE
9080 STNP
END
```

```
PREP 351
PREP 352
PREP 353
PREP 354
PREP 355
PREP 356
PREP 357C
PREP 358
PREP 359
```

PREP

SUBROUTINE SOLVIT (A, ND, MD, KD, NI, MM, NO, NW, NCK)

```

      ***      ***/      *****      *      ***/
      *      *      *      *      *      *      *      *
      ***      *      *      *      *      *      *      *
      *      *      *      *      *      *      *      *
      *      *      *      *      *      *      *      *
      *      *      *      *      *      *      *      *

```

DIRECT MATRIX SOLUTION

WRITTEN BY J. L. HESS * PROGRAMMED BY T. M. RIDDELL

DIMENSION A (KD)

LOGICAL LAST

CALL TIMEV(AA1)

NCK=0

N=ND

M=MD

KORE=KD

NPM=N+M

IF (MAX0(3*NPM, M*N).GT. KORE) NCK=1

MT=MM

REWIND MT

NIN=NI

REWIND NIN

NOUT=NO

REWIND NOUT

MP1=M+1

NN=N

NEL=NPM

C - - CALCULATE THE MAXIMUM NO. OF ROWS, NK=

SOLV 001
SOLV 002
SOLV 003
SOLV 004
SOLV 005
SOLV 006
SOLV 007
SOLV 008
SOLV 009
SOLV 010
SOLV 011
SOLV 012
SOLV 013
SOLV 014
SOLV 015
SOLV 016
SOLV 017
SOLV 018
SOLV 019
SOLV 020
SOLV 021
SOLV 022
SOLV 023
SOLV 024
SOLV 025
SOLV 026
SOLV 027
SOLV 028
SOLV 029
SOLV 030
SOLV 031
SOLV 032
SOLV 033
SOLV 034
SOLV 035

SOLV

```

C      10 K = (KORE - NEL) / NEL
C
C      - - TEST TO SEE IF THE REST OF THE MATRIX WILL FIT IN CORE
C
C      LAST = K * GE. NN
C      IF (LAST) K = NN
C
C      - - READ #K# ROWS OF THE AUGMENTED #A# MATRIX
C
C      30 NT = 0
C      DO 40 IB = 1, K
C      NS = NT + 1
C      NT = NT + NEL
C      40 READ (NIN) (A(IO), IO = NS, NT)
C
C      - - CHECK TO SEE IF WE WERE UNLUCKY ENOUGH TO END UP WITH ONLY ONE ROW
C
C      IF (K .EQ. 1) GO TO 90
C
C      - - #K# IS GREATER THAN #1# SO WE CAN START THE TRIANGULARIZATION
C
C      NHELP1 = NEL + 1
C      NS = - NEL
C      NHELP2 = NHELP1 + 1
C
C      - - FORM THE #TRAPZOIDAL# ARRAY (8)
C
C      DO 50 IB = 2, K
C      NP = NHELP2 - IB
C      NS = NS + NHELP1
C      NT = NS
C      DO 50 IO = IP, K
C      NT = NT + NEL
C      MN = NT

```

SOLV 036
 SOLV 037
 SOLV 038
 SOLV 039
 SOLV 040
 SOLV 041
 SOLV 042
 SOLV 043
 SOLV 044
 SOLV 045
 SOLV 046
 SOLV 047
 SOLV 048
 SOLV 049
 SOLV 050
 SOLV 051
 SOLV 052
 SOLV 053
 SOLV 054
 SOLV 055
 SOLV 056
 SOLV 057
 SOLV 058
 SOLV 059
 SOLV 060
 SOLV 061
 SOLV 062
 SOLV 063
 SOLV 064
 SOLV 065
 SOLV 066
 SOLV 067
 SOLV 068
 SOLV 069
 SOLV 070

SOLV

SOLV

```

NB = NS
A(NT) = (-A(NT)) / A(NS)
DO 50 NF = 2, NP
  MN = MN + 1
  NB = NB + 1
50 A(MN) = A(MN) + A(NT) * A(NB)
  IF (LAST) GO TO 90

C - - WRITE THE #TRAPEZOIDAL# MATRIX ON TAPE
C
C
NT = 0
NP = NFL
NS = - NEL
DO 60 IO = 1, K
  NS = NS + NEIPI
  NT = NT + NEL
  WRITE (MT) NP, (A(IB), IB = NS, NT)
60 NP = NP + 1
  NP = NP - M
  NS = KORE - NEL + 1

C - - READ ANOTHER ROW
C
C
DO 80 IO = 1, NP
  READ (NIN) (A(IB), IB = NS, KORE)

C - - MODIFY THIS ROW BY THE #TRAPEZOIDAL# ARRAY
C
C
NT = 1
MN = NS
DO 70 IB = 1, K
  NB = NT
  NF = MN + 1
  A(MN) = (-A(MN)) / A(NT)
DO 65 NN = NF, KORE

```

SOLV 071
 SOLV 072
 SOLV 073
 SOLV 074
 SOLV 075
 SOLV 076
 SOLV 077
 SOLV 078
 SOLV 079
 SOLV 080
 SOLV 081
 SOLV 082
 SOLV 083
 SOLV 084
 SOLV 085
 SOLV 086
 SOLV 087
 SOLV 088
 SOLV 089
 SOLV 090
 SOLV 091
 SOLV 092
 SOLV 093
 SOLV 094
 SOLV 095
 SOLV 096
 SOLV 097
 SOLV 098
 SOLV 099
 SOLV 100
 SOLV 101
 SOLV 102
 SOLV 103
 SOLV 104
 SOLV 105

SOLV

SOLV

```

        NB = NB + 1
        65 A(NN) = A(NN) + A(MN) * A(NB)
           MN = NF
        70 NT = NT + NEIP1
C
C -- WRITE THE MODIFIED ROW ON TAPE
C
        80 WRITE (NOUT)      (A(NT), NT = MN, KURE)
           REWIND NOUT
           REWIND NIN
C
C -- SWITCH THE TAPES
C
        NT = NIN
        NIN = NOUT
        NOUT = NT
C
C -- RE-CALCULATE ROW LENGTH AND LOOP BACK
C
        NEL = NEL - K
        NN = NEL - M
        GO TO 10
C
C -- REWIND ALL TAPES
C
        90 REWIND MY
           REWIND NIN
           REWIND NOUT
C
C -- CONDENSE THE MATRIX
C
        NN = NEL
        NL = NFL + 1
        IF (K.EQ. 1) GO TO 105
        NS = 1

```

```

SOLV 106
SOLV 107
SOLV 108
SOLV 109
SOLV 110
SOLV 111
SOLV 112
SOLV 113
SOLV 114
SOLV 115
SOLV 116
SOLV 117
SOLV 118
SOLV 119
SOLV 120
SOLV 121
SOLV 122
SOLV 123
SOLV 124
SOLV 125
SOLV 126
SOLV 127
SOLV 128
SOLV 129
SOLV 130
SOLV 131
SOLV 132
SOLV 133
SOLV 134
SOLV 135
SOLV 136
SOLV 137
SOLV 138
SOLV 139
SOLV 140

```

SOLV

SOLV

```

NT = NFL
DO 100 IR = 2, K
NS = NS + NELP1
NT = NT + NEL
DO 100 IO = NS, NT
A(NL) = A(IO)
100 NL = NL + 1
105 N1 = KORF = K * M + 1
C
C = - THERE, NOW WE CAN START THE BACK-SOLUTION
C * * NOTE., THE FIRST AVAILABLE LOCATION FOR THE SOLUTIONS IS A(N1)
C
NREM = N
NEL = NPM
LAST = K.EQ. N
NPASS = 0
C
C = - SOLVE FOR THE ANSWERS CORRESPONDING TO K* ROWS
C
110 KM1 = K - 1
KPI = K + 1
NS = NL = MP1
NPASS = NPASS + 1
DO 130 MN = 1, M
NF = NS + MN
A(NF) = A(NF) / A(NS)
NT = NS
IF (KM1.EQ. 0) GO TO 130
DO 125 IR = 1, KM1
NF = NF - IB = M
NT = NT - MP1 = IB
SUM = 0.0
NP = NF
N2 = MP1 + IR
DO 120 IO = 1, IR

```

SOLV

```

SOLV 141
SOLV 142
SOLV 143
SOLV 144
SOLV 145
SOLV 146
SOLV 147
SOLV 148
SOLV 149
SOLV 150
SOLV 151
SOLV 152
SOLV 153
SOLV 154
SOLV 155
SOLV 156
SOLV 157
SOLV 158
SOLV 159
SOLV 160
SOLV 161
SOLV 162
SOLV 163
SOLV 164
SOLV 165
SOLV 166
SOLV 167
SOLV 168
SOLV 169
SOLV 170
SOLV 171
SOLV 172
SOLV 173
SOLV 174
SOLV 175

```

SOLV

```

      NN = NT + IO
      NP = NP + N2 - IO
      120 SUM = SUM + A(NN) * A(NP)
      125 A(NF) = (A(NF) * SUM) / A(NT)
      130 CONTINUE
C
C  - MOVE THE SOLUTIONS TO CONTIGUOUS LOCATIONS STARTING AT A(N1)
C
      N1 = KORE + 1
      DO 140 NN = 1, K
      DO 135 MN = 1, M
      NL = NL + 1
      N1 = N1 + 1
      135 A(N1) = A(NL)
      140 NL = NL - NN
C
C  - WRITE THE SOLUTIONS ON TAPE
C
      WRITE (NIN) K
      NS = N1 - 1
      DO 145 MN = 1, M
      NT = NS + MN
      145 WRITE ( NIN , ) ( A(IO), IO = NT, KORE, M)
C
C  - TEST IF THIS IS THE LAST PASS
C
      IF (LAST) GO TO 200
C
C  - WE MUST NOW MODIFY THE TRIANGULAR MATRIX TO REFLECT THE EFFECT OF
      THE SOLUTIONS OBTAINED SO FAR (EQ 21)
C
C  - NOTE. LOCATIONS A(1) TO A(N1-1) ARE NOW FREE TO USE
C
C  - CALCULATE THE NEXT VALUES OF #NEL# AND #NREM#
      NELOLD = NEL

```

SOLV

SOLV

SOLV 211
 SOLV 212
 SOLV 213
 SOLV 214
 SOLV 215
 SOLV 216
 SOLV 217
 SOLV 218
 SOLV 219
 SOLV 220
 SOLV 221
 SOLV 222
 SOLV 223
 SOLV 224
 SOLV 225
 SOLV 226
 SOLV 227
 SOLV 228
 SOLV 229
 SOLV 230
 SOLV 231
 SOLV 232
 SOLV 233
 SOLV 234
 SOLV 235
 SOLV 236
 SOLV 237
 SOLV 238
 SOLV 239
 SOLV 240
 SOLV 241
 SOLV 242
 SOLV 243
 SOLV 244
 SOLV 245

```

KOLD = K
NEL = NEL + K
NRFM = NREM + K
C - - NOW APPLY THE INCREDIBLE FORMULA FOR THE NEW #K#
C
C      K = (-4 * M + 1) / 2 + IFIX(SQRT(0.25 + FLOAT((4 * M + 2) * M +
      1 2 * (KORE - NEOLD))))
      NROW = NREM + K + 1
      IF (K .LT. NREM) GO TO 150
      LAST = .TRUE.
      NROW = 1
      K = NREM
150 NS = 1
      NT = NEOLD + 1
C - - READ IN THE ROWS TO BE MODIFIED
C
C      DO 190 IB = 1, NREM
      NT = NT + 1
      IF (IB .LE. NROW) GO TO 160
      NS = NS + NN
      NT = NT + NN
160 READ ( MT ) NN, (A(IO), IO = NS, NT)
      NP = N1 + 1
      NF = NT - M - KM1
      NN = NN - KOLD
      DO 170 MN = 1, M
      N2 = NF
      NA = NP + MN
      NB = NA
      SUM = 0.0
      DO 165 IO = 1, KOLD
      SUM = SUM + A(N2) * A(NA)
      N2 = N2 + 1

```

SOLV


```

165 NA = NA + M
170 A(N2) = A(N2) + SUM
C
C - - WRITE THE MODIFIED ROW ON TAPE OR CONDENSE THE ROW
C
      NL = NT + M + 1
      IF (IB.GE. NROW) GO TO 175
      NF = NL - KP1
      WRITE (NOUT) NN, (A(IO), IO = NS, NF), (A(IO), IO = NL, NT)
      GO TO 190
175 NF = NL - KOLD
      DO 180 MN = NL, NT
      A(NF) = A(MN)
180 NF = NF + 1
190 CONTINUE
      REWIND MT
      REWIND NOUT
C
C - - SWITCH THE TAPES
C
      NT = MT
      MT = NOUT
      NOUT = NT
C
C - - LOOP BACK THRU THE SOLUTION
C
      NL = NF
      GO TO 110
C
C - - START TO WRAP IT UP
C
200 REWIND NIN
      N2 = N
C

```

SOLV 246
 SOLV 247
 SOLV 248
 SOLV 249
 SOLV 250
 SOLV 251
 SOLV 252
 SOLV 253
 SOLV 254
 SOLV 255
 SOLV 256
 SOLV 257
 SOLV 258
 SOLV 259
 SOLV 260
 SOLV 261
 SOLV 262
 SOLV 263
 SOLV 264
 SOLV 265
 SOLV 266
 SOLV 267
 SOLV 268
 SOLV 269
 SOLV 270
 SOLV 271
 SOLV 272
 SOLV 273
 SOLV 274
 SOLV 275
 SOLV 276
 SOLV 277
 SOLV 278
 SOLV 279
 SOLV 280

SOLV

```

C * * NOTE.. AT THIS POINT ALL LOCATIONS A(1) THRU A(KORE) ARE FREE
C
DO 220 I4 = 1, NPASS
  READ (NIN) K
  N1 = N2 - K + 1
  NS = N1
  NT = N2
C
C - - READ IN THE SOLUTIONS
C
DO 210 IO = 1, M
  READ (NIN) (A(NN), NN = NS, NT)
  NT = NT + N
210 NS = NS + N
220 N2 = N1 + 1
C
C - - - REWIND ALL INPUT TAPES
C
REWIND NIN
REWIND MT
REWIND NOUT
C - - WRITE THE SOLUTIONS ON TAPE
C
NT = 0
DO 230 IO = 1, M
  NS = NT + 1
  NT = NT + N
230 WRITE (NOUT) (A(NN), NN = NS, NT)
C
CALL TIMEV(AA2)
BB = (AA2 - AA1) / 60.
WRITE (6, 300) N, N, M, BB
C 300 FORMAT (4H0THE IS, 2H X IS, 12H MATRIX WITH I4, 35H RIGHT SIDES WA
C
1S SOLVED DIRECTLY IN F8.3, 9H MINUTES. )
RETURN
END

```

SOLV 281
 SOLV 282
 SOLV 283
 SOLV 284
 SOLV 285
 SOLV 286
 SOLV 287
 SOLV 288
 SOLV 289
 SOLV 290
 SOLV 291
 SOLV 292
 SOLV 293
 SOLV 294
 SOLV 295
 SOLV 296
 SOLV 297
 SOLV 298
 SOLV 299
 SOLV 300
 SOLV 301
 SOLV 302
 SOLV 303
 SOLV 304
 SOLV 305
 SOLV 306
 SOLV 307
 SOLV 308
 SOLV 309
 SOLV 310
 SOLV 311
 SOLV 312
 SOLV 313
 SOLV 314
 SOLV 315

SOLV

PAR4

OVERLAY(AXSY,4,0)
PROGRAM PART4
SUBROUTINE PART4

C
C
C
C

* COMPUTE VELOCITY COMPONENTS AND PRINT

COMMON /IPSF/ PSF

COMMON HEDR(10)

1 ,FLG03 ,CASE ,NNU ,FLG07
2 ,FLG08 ,FLG04 ,FLG06 ,FLG12
3 ,FLG13 ,FLG09 ,FLG11 ,FLG16
4 ,FLG18 ,FLG14 ,FLG15 ,FLG21 ,FLG22
5 ,FLG23 ,FLG19 ,FLG20 ,FLG26 ,FLG27

COMMON NT, ND(11), MN, NUNA(5), TYPEA(5),

1 NER1, NER2, NMA, NSIGA, NSIGC,

2 NUNC(5), TYPEC(5), NLF(11), IFC, NSIGEC,

3 TYPEEC(5), NUNEC(5)

C DOUBLE PRECISION HEDR, CASE

COMMON /COMBIN/CHAY(2)

INTEGER

1 ,FLG03 ,FLG04 ,FLG06 ,FLG07
2 ,FLG08 ,FLG09 ,FLG11 ,FLG12
3 ,FLG13 ,FLG14 ,FLG15 ,FLG16
4 ,FLG18 ,FLG19 ,FLG20 ,FLG21
5 ,FLG23 ,FLG24 ,FLG25 ,FLG26 ,FLG27

REAL

C

COMMON /C4/

1 X1(100), Y1(100), X2(100), Y2(100), DELS(100),
SINA(100), CUSA(100), XP(100), YP(100)
COMMON /TC/
1 RB(100,10), SIG(100,5), A(100), B(100),
2 Z(100), PHI(100,5), XN(100,5), T(100,5),
3 T3(100,5), NSIG, NP,
SUMV, SUMM(5)

* START

DO 20 J = 1,10

C
C

PAR4 001C
PAR4 002C
PAR4 003I
PAR4 004
PAR4 005
PAR4 006
PAR4 007
PAR4 008
PAR4 009
PAR4 010
PAR4 011
PAR4 012
PAR4 013
PAR4 014
PAR4 015
PAR4 016
PAR4 017
PAR4 018I
PAR4 019
PAR4 020
PAR4 021
PAR4 022
PAR4 023
PAR4 024
PAR4 025
PAR4 026
PAR4 027
PAR4 028
PAR4 029
PAR4 030
PAR4 031
PAR4 032
PAR4 033
PAR4 034
PAR4 035

PAR4

PAR4

```

      DO 20 I = 1,500
      RB(I,J) = 0.0
      REWIND 3
      IF (FLG05.FQ.0) GO TO 30
      * RFAD OFF-RODY XP,YP
      NP=ND(NR+1)
      READ (12) (XP(I),I=1,NP),(YP(I),I=1,NP)
      * READ X1,Y1,X2,Y2,DELS WITH WACH NO. ADJUSTMENT IF ANY
      30 NI=NT+NB
      READ (12) (X1(I),I=1,NI),(Y1(I),I=1,NI),(X2(I),I=1,NT)
      1 (Y2(I),I=1,NT),(DELS(I),I=1,NT)
      * RFAD SINA,COSA,NO,TO,,
      READ (4) (A(I),I=1,NT),(B(I),I=1,NT)
      NMAP1 = NMA + 1
      IF(FLG23.GT. 0)READ(4)(Z(I),I=NMAP1,NT)
      SUMV = 0.0
      DO 100 I = 1, NT
      SINA(I) = A(I)
      COSA(I) = B(I)
      100 SUMV = SUMV + B(I)*DELS(I)*Y2(I)**2
      SUMV = SUMV*3.141593
      IF (FLG03.LE.0) GO TO 1000
      L = 1
      LS = 0
      IF (FLG16.NE.0) GO TO 200
      DO 150 I = 1, NT
      RB(I,L) = A(I)
      150 RB(I,L+1) = B(I)
      200 IF (NNU) 600,600,300
      300 DO 500 J = 1, NNU
      READ (4) MS,(A(I),I=1,NT),(B(I),I=1,NT)
      IF (MS.EQ.1.OR.MS.EQ.2.OR.MS.EQ.5) GO TO 500
      L = I+2
      LS = LS+1
      IF (LS.EQ.1.AND.FLG16.GT.0) L=L-2

```

PAR4

```

      DO 400 I = 1, NT
      RB(I,L) = A(I)
      400 RB(I,L+1) = R(I)
      500 CONTINUE
      IF (FLG23.LE.0) GO TO 600
      IPV = NB - FLG14 + 1
      NN = NMA
      DO 550 KCNT = IPV,NB
      L = L + 2
      NN = NN + ND(KCNT) - 1
      C ** READ NOTS COLUMNS OF RHS
      READ(4)(RB(I,L),I=1,NT),(RB(I,L+1),I=1,NT)
      C ** MULTIPLY NOTS COLUMN BY LAST INPUT PV ON THAT BODY
      DO 550 I=1,NT
      RB(I,L) = RB(I,L) * Z(NN)
      550 RB(I,L+1) = RB(I,L+1) * Z(NN)
      600 REWIND 4
      NSIG = NSIGA
      IF (FLG23.GT.0) NSIG = 2.0 * NSIG - 1
      C CALL AXIS
      CALL OVERLAY (4HAXSY,4,1,6HRECALL )
      1000 IF (FLG04.LE.0) GO TO 2000
      IF (FLG03.LE.0) GO TO 1050
      READ (4) (A(I),I=1,NT),(R(I),I=1,NT)
      1050 L = 1
      LS=0
      IF (FLG17.NE.0) GO TO 1200
      DO 1100 I = 1, NT
      RB(I,L) = A(I)
      1100 RB(I,L+1) = R(I)
      1200 IF (NNU) 1600,1600,1300
      1300 DO 1500 J = 1, NNU
      READ (4) MS,(A(I),I=1,NT),(B(I),I=1,NT)
      IF ( MS.EQ.0.OR.MS.EQ.2.OR.MS.FQ.4) GO TO 1500
      L = I + 2

```

```

PAR4 071
PAR4 072
PAR4 073
PAR4 074
PAR4 075
PAR4 076
PAR4 077
PAR4 078
PAR4 079
PAR4 080
PAR4 081
PAR4 082
PAR4 083
PAR4 084
PAR4 085
PAR4 086
PAR4 087
PAR4 088
PAR4 089
PAR4 090
PAR4 091
PAR4 092
PAR4 093
PAR4 094
PAR4 095
PAR4 096
PAR4 097
PAR4 098
PAR4 099
PAR4 100
PAR4 101
PAR4 102
PAR4 103
PAR4 104
PAR4 105

```

PAR4

```

LS=LS+1
IF (LS.EQ.1.AND.FLG17.GT.0) L=L+2
DO 1400 I = 1, NT
  RB(I,L) = A(I)
  1400 RB(I,L+1) = B(I)
  1500 CONTINUE
  1600 REWIND 4
  NSIG = NSIGC
  C CALL CROSS
  CALL OVERLAY (4HAXSY,4,2,6HRECALL )
  C2000 IF (FLG21.LE.0) RETURN
  2000 IF (FLG21.LE.0) GO TO 2500
  2050 REWIND 4
  IF(FLG22.GT.0) GO TO 2400
  L = 0
  C** ***IF CONTROL REACHES THIS POINT, THERE IS AT LEAST 1 NNU
  C** ***SKIP RECORD WITH SIN AND COS
  READ (4)
  DO 2200 J = 1, NNU
    READ(4) MS, ( A(I),I=1,NT ), ( B(I),I=1,NT )
    L = L + 1
    DO 2200 I = 1, NT
      RB(I,L) = A(I)
      2200 RB(I,L+1) = B(I)
      2400 REWIND 4
    NSIG = NSIGEC
    C** ***CALL TO EXCROS FOR GENERATFD (RESEP) BOUNDARY CONDITIONS
    C CALL EXCROS
    CALL OVERLAY (4HAXSY,4,3,6HRECALL )
    RETURN
    C 2500 CONTINUE
    END

```

PAR4


```

C
1  DIMENSION      VX(100,5),      VY(100,5);      VT(100,5),
      TH(100,5),      CP(100,5);      SUMTDS(5)

C
      DATA FOURPI /12.5663706/
      EQUIVALENCE ( VX(1,1) , XN(1,1) ) , ( VY(1,1), Y(1,1) ) ,
1  ( VT(1,1), T3(1,1) ) , ( TH(1,1), SIG(1,1) ) , ( CP(1,1), T3(1,1) )

C
C      * START
      NC=NT
      IF (FLG19.GT.0) NC=NMA
      IF (FLG08.EQ.0) GO TO 10
      * TITLE FOR MATRIX PRINT
      WRITE(6,150)HEDR,CASE,PSF
      WRITE (6,8)
      * READ AXIS SIGMAS
      * FORMAT (1H 43H MATRICES A,R,Z BY ROWS * AXISYMMETRIC FLOW //)
10  DO 20 N=1,NSTG
      SUMM(N)=0.0
      SUMTDS(N)=0.0
      20  READ (3) (SIG(I,N),I=1,NC)
      IF (FLG19.LE.0) GO TO 25
      READ (4)
      NR = NMA+1
      IF(FLG23.GT. 0)GO TO 21
      READ (4) (SIG(I,1),I=NR,NT)
      REWIND 4
      GO TO 25

C
C      * RING WING
C
21  LIFBND = 0
      DO 22 K = 1,NB
      IF( NLF(K).GT. 0)GO TO 22
      LIFBND = LIFBND + 1

```

AXIS 036
 AXIS 037
 AXIS 038
 AXIS 039
 AXIS 040
 AXIS 041
 AXIS 042
 AXIS 043
 AXIS 044
 AXIS 045
 AXIS 046
 AXIS 047
 AXIS 048
 AXIS 049
 AXIS 050
 AXIS 051
 AXIS 052
 AXIS 053
 AXIS 054
 AXIS 055
 AXIS 056
 AXIS 057
 AXIS 058
 AXIS 059
 AXIS 060
 AXIS 061
 AXIS 062
 AXIS 063
 AXIS 064
 AXIS 065
 AXIS 066
 AXIS 067
 AXIS 068
 AXIS 069
 AXIS 070

AXIS

```

22 CONTINUE
   LBP1 = LIFBOD + 1
   DO 23 N=1,LBP1
   DO 23 I=NR,NT
23 SIG(I,N) = 0.0
   LBP2 = LBP1 + 1
   DO 24 N = LBP2,NSIG
24 READ(4) (SIG(I,N),I=NR,NT)
   ** SIGMAS HERE HAVE BECOME THE INPUT PV
   DO 26 N = LBP2,NSIG
   DO 26 I=NR,NT
26 SIG(I,N) = SIG(I,N) / (-FOURPI)
   REWIND 4
   * NO. OF MIDPOINTS LOOP
25 DO 100 I=1,NT
   * READ MATRICES A,B,Z
   READ (9) (A(J),J=1,NT),(R(J),J=1,NT),(7(J),J=1,NT)
   * NO. OF FLOWS LOOP
   NI=0
   DO 70 N=1,NSIG
   NI=NI+2
   SN=0.0
   ST=0.0
   SP=0.0
   * NO. OF ELEMENTS LOOP
   DO 30 J=1,NT
   SN=SN+A(J)*SIG(J,N)
   ST=ST+R(J)*SIG(J,N)
   IF (FLG23.GT. 0) Z(J) = 0.0
30 SP=SP+Z(J)*SIG(J,N)
   IF (FLG22.GT.0) GO TO 6A
   IF (FLG12.FQ.0) GO TO 40
   XN(I,N)=SN
   PHT(I,N)=SP-RB(I,NI-1)
   GO TO 50

```

```

AXIS 071
AXIS 072
AXIS 073
AXIS 074
AXIS 075
AXIS 076
AXIS 077
AXIS 078
AXIS 079
AXIS 080
AXIS 081
AXIS 082
AXIS 083
AXIS 084
AXIS 085
AXIS 086
AXIS 087
AXIS 088
AXIS 089
AXIS 090
AXIS 091
AXIS 092
AXIS 093
AXIS 094
AXIS 095
AXIS 096
AXIS 097
AXIS 098
AXIS 099
AXIS 100
AXIS 101
AXIS 102
AXIS 103
AXIS 104
AXIS 105

```

AXIS

AXIS

AXIS 106
AXIS 107
AXIS 108
AXIS 109
AXIS 110
AXIS 111
AXIS 112
AXIS 113
AXIS 114
AXIS 115
AXIS 116
AXIS 117
AXIS 118
AXIS 119
AXIS 120
AXIS 121
AXIS 122
AXIS 123
AXIS 124
AXIS 125
AXIS 126
AXIS 127
AXIS 128
AXIS 129
AXIS 130
AXIS 131
AXIS 132
AXIS 133
AXIS 134
AXIS 135
AXIS 136
AXIS 137
AXIS 138
AXIS 139
AXIS 140

```

40 XN(I,N)=SN-RR(I,N1-1)
   PHI(I,N)=SP
50 IF (FLG11.EQ.0) GO TO 60
   T(I,N)=ST
   GO TO 65
60 T(I,N)=ST+RB(I,N1)
65 SUMM(N)=SUMM(N)+PHI(I,N)*Y2(I)*RB(I,N1-1)*DELS(I)
   CP(I,N)=1.-T(I,N)**2
   GO TO 70
68 XN(I,N) = SN
   PHI(J,N) = SP
   T(I,N) = ST
   CP(I,N) = 1.0 - T(I,N)**2
70 CONTINUE
   IF (FLG08.EQ.0) GO TO 100
   WRITE (6,80) I,(A(J),J=1,NT)
80 FORMAT (1H0 13H MATRIX A ROW I6/ (1H 10F10.5))
   WRITE (6,85) I,(B(J),J=1,NT)
85 FORMAT (1H0 13H MATRIX B ROW I6/ (1H 10F10.5))
   WRITE (6,90) I,(Z(J),J=1,NT)
90 FORMAT (1H0 13H MATRIX Z ROW I6/ (1H 10F10.5))
100 CONTINUE
   IF (MN.EQ.0.0) GO TO 130
   * MACH NO. ADJUSTMENT
   D1=MN*MN
   D2=1.-D1
   D3=SQRT(D2)
   D4=.7*D1
   D5=.2*D1
   DO 120 N=1,NSIG
   DO 120 I=1,NT
   TX=(T(I,N)*COS(A(I)-1.)/D2+1.
   TY = ( T(I,N) * SINA(I) ) / D3
   T(I,N)=SQRT(TX*TX+TY*TY)
120 CP(I,N)=((1.+D5*(1.-T(I,N)**2))**3.5-1.)/D4

```

C

AXIS

```

C      * ELIMINATE MACH NO EFFECT FOR PRINTOUT
      DO 122 I=1,NY
122    X1(I)=X1(I)*D3
      N=0
      J1=0
      DO 126 K=1,NR
      M=N+1
      N=ND(K)-1
      DO 124 J=M,N
      J1=J1+1
      T1=X1(J1+1)-X1(J1)
      T2=Y1(J1+1)-Y1(J1)
      X2(J)=(X1(J1+1)+X1(J1))/2.
      DELS(J)=SQRT(T1*T1+T2*T2)
      COSA(J)=T1/DELS(J)
      SINA(J)=T2/DELS(J)
124    J1=J1+1
C      * PRINT AXIS FLOW (ON-BODY) OUTPUT
130    DO 250 L=1,NSIG
      KA = L
      IF (FLG16.LE.0) KA=L+1
      IF (FLG22.GT.0) OR, FLG23.GT.0 )KA = L
      IF (FLG22.GT.0)GO TO 136
      SUMM(L)=-6.2831853*SUMM(L)
      DO 135 J = 1, NY
135    SUMTDS(L) = SUMTDS(L) + T(J,L)*DELS(J)
136    I = 1
      J=1
      REWIND 1
      REWIND 3
      M=1
      N=ND(M)
      NSM=N-1
      XB(1)=X1(1)
      UB(1)=.9999999

```

AXIS 141
 AXIS 142
 AXIS 143
 AXIS 144
 AXIS 145
 AXIS 146
 AXIS 147
 AXIS 148
 AXIS 149
 AXIS 150
 AXIS 151
 AXIS 152
 AXIS 153
 AXIS 154
 AXIS 155
 AXIS 156
 AXIS 157
 AXIS 158
 AXIS 159
 AXIS 160
 AXIS 161
 AXIS 162
 AXIS 163
 AXIS 164
 AXIS 165
 AXIS 166
 AXIS 167
 AXIS 168
 AXIS 169
 AXIS 170
 AXIS 171
 AXIS 172
 AXIS 173
 AXIS 174
 AXIS 175

AXIS

```

176 YB(1)=Y1(1)
177 DO 138 KK=1,NSM
178 XA(KK+1)=X2(KK)
179 YB(KK+1)=Y2(KK)
180 YB(KK+1)=CP(KK,L)
181 WRITE(3) N
182 WRITE(3) (XB(K),K=1,N)
183 WRITE(3) (YB(K),K=1,N)
184 WRITE(3) (UB(K),K=1,N)
185 IF(ITER,GE,1) GO TO 139
186 WRITE(15) N
187 WRITE(15) (X1(K),K=1,N)
188 WRITE(15) (Y1(K),K=1,N)
189
190 139 CONTINUE
191 LCTR=22
192
193 140 WRITE(6,150)MEDR,CASE,PSF
194 150 FORMAT (1H1 25X, 26HDOUGLAS AIRCRAFT COMPANY /
195 1 28X, 21HLONG BEACH DIVISION ///
196 2 6X,10A6,4X,10HCASE NO. A6,10H PSF = ,A4 //)
197 IF (FLG22.GT.0) GO TO 178
198 IF (L.GT.1.OR,FLG16.NE.0) GO TO 170
199 WRITE (6,160)
200 160 FORMAT (1H 34H ON-BODY UNIFORM AXISYMMETRIC FLOW )
201 GO TO 190
202 IF (TYPEA(KA).GE.0.0) GO TO 175
203 WRITE (6,172)
204 172 FORMAT (1H 44H FLOW GENERATOR * ROTATING BODY * TYPE ERROR )
205 IF (NUNA(KA).EQ.123456) WRITE (6,177)
206 177 FORMAT (27H ON-BODY STRIP VORTEX FLOW,
207 178 IF (NUNA(KA).NE.123456) WRITE(6,180)NUNA(KA)
208 180 FORMAT (1H 42H ON-BODY NON-UNIFORM AXISYMMETRIC FLOW NO. 18)
209 190 WRITE (6,200)
210 200 FORMAT (1H 5X 24H TRANSFORMED COORDINATES //
211 1 12X 1HX 13X 1HY 13X 2HT1 12X 2HCP 9X 5HSIN A
212 2 6X 5HCOS A 7X 5HSIGMA 11X 1HN 13X 3HPHI //)

```

AXIS

AXIS

```

210 WRITE (6,220) I,X1(I),Y1(I),X2(J),Y2(J),
1      SYNA(J),COXA(J),SIG(J,L),XN(J,L),PHI(J,L),
220 FORMAT (1H I3,2F14.7/ 4X 4F14.7,2F11.5,3F14.7)
I=I+1
J=J+1
IF (I.EQ.N) GO TO 230
IF (Y.LF.LCTR) GO TO 210
LCTR=LCTR+22
GO TO 140
230 MEM+1
NEN+ND(M)
WRITE (6,240) I,X1(I),Y1(I)
240 FORMAT (1H I3, 2F14.7 //)
I=I+1
IF ( J - NT ) 210, 242, 242
242 IF(FLG22.GT.0) GO TO 250
WRITE(6,244) SUMM(L), SUMV, SUMIDS(L)
244 FORMAT (1H0 10X 13H ADDED MASS =F12.7, 4X 9H VOLUME = F12.7,
A      5X 18H SUM (I)(DELTA S) = F12.7 )
250 CONTINUE
252 LL = 1
IF(FLG23.GT. 0)CALL COMRU(LL)
C      IF(FLG05.EQ. 0)RETURN
IF(FLG05.EQ. 0) GO TO 700
* OFF=BODY POINT
253 IF (FLG15.LE.0) GO TO 25A
M = 0
DO 254 I = 1, NR
254 IF (NLF(I).LE. 0) M = M + 1
IF ( M.EQ. 0 ) GO TO 25A
MM = NNU + 1
IF(FLG23.GT. 0)MM = MM + NNU
DO 255 I = 1, MM
255 READ (4)
IF (FLG22.GT.0)WFAD(4)

```

AXIS

AXIS

```

DO 256 J = 1, M
256 READ(4) (RB(I,J), I = 1, NP), (T3(I,J), I = 1, NP)
      REWIND 4
258 DO 300 I = 1, NP
      L=0
      * READ MATRICES X,Y,Z
      READ (9) (A(J),J=1,NT),(B(J),J=1,NT),(7(J),J=1,NT)
      * NO. OF FLOW
      DO 300 N=1,NSIG
      KA=N
      IF (FLG16.LE.0) KA=N-1
      SX=0.0
      SY=0.0
      SP=0.0
      * NO. OF FLEMENTS LOOP
      DO 260 J=1,NT
      SX=SX+A(J)*SIG(J,N)
      SY=SY+B(J)*SIG(J,N)
      IF(FLG23.GT. 0)Z(J) = 0.0
      SP=SP+Z(J)*SIG(J,N)
      PHI(I,N)=SP
      IF (FLG22.GT.0) GO TO 270
      IF (FLG11.GT.0) GO TO 270
      IF (N.NE.1.OR,FLG16.GT.0) GO TO 262
      VX(I,N) = SX+1.
      GO TO 280
262 IF (NUNA(KA).NE.123456) GO TO 270
      L=L+1
      VX(I,N)=SX+RB(I,L)
      VY(I,N)=SY+T3(I,L)
      GO TO 300
270 VX(I,N) = SX
280 VY(I,N) = SY
300 CONTINUE
      IF (MN.EQ.0.0) GO TO 330

```

AXIS

```

C          * MACH NO. ADJUSTMENT
      DO 320 N=1,NSIG
      DO 320 I=1,NP
        VY(I,N)=VY(I,N)/D3
      320 VX(I,N)=(VX(I,N)-1.)/D2+1.
      DO 322 I = 1, NP
      322 XP(I)=XP(I)*D3
C          * COMPUTE VT AND THETA
      330 DO 335 N=1,NSIG
      DO 335 I=1,NP
        VT(I,N)=SQRT(VX(I,N)**2+VY(I,N)**2)
      335 TH(I,N)=ATAN2(VY(I,N),VX(I,N)) * 57.29578
C          * PRINT AXIS FLOW (OFF-BODY) OUTPUT
      DO 450 L=1,NSIG
      KA = L
      IF (FLG16 .LE. 0) KA = L - 1
      IF (FLG22 .GT. 0 .OR. FLG23 .GT. 0) KA = L
      I=1
      LCTR=45
      340 WRITE(6,150)HEDR,CASE,PSF
      IF (L.GT.1.OR.FLG16.NE.0) GO TO 370
      IF (FLG22.GT.0) GO TO 378
      WRITE (6,360)
      360 FORMAT (1H 35H OFF-BODY UNIFORM AXISYMMETRIC FLOW )
      GO TO 390
      370 IF (TYPEA(KA),GE.0.) GO TO 375
      WRITE (6,172)
      375 IF (NUNA(KA).EQ.123456) WRITE (6,377)
      377 FORMAT (28H OFF-BODY STRIP VORTEX FLOW)
      378 IF (NUNA(KA).NE.123456) WRITE (6,380) NUNA(KA)
      380 FORMAT (1H 43H OFF-BODY NON-UNIFORM AXISYMMETRIC FLOW NO. 18)
      390 WRITE (6,400)
      400 FORMAT (1H 5X, 24H TRANSFORMED COORDINATES //
      1      12X 1HX 13X 1HY 13X
      2      5H THETA 11X 3H PHI //)

```

AXIS

AXIS 316
 AXIS 317
 AXIS 318
 AXIS 319
 AXIS 320
 AXIS 321
 AXIS 322
 AXIS 323
 AXIS 324
 AXIS 325
 AXIS 326
 AXIS 327I
 AXIS 328C
 AXIS 329

VX(I,L),VV(I,L),VY(I,L),

```

410 WRITE (6,420) I,XP(I),YP(I),
      1 TH(I,L), PHI(I,L)
420 FORMAT (1H I3, 7F14.7)
      I=I+1
      IF (I.GT.NP) GO TO 450
      IF (I.LE.LCTR) GO TO 410
      LCTR=LCTR+45
      GO TO 340
450 CONTINUE
500 LL = 0
      IF (FLG23 .GT. 0) CALL COMBU(LL)
      RETURN
C 700 CONTINUE
      END
  
```

AXIS

COMB

```

C
SUBROUTINE COMBO(LL)
COMMON / IPSF / PSF
COMMON / COMBIN/CHAY(2)
COMMON
1   ,FLG03
2   ,FLG08
3   ,FLG13
4   ,FLG18
5   ,FLG23
COMMON NT, ND(11), MN, NUNA(5), TYPEA(5),
1   NER1, NER2, NMA, NSIGA, NSIGC,
2   NUNC(5), TYPEC(5), NLF(11), IEC, NSIGEC,
3   TYPEEC(5), NUNFC(5)
C
DOUBLE PRECISION HEDR, CASE
INTEGER
1   ,FLG03
2   ,FLG08
3   ,FLG13
4   ,FLG18
5   ,FLG23
COMMON /C4/ X1(100), Y1(100), X2(100), Y2(100), DELS(100),
1   SINA(100), COSA(100), XP(100), YP(100)
COMMON /IC/ RB(100,10), SIG(100,5), A(100), B(100),
1   Z(100), PHI(100,5), XN(100,5), T(100,5),
2   T3(100,5), NSIG, NP, NI,
3   SUMV, SUMM(5)
DIMENSION C(2,2), DV(2),
1   TFIRST(2,5), TLAST(2,5), TSUM(2,5)
COMMON CP(100)
EQUIVALENCE ( CP(1),A(1) )
EQUIVALENCE ( DV(1),CHAY(1) )
DIMENSION VX(100,5), VY(100,5), VT(100,5)
EQUIVALENCE (VX(1,1),XN(1,1)), (VY(1,1),T(1,1)),
1   (VT(1,1),T3(1,1))

```

COMB

COMB

```

C ** ICNT WILL BE THE NUMBER OF LIFTING BODIES
C * NFLOW WILL BE THE NUMBER OF FLOWS
C
C
C      ICNT = 0
C      DO 10 K=1,NB
C      IF( NLF(K) .LE. 0)ICNT=ICNT+1
C      NFLOW = 1 + P*ICNT
C      IF(LL.EQ. 0)GO TO 1000
C      READ(5,4)( DV(I),I=1,ICNT )
C      4 FORMAT (6F10.0)
C      WRITE(6,6) (DV(I),I=1,ICNT)
C      6 FORMAT(1H1,42H THE INPUT DV FOR COMBINATION SOLUTION ARE /
C      1 (2X,6F10.4) )
C
C ** IPTCNT WILL BE THE LAST MIDPOINT ON BODY K
C
C      IPTCNT = 0
C      ILIFT WILL BE THE LIFTING BODY NUMBER
C      ILIFT = 0
C      DO 100 K=1,NA
C      IPTCNT = IPTCNT + ND(K) - 1
C      IFIRST = IPTCNT - ND(K) + 2
C      IF ( NLF(K) .GT. 0 )GO TO 100
C      ILIFT = ILIFT + 1
C
C      DO 50 J=1,NFLOW
C      TFIRST(ILIFT,J) = T(IFIRST,J)
C      TLAST(ILIFT,J) = T(IPTCNT,J)
C      50 TSUM(ILIFT,J) = TFIRST(ILIFT,J) + TLAST(ILIFT,J)
C      100 CONTINUE
C
C ** IPVBD WILL BE 1ST PRESCRIBED VORTICITY FLOW
C * LASTSV WILL BE LAST STRIP VORTEX FLOW
C

```

COMB

COMB

```

      IPVBD = 2+ICNT
      LASTSV = IPVBD - 1
      DO 300 I=1,ICNT
        JCNT = 0
        DV(I) = DV(I) - TSUM(I,1)
      C
      DO 200 J=IPVBD,NFLOW
        200 DV(I) = DV(I) - TSUM(I,J)
      C
      DO 250 J=2,LASTSV
        JCNT = JCNT + 1
        250 C(I,JCNT) = TSUM(I,J)
        300 CONTINUE
      C
      C
      CALL SOLCOM( DV, C, ICNT )
      DO 500 I = 1,NT
        C *** ADD PV FLOWS TO AXIS FLOW FOR COMBINATION SOLUTION      ON BODY
        JCNT = 0
        DO 350 J=IPVBD,NFLOW
          XN(I,1) = XN(I,1) + XN(I,J)
          350 T(I,1) = T(I,1) + T(I,J)
          C *** ADD K * STRIP VORTEX BODY VELOCITY FOR COMBINATION SOLUTION
          DO 400 J = 2,LASTSV
            JCNT = JCNT + 1
            XN(I,1) = XN(I,1) + CHAY(JCNT)* XN(I,J)
            400 T(I,1) = T(I,1) + CHAY(JCNT)*T(I,J)
            CP(I) = 1.0 - T(I,1)**2
          500 CONTINUE
          I=1
          J=1
          M=1
          N=ND(M)
          LCTR = 22
          540 WRITE(6,550)HEDR,CASE,PSF

```

COMB

```

COMB 071
COMB 072
COMB 073
COMB 074
COMB 075
COMB 076
COMB 077
COMB 078
COMB 079
COMB 080
COMB 081
COMB 082
COMB 083
COMB 084
COMB 085
COMB 086
COMB 087
COMB 088
COMB 089
COMB 090
COMB 091
COMB 092
COMB 093
COMB 094
COMB 095
COMB 096
COMB 097
COMB 098
COMB 099
COMB 100
COMB 101
COMB 102
COMB 103
COMB 104
COMB 105

```

COMB

```

550 FORMAT(1H1,25X, 26HDOUGLAS AIRCRAFT COMPANY /
1 28X, 21HLONG BEACH DIVISION ///
2 6X,10A6, 4X,10HCASE NO. A6, 9H PSF = ,A4 // )
WRITE(6,560)
560 FORMAT( 1H ,21H COMBINATION SOLUTION )
WRITE(6,700)
700 FORMAT(1H 5X 24H TRANSFORMED COORDINATES //
1 12X,1HX 13X 1HY 13X 2HT1 12X 2HCP 9X 5HSIN A 6X 5HCOS A 11X 1HN
2 // )
710 WRITE(6,720)I,X1(I),Y1(I),X2(J),Y2(J),T(J,1),CP(J),SINA(J),COSA(J)
, XN(J,1)
720 FORMAT(1H 13,2F14.7 / 4X 4F14.7,2F11.5,2F14.7 )
I=I+1
J=J+1
IF( I .EQ. N) GO TO 730
IF( J .LE. LCTR ) GO TO 710
LCTR = LCTR + 22
GO TO 540
730 M=I+1
N=N+ND(M)
WRITE(6,740)I,X1(I),Y1(I)
740 FORMAT( 1H ,13, 2F14.7 // )
I=I+1
IF( J .LT. NT)GO TO 710
M1 = 0
N1 = 0
DO 800 K = 1,NR
M1 = N1 + 1
N1 = N1 + ND(K) - 1
CIRC = 0.0
THRUST = 0.0
DO 790 I = M1,N1
CIRC = CIRC + ( T(I,1) * DELS(I) )
THRUST = THRUST + ( Y2(I) * CP(I) * SINA(I) * DELS(I) )
790 THRUST = -6.283186 * THRUST

```

COMB

```

WRITE(6,795)K,CIRC,THRUST
795 FORMAT(//13H BODY NO. ,I4,5X,14HCIRCULATION = ,F14.7,5X,
1 9HTHRUST = ,F14.7)
ADD CONTINUE
RETURN
C *** OFF BODY COMBINATION SOLUTION
1000 IPVRND = 2 + ICNT
LASTSV = IPVRND - 1
DO 1500 I=1,NP
JCNT = 0
C *** ADD PV FLOWS TO AXIS FLOW FOR COMBINATION SOLUTION OFF BODY
DO 1350 J = IPVRND,NFLOW
VX(I,1) = VX(I,1) + VX(I,J)
1350 VY(I,1) = VY(I,1) + VY(I,J)
C *** ADD K * STRIP VORTEX OFF BODY VELOCITY
DO 1400 J=2,LASTSV
JCNT = JCNT + 1
VX(I,1) = VX(I,1) + CHAY(JCNT) * VX(I,J)
1400 VY(I,1) = VY(I,1) + CHAY(JCNT) * VY(I,J)
VY(I,1) = SQRT( VX(I,1)**2 + VY(I,1)**2 )
1500 CONTINUE
I = 1
LCTR = 45
1540 WRITE(6,550)HEDR,CASE,PSF
WRITE(6,1560)
1560 FORMAT(1H ,31H COMBINATION SOLUTION OFF BODY )
WRITE(6,1700)
1700 FORMAT(1H ,5X,24H TRANSFORMED COORDINATES //
1 12X,14HX,13X,14HY,13X,24HVT,12X,24HVT //)
1710 WRITE(6,1720)I,XP(I),YP(I),VX(I,1),VY(I,1),VT(I,1)
1720 FORMAT(1H ,I3,5F14.7)
I = I + 1
IF(I .GT. NP)GO TO 1750
IF(I .LE. LCTR)GO TO 1710
LCTR = LCTR + 45

```

COMB 141
COMB 142
COMB 143
COMB 144
COMB 145
COMB 146
COMB 147
COMB 148
COMB 149
COMB 150
COMB 151
COMB 152
COMB 153
COMB 154
COMB 155
COMB 156
COMB 157
COMB 158
COMB 159
COMB 160
COMB 161
COMB 162
COMB 163
COMB 164
COMB 165
COMB 166
COMB 167
COMB 168
COMB 169
COMB 170
COMB 171
COMB 172
COMB 173
COMB 174
COMB 175

COMB

GO TO 1540
1750 CONTINUE
RETURN
END

COMB 176
COMB 177
COMB 178
COMB 179

COMB

001	\$01C
002	\$01C
003	\$01C
004	\$01C
005	\$01C
006	\$01C
007	\$01C
008	\$01C
009	\$01C
010	\$01C
011	\$01C
012	\$01C
013	\$01C
014	\$01C
015	\$01C
016	\$01C
017	\$01C

001C
CROS
002C
CROS
003I
CROS
004
CROS
005
CROS
006
CROS
007
CROS
008
CROS
009
CROS
010
CROS
011
CROS
012
CROS
013
CROS
014
CROS
015
CROS
016
CROS
017
CROS
018I
CROS
019
CROS
020
CROS
021
CROS
022
CROS
023
CROS
024
CROS
025
CROS
026
CROS
027
CROS
028
CROS
029
CROS
030
CROS
031
CROS
032
CROS
033
CROS
034
CROS
035

OVERLAY(AXSY,4,2)
PROGRAM CROSS
SURROUTINE CROSS

* COMPUTE CROSS FLOW VELOCITY COMPONENTS AND PRINT

COMMON /TPSF/ PSF
COMMON

1 HEDR(10) ,CASE ,NNU ,FLG06 ,FLG07
2 ,FLG03 ,FLG04 ,FLG05 ,FLG11 ,FLG12
3 ,FLG08 ,FLG09 ,FLG10 ,FLG16 ,FLG17
4 ,FLG13 ,FLG14 ,FLG15 ,FLG21 ,FLG22
5 ,FLG18 ,FLG19 ,FLG20 ,FLG26 ,FLG27
6 ,FLG23 ,FLG24 ,FLG25 ,FLG26 ,FLG27

COMMON
1 NT, ND(11), MN, NUNA(5), TYPEA(5),
2 NER1, NER2, NMA, NSIGA, NSIGC,
3 NUNC(5), TYPEC(5), NUF(11), IEC, NSIGEC,
4 TYPEEC(5), NUNEC(5)

DOUBLE PRECISION HEDR, CASE
INTEGER
1 FLG03 ,FLG04 ,FLG05 ,FLG06 ,FLG07
2 ,FLG08 ,FLG09 ,FLG10 ,FLG11 ,FLG12
3 ,FLG13 ,FLG14 ,FLG15 ,FLG16 ,FLG17
4 ,FLG18 ,FLG19 ,FLG20 ,FLG21 ,FLG22
5 ,FLG23 ,FLG24 ,FLG25 ,FLG26 ,FLG27

REAL

COMMON /C4/ X1(100), Y1(100), X2(100), Y2(100), DELS(100),
1 SINA(100), CUSA(100), XP(100), YP(100)
COMMON /TC/ RB(100,10), SIG(100,5), A(100), B(100),
1 Z(100), PHI(100,5), XN(100,5), T(100,5),
2 T3(100,5), NSIG, NP,
3 SUMV, SUMM(5)

DIMENSION VX(100,5), VY(100,5), VZ(100,5), T2(100,5)

EQUIVALENCE (VX(1,1), XN(1,1)), (VY(1,1), T(1,1)),


```

1      (VZ(1,1), T3(1,1) ), (T2(1,1), T(1,1) )
C
C      * START
C      IF (FLG08.EQ.0) GO TO 10
C      * TITLE FOR MATRIX PRINT
C      WRITE(6,150)HEDR,CASE,PSF
C      WRITE(6,8)
C      * FORMAT (1H 36H MATRICES A,B,Z BY ROWS * CROSS FLOW //)
C      * READ CROSS SIGMAS
10      DO 20 N=1,NSIG
C      SUMM(N)=0.0
20      READ (3) (SIG(I,N),I=1,NT)
C      * NO. OF MIDPOINTS LOOP
C      DO 100 I=1,NT
C      * READ MATRICES A,B,Z
C      READ (10) (A(J),J=1,NT),(B(J),J=1,NT),(Z(J),J=1,NT)
C      * NO. OF FLOWS LOOP
C      M=0
C      DO 70 N=1,NSIG
C      M=M+2
C      SA=0.0
C      SB=0.0
C      SZ=0.0
C      * NO. OF ELEMENTS LOOP
C      DO 30 J=1,NT
C      SA=SA+A(J)*SIG(J,N)
C      SB=SB+B(J)*SIG(J,N)
C      SZ=SZ+Z(J)*SIG(J,N)
C      * INITIALIZE UNIFORM OR NON-UNIFORM PARAMETERS
30      IF (FLG21.GT.0) GO TO 38
C      IF (N.FQ.1.AND.FLG17.LE.0) GO TO 35
C      C1=RR(I,M)
C      C2 = -RB(I,M-1)
C      C3=0.0
C      GO TO 40

```

```

CROS 036
CROS 037
CROS 038
CROS 039
CROS 040
CROS 041
CROS 042
CROS 043
CROS 044
CROS 045
CROS 046
CROS 047
CROS 048
CROS 049
CROS 050
CROS 051
CROS 052
CROS 053
CROS 054
CROS 055
CROS 056
CROS 057
CROS 058
CROS 059
CROS 060
CROS 061
CROS 062
CROS 063
CROS 064
CROS 065
CROS 066
CROS 067
CROS 068
CROS 069
CROS 070

```

```

35 C1=SINA(I)
   C2=COSA(I)
   C3=1.
   GO TO 40
38 C1 = 0.0
   C2 = 0.0
   C3 = 0.0
40 IF (FLG12.EQ.0) GO TO 45
   * OPTION FOR Z (PHI) MATRIX SOLUTION
   XN(I,N) = SA
   PHI(I,N) = Y2(I) * SZ
   GO TO 50
C
   * REGULAR A MATRIX SOLUTION
45 PHI(I,N)=Y2(I)*SZ
   XN(I,N)=SA+C2
50 IF (FLG11.EQ.0) GO TO 55
   * OPTION PERTURBATIONS
C
   T2(I,N)=SB
   T3(I,N)=SZ
   GO TO 60
55 T2(I,N)=SB+C1
   T3(I,N)=SZ+C3
60 IF(FLG21.GT.0) GO TO 70
   SUMM(N) = SUMM(N) + PHI(I,N) * Y2(I) * C2 * DELS(I)
70 CONTINUE
   IF (FLG08.EQ.0) GO TO 100
   WRITE (6,80) I,(A(J),J=1,NT)
80 FORMAT (1H0 13H MATRIX A ROW I6/ (1H 10F10.5))
   WRITE (6,85) I,(B(J),J=1,NT)
85 FORMAT (1H0 13H MATRIX B ROW I6/ (1H 10F10.5))
   WRITE (6,90) I,(Z(J),J=1,NT)
90 FORMAT (1H0 13H MATRIX Z ROW I6/ (1H 10F10.5))
100 CONTINUE
C
   * PRINT CROSS FLOW (ON=BODY) OUTPUT
130 DO 250 L=1,NSIG

```

```

CROS 071
CROS 072
CROS 073
CROS 074
CROS 075
CROS 076
CROS 077
CROS 078
CROS 079
CROS 080
CROS 081
CROS 082
CROS 083
CROS 084
CROS 085
CROS 086
CROS 087
CROS 088
CROS 089
CROS 090
CROS 091
CROS 092
CROS 093
CROS 094
CROS 095
CROS 096
CROS 097
CROS 098
CROS 099
CROS 100
CROS 101
CROS 102
CROS 103
CROS 104
CROS 105

```

```

138 I = 1
139 J = 1
140 K = L
141 IF (FLG17.LE.0) KC=L-1
142 IF (FLG21.GT.0) GO TO 138
143 SUMM(L) = 3.141593 *SUMM(L)
144 I = 1
145 J = 1
146 M = 1
147 NEND(M)
148 LCTR=22
149 WRITE(6,150)HEDR,CASE,PSF
150 FORMAT (1H1 25X, 26HDOUGLAS AIRCRAFT COMPANY /
1 28X, 21HLONG BEACH DIVISION ///
2 6X,10A6,4X,10HCASE NO. A6,10H PSF = ,A4 //)
151 IF (FLG22.GT.0) GO TO 175
152 IF (L.GT.1.OR.FLG17.NE.0) GO TO 170
153 WRITE (6,160)
154 FORMAT (1H 27H ON-BODY UNIFORM CROSS FLOW )
155 GO TO 190
156 IF (TYPEC(KC).GE.0.) GO TO 175
157 WRITE (6,172)
158 FORMAT (1H 31H FLOW GENERATOR * ROTATING BODY )
159 WRITE (6,180) NUNC(KC)
160 FORMAT (1H 35H ON-BODY NON-UNIFORM CROSS FLOW NO. I8)
161 WRITE (6,200)
162 FORMAT (1H 5X 24H TRANSFORMED COORDINATES //
1 12X 1HX 13X 1HY 13X 2HT2 12X 2HT3 9X 5HSIN A
2 6X 5HCOS A 7X 5HSIGMA 11X 1HN 13X 3HPHI //)
163 WRITE (6,220) I,X1(I),Y1(I),X2(J),Y2(J),
1 SINA(J),COSA(J),SIG(J,L),XN(J,L),PHI(J,L),
220 FORMAT (1H I3,2F14,7/ 4X 4F14,7,2F11.5,3F14,7)
164 I=I+1
165 J=J+1
166 IF (I.EQ.N) GO TO 230
167 IF (I.LE.LCTR) GO TO 210
168 LCTR=LCTR+22

```

CROS 106
CROS 107
CROS 108
CROS 109
CROS 110
CROS 111
CROS 112
CROS 113
CROS 114
CROS 115
CROS 116
CROS 117
CROS 118
CROS 119
CROS 120
CROS 121
CROS 122
CROS 123
CROS 124
CROS 125
CROS 126
CROS 127
CROS 128
CROS 129
CROS 130
CROS 131
CROS 132
CROS 133
CROS 134
CROS 135
CROS 136
CROS 137
CROS 138
CROS 139
CROS 140

CRUS

```

      GO TO 140
230  M=M+1
      N=N+ND(M)
      WRITE (6,240) I,X1(I),Y1(I)
240  FORMAT (1H I3, 2F14.7 //)
      I=I+1
      IF (J.GT.NT) GO TO 242
      GO TO 210
242  IF (FLG22.GT.0) GO TO 250
      WRITE (6,244) SUMM(L), SUMV
244  FORMAT (1H0 10X,14H ADDED MASS = F12.7; 4X,10H VOLUME = F12.7)
250  CONTINUE
252  IF (FLG05.EQ.0) RETURN
      * OFF-BODY POINT
      DO 300 I=1,NP
      * READ MATRICES X,Y,Z
      READ (10) (A(J),J=1,NT),(B(J),J=1,NT),(Z(J),J=1,NT)
      * NO. OF FLOW
      DO 300 N=1,NSIG
      SX=0.0
      SY=0.0
      SP=0.0
      * NO. OF ELEMENTS LOOP
      DO 260 J=1,NT
      SX=SX+A(J)*SIG(J,N)
      SY=SY+B(J)*SIG(J,N)
      SP=SP+Z(J)*SIG(J,N)
      VX(I,N)=SX
      PH(I,I,N)=YP(I)*SP
      IF (FLG22.GT.0) GO TO 270
      IF (FLG11.GT.0.OR.N.NE.1.OR.FLG17.GT.0) GO TO 270
      VY(I,N)=SY+1.
      VZ(I,N)=SP+1.
      GO TO 300
      * PERTURBATION OR NON-UNIFORM VY,VZ

```

```

CRUS 141
CRUS 142
CRUS 143
CRUS 144
CRUS 145
CRUS 146
CRUS 147
CRUS 148
CRUS 149
CRUS 150
CRUS 151
CRUS 152
CRUS 153
CRUS 154
CRUS 155
CRUS 156
CRUS 157
CRUS 158
CRUS 159
CRUS 160
CRUS 161
CRUS 162
CRUS 163
CRUS 164
CRUS 165
CRUS 166
CRUS 167
CRUS 168
CRUS 169
CRUS 170
CRUS 171
CRUS 172
CRUS 173
CRUS 174
CRUS 175

```

CRUS

```

270 VY(I,N)=SY
V7(I,N)=SP
300 CONTINUE
      * PRINT CROSS FLOW (OFF-BODY) OUTPUT
330 DO 450 L=1,NSIG
    KC = L
    IF (FLG17,LE.0) KC=L-1
    I=1
    LCTR=45
340 WRITE(6,150)MEDR,CASF,PSF
    IF (FLG22,GT.0) GO TO 375
    IF (L.GT.1.OR.FLG17,NE.0) GO TO 370
    WRITE(6,360)
360 FORMAT (1H 2RH OFF-BODY UNIFORM CROSS FLOW )
    GO TO 390
370 IF (TYPEC(KC).GE.0.) GO TO 375
    WRITE(6,172)
375 WRITE(6,380) NUNC(KC)
380 FORMAT (1H 36H OFF-BODY NON-UNIFORM CROSS FLOW NO. 18)
390 WRITE(6,400)
400 FORMAT (1H 5X, 24H TRANSFORMED COORDINATES //
1 12X 1HX 13X 1HY 13X 2HVX 12X 2HVV 12X 2HVZ 12X 3HPHI //)
410 WRITE(6,420) I,XP(I),VP(I),VX(I,L),VY(I,L),VZ(I,L),PHI(I,L)
420 FORMAT (1H 13, 6F14.7)
    I=I+1
    IF (I.GT.NP) GO TO 450
    IF (I.LE.LCTR) GO TO 410
    LCTR=LCTR+45
    GO TO 340
450 CONTINUE
500 CONTINUE
      C RETURN
      FND

```

```

CROS 176
CROS 177
CROS 178
CROS 179
CROS 180
CROS 181
CROS 182
CROS 183
CROS 184
CROS 185
CROS 186
CROS 187
CROS 188
CROS 189
CROS 190
CROS 191
CROS 192
CROS 193
CROS 194
CROS 195
CROS 196
CROS 197
CROS 198
CROS 199
CROS 200
CROS 201
CROS 202
CROS 203
CROS 204
CROS 205
CROS 206
CROS 207I
CROS 208

```

EXCR

```

OVERLAY(AXSY,4,3)
PROGRAM EXCRNS
SUBROUTINE EXCRNS
  **COMPUTE EXTRA CROSS FLOW VELOCITY COMPONENTS AND PRINT
  COMMON /IPSF/ PSF
  COMMON
    HEDR(10) ,CASE ,NB ,NNU ,FLG06 ,FLG07
    ,FLG03 ,FLG04 ,FLG05 ,FLG11 ,FLG12
    ,FLG08 ,FLG09 ,FLG10 ,FLG16 ,FLG17
    ,FLG13 ,FLG14 ,FLG15 ,FLG21 ,FLG22
    ,FLG18 ,FLG19 ,FLG20 ,FLG26 ,FLG27
    ,FLG23 ,FLG25 ,FLG27
  COMMON NT, ND(11), MN, NUNA(5), TYPEA(5),
  1 NER1, NER2, NMA, NSIGA, NSIGC,
  2 NUNC(5), TYPEC(5), NLF(11), IFC, NSIGEC,
  3 TYPEEC(5), NUNEC(5)
  DOUBLE PRECISION HEDR, CASE
  INTEGER FLG03 ,FLG04 ,FLG05 ,FLG06 ,FLG07
  1 ,FLG08 ,FLG09 ,FLG10 ,FLG11 ,FLG12
  2 ,FLG13 ,FLG14 ,FLG15 ,FLG16 ,FLG17
  3 ,FLG18 ,FLG19 ,FLG20 ,FLG21 ,FLG22
  4 ,FLG23 ,FLG25 ,FLG27
  REAL MN
  COMMON /C4/ X1(100), Y1(100), X2(100), Y2(100), DELS(100),
  1 SINA(100), COSA(100), XP(100), YP(100)
  COMMON /TC/ RB(100,10), SIG(100,5), A(100), B(100),
  1 Z(100), PHI(100,5), XN(100,5), T(100,5),
  2 T3(100,5), NSIG, NP, NI,
  3 SUMV, SUMM(5)
  DIMENSION VX(100,5), VY(100,5), VZ(100,5), T2(100,5)
  EQUIVALENCE ( VX(1,1), XN(1,1) ), ( VY(1,1), T(1,1) ),
  1 ( VZ(1,1), T3(1,1) ), ( T2(1,1), T(1,1) )

```

EXCR

```

REWIND 8
IF (FLG08.EQ.0) GO TO 10
***
**TITLE FOR MATRIX PRINT
WRITE(6,150)HEDR,CASF,PSF
WRITE (6,8)
8 FORMAT (1H 42H MATRICES A,B,Z BY ROWS * EXTRA CROSS FLOW //)
***
**READ EXTRA CROSS SIGMAS
10 DO 20 N = 1,NSIG
20 READ (3) ( SIG(I,N),I = 1,NT )
***
**NO. OF MIDPOINTS LOOP
DO 100 I = 1,NT
***
**READ MATRICES A,B,Z
***
**YOU MUST SOLVE POTENTIAL MATRIX FOR EXCROS
READ (8) ( A(J),J = 1,NT),( B (J),J = 1,NT ), ( Z(J),J = 1,NT )
***
**NO. OF FLOWS LOOP
M = 0
DO 70 N = 1,NSIG
M = M + 2
SA = 0.0
SB = 0.0
SZ = 0.0
***
**NO. OF ELEMENTS LOOP
DO 30 J = 1,NT
SA = SA + A(J) * SIG(J,N)
SB = SB + B(J) * SIG(J,N)
30 SZ = SZ + Z(J) * SIG(J,N)
40 T2(I,N) = SB
T3(I,N) = SZ
XN(I,N) = SA
PHY(I,N) = Y2(I) * SZ / 2.0
70 CONTINUE
IF (FLG08.EQ.0) GO TO 100
WRITE (6,80) I, (A(J),J = 1,NT)
80 FORMAT (1H0 13H MATRIX A ROW I6/ (1H 10F10.5) )
WRITE (6,85) I, (B(J),J = 1,NT)

```

EXCR 036
 EXCR 037
 EXCR 038
 EXCR 039
 EXCR 040
 EXCR 041
 EXCR 042
 EXCR 043
 EXCR 044
 EXCR 045
 EXCR 046
 EXCR 047
 EXCR 048
 EXCR 049
 EXCR 050
 EXCR 051
 EXCR 052
 EXCR 053
 EXCR 054
 EXCR 055
 EXCR 056
 EXCR 057
 EXCR 058
 EXCR 059
 EXCR 060
 EXCR 061
 EXCR 062
 EXCR 063
 EXCR 064
 EXCR 065
 EXCR 066
 EXCR 067
 EXCR 068
 EXCR 069
 EXCR 070

EXCR

```

85 FORMAT (1H0 13H MATRIX 8 ROW 16/ (1H 10F10.5) )
WRITE (6,90) I, ( Z(J),J = 1,NT)
90 FORMAT (1H0 13H MATRIX 2 ROW 16/ (1H 10F10.5) )
100 CONTINUE
C*** **PRINT EXTRA CROSS FLOW (ON BODY) OUTPUT
130 DO 250 L = 1,NSIG
    KEC = L
    I = 1
    J = 1
    M = 1
    N = ND(M)
C*** **M IS THE BODY NUMBER
C*** **N IS THE NUMBER OF POINTS ON BODY M
    LCTR = 22
140 WRITE(6,150)HEDR,CASE,PSF
150 FORMAT (1H1 25X, 26HDOUGLAS AIRCRAFT COMPANY /
1      28X, 21HLONG BEACH DIVISION ///
2      6X,10A6,4X,10HCASE NO, A6,10H PSF = ,A4 //)
    IF (FLG22.GT.0) GO TO 160
    WRITE (6,155)NUNEC(KEC)
155 FORMAT(41H ON=BODY NON-UNIFORM EXTRA CROSS FLOW NO. 18)
    GO TO 190
160 WRITE (6,162)
162 FORMAT(68H ON BODY GENERATED (RESEP) BOUNDARY CONDITIONS EXTR
1A CROSS FLOW)
190 WRITE (6,200)
200 FORMAT (1H 5X 24H TRANSFORMED COORDINATES //
1      12X 1HX 13X 1HY 13X 2HT2 12X 2HT3 9X 5HSIN A
2      6X 5HCOS A 7X 5HSIGMA 11X 1HN 13X 3PHI //)
210 WRITE (6,220) I,X1(I),Y1(I),X2(J),Y2(J),
1      SINA(J),COSA(J),SIG(J,L),XN(J,L),PHI(J,L),
220 FORMAT (1H 13,2F14.7/ 4X 4F14.7,2F11.5,3F14.7)
    I = I + 1
    J = J + 1
    IF (I.EQ.N) GO TO 230

```

EXCR

EXCR

```

IF (I,LF,LCTR) GO TO 210
LCTR = LCTR + 22
GO TO 140
230 M = M + 1
N = N + ND(M)
WRITE (6,240) I, X1(I), Y1(I)
240 FORMAT (1H I3,2F14.7 //)
I = I + 1
IF (J,GE,NT) GO TO 250
GO TO 210
250 CONTINUE
C 252 IF (FLG05.EQ.0) RETURN
252 IF (FLG05.EQ.0) CONTINUE
C*** **OFF BODY POINTS
DO 300 I = 1,NP
C*** **READ MATRICES X,Y,Z
READ (R) (A(J),J=1,NT),(B(J),J = 1,NT), (Z(J),J = 1,NT)
DO 300 N = 1,NSIG
SX = 0.0
SY = 0.0
SP = 0.0
C*** **NUMBER OF ELEMENTS LOOP
DO 260 J = 1,NT
SX = SX + A(J) * SIG (J,N)
SY = SY + B(J) * SIG (J,N)
260 SP = SP + Z(J) * SIG(J,N)
VX(I,N) = SX
VY(I,N) = SY
VZ(I,N) = SP
PHI(I,N) = YP(I) * SP / 2.0
300 CONTINUE
C*** **PRINT EXTRA CROSS FLOW (OFF-BODY) OUTPUT
330 DO 450 L = 1,NSIG
KFC = L
I = 1

```

EXCR

```

EXCR 106
EXCR 107
EXCR 108
EXCR 109
EXCR 110
EXCR 111
EXCR 112
EXCR 113
EXCR 114
EXCR 115
EXCR 116
EXCR 117I
EXCR 118C
EXCR 119
EXCR 120
EXCR 121
EXCR 122
EXCR 123
EXCR 124
EXCR 125
EXCR 126
EXCR 127
EXCR 128
EXCR 129
EXCR 130
EXCR 131
EXCR 132
EXCR 133
EXCR 134
EXCR 135
EXCR 136
EXCR 137
EXCR 138
EXCR 139
EXCR 140

```

EXCR

```

      LCTR = 45
340  WRITE(6,150)HEDR,CASE,PSF
      IF (FLG22.GT.0) GO TO 355
      WRITE(6,350) NUNEC(KEC)
350  FORMAT (43H OFF BODY NON-UNIFORM EXTRA CROSS FLOW NO. 18)
      GO TO 390
355  WRITE(6,357)
357  FORMAT(68H OFF BODY GENERATED (RFESEP) BOUNDARY CONDITIONS
      1A CROSS FLOW)
390  WRITE (6,400)
400  FORMAT (1H 5X, 24H TRANSFORMED COORDINATES //
      1 12X 1HX 13X 1HY 13X 2HVX 12X 2HVV 12X 2HVZ 12X 3MPHI //)
410  WRITE (6,420) I,XP(I),YP(I),VX(I,L),VY(I,L),VZ(I,L),PHI(I,L)
420  FORMAT (1H 13, 6F14,7)
      I = I + 1
      IF (I.GT.NP)GO TO 450
      IF (I.LE.LCTR) GO TO 410
      LCTR = LCTR + 45
      GO TO 340
450  CONTINUE
      RETURN
C 501 CONTINUE
      END

```

```

EXCR 141
EXCR 142
EXCR 143
EXCR 144
EXCR 145
EXCR 146
EXCR 147
EXCR 148
EXCR 149
EXCR 150
EXCR 151
EXCR 152
EXCR 153
EXCR 154
EXCR 155
EXCR 156
EXCR 157
EXCR 158
EXCR 159
EXCR 160
EXCR 161I
EXCR 162C
EXCR 163

```

EXCR

2012

NCDE

```
COMMON /RL14/ RX1, RTH1, CF0, CF1, CF2, CFSUM0, CFSUM,  
    THETA(100), DELS(100), FPPW(100)  
COMMON /BL15/ NX  
COMMON /RL17/ RX(100), CFA(100), CF(100), EYAE(100), ST(100),  
    INP(100)  
COMMON /RL19/ C(100,2), G(100,2), GP(100,2),  
    RHD(100), RMU(100), TVCT(100)  
COMMON /BL20/ RTHYR, UEIN, ROIN, GAMAT  
COMMON /RL21/ A1(100,2), A2(100,2)  
COMMON /RADIUS/ ROMAX
```

NOO

```

      IF(NX.LT.NXT) IGOL = 1
      IF(NX.GF.NXT) IGOY = 1
C ----
      IGCY=0
      CALL FINE
      IF(LG32.NE.1.OR.NX.EQ.1) CALL HEAD
      IF(LG32.EQ.1) GO TO 130
      WRITE(6,6015) NX,BETA(NX),XI(NX),XS(NX),ETAINF(NX)
      GO TO 138
130 IF(NX.EQ.1) WRITE(6,7000)
      LC = LC+3
      IF(LC.LT.LCMAX) GO TO 135
      CALL HEAD
      LC=0
135 WRITE(6,7015) NX,BETA(NX),XI(NX),XS(NX),ETAINF(NX)
      LC = LC+2
138 IF(LSP.EQ.1) GO TO 700
C ----
      IF(NX.EQ.1) CALL IVPF
      IF(LSP.EQ.1) GO TO 700
C ----
      IF(NX.EQ.1) CALL FLPR
      IF(LSP.EQ.1) GO TO 700
C ----
      IF(NX.NE.1.OR.XS(NX).EQ.0.) GO TO 140
      CALL EDVS
      IF(LSP.EQ.1) GO TO 700
C ----
140 IF(NX.EQ.1) GO TO 145
      CALL SHFT
      IF(LSP.EQ.1) GO TO 700
      CALL FIPR
      IF(LSP.EQ.1) GO TO 700
C ----
145 IT=0

```

```

BOUN 071
BOUN 072
BOUN 073
BOUN 074
BOUN 075
BOUN 076
BOUN 077
BOUN 078
BOUN 079
BOUN 080
BOUN 081
BOUN 082
BOUN 083
BOUN 084
BOUN 085
BOUN 086
BOUN 087
BOUN 088
BOUN 089
BOUN 090
BOUN 091
BOUN 092
BOUN 093
BOUN 094
BOUN 095
BOUN 096
BOUN 097
BOUN 098
BOUN 099
BOUN 100
BOUN 101
BOUN 102
BOUN 103
BOUN 104
BOUN 105

```

BOUN

BOUN

```

LC = LC+2
IF(NX-NXT)150,142,150
142 ITC=1
150 IT=IT+1
LC = LC+1
IF(IT.LE.9) GO TO 220
IF(ITC.EQ.0) GO TO 200
WRITE(6,6000)
ITC=0
IT=1
GO TO 220
200 WRITE(6,6010)
LSP=1
GO TO 700
220 CALL EDVS
IF(LSP.EQ.1) GO TO 700
CALL MOMX
300 IF(IGOL.EQ.1) GO TO 540
IF(IGOT.EQ.1) GO TO 550
540 IF(ABS(DELV1).LT.EPSLN) GO TO 600
IF(V(1,2).LT.0. .AND. LG16.NE.0) GO TO 670
GO TO 150
550 EAG= DELV1/((V(1,2)+VMPRI)*.5)
IF(ABS(EAG).LT.0.02) GO TO 600
IF(IGTR.LE.1 .OR. V(1,2).LE.0.) GO TO 150
IGCV=1
CALL EINF
IF(NX.EQ.1) GO TO 150
IF(LSP.EQ.1) GO TO 700
IF(IGRC.EQ.0) GO TO 150
CALL SHFT
CALL FLPR
GO TO 145
C=---
600 WRITE(6,6030) V(1,2)

```

C=---

BOUN

BOUN

```

LC = LC+1
IF(IGTR.GT.1) IGTR=0
IGCV=1
CALL EINF
LC=LC+3
IF(LSP.EQ.1) GO TO 700
IF(IGRC.EQ.0) GO TO 670
CALL SHFT
CALL FLPR
IF(LSP.EQ.1) GO TO 700
LC = LC+2
GO TO 145

C ----
670 CALL OTPT
IF(NX.EQ.NXM) GO TO 700

C ----
IF(IGOT.EQ.1) GO TO 100
IF(NX.GT.1.AND.LG16.NE.0) CALL TRNS
IF(IGTR.GT.1) IGRC=1
IF(LSP.EQ.1) GO TO 700
IF(IGTR.GT.1) GO TO 120

C ----
GO TO 100
700 IF(NX.EQ.0) GO TO 800
IOUT=1
CALL OTPT
800 IF(LSP.EQ.1) WRITE(6,9999)

C ----
5010 FORMAT(13,39X,I1)
6000 FORMAT(1H,20X,43HCONVGRGENCE IS SLOW - ITERATIONS CONTINUING,/)
6010 FORMAT(1H,15X,45H** ITERATIONS EXCEED THE ALLOWABLE LIMIT ** /)
6015 FORMAT(1H0,///5X,8HSTATION=,I3,3X,5HBETA=,E16.9,2X,3HXI=,E16.9,2X,
1 2HS=,E16.9,2X,8HETAINF =,E16.9,////)
6030 FORMAT(1H,32X,E20.9)
7000 FORMAT(1H,45X,20HOUTPUT IN SHORT FORM; /)

```

BOUN

```

BOUN 141
BOUN 142
BOUN 143
BOUN 144
BOUN 145
BOUN 146
BOUN 147
BOUN 148
BOUN 149
BOUN 150
BOUN 151
BOUN 152
BOUN 153
BOUN 154
BOUN 155
BOUN 156
BOUN 157
BOUN 158
BOUN 159
BOUN 160
BOUN 161
BOUN 162
BOUN 163
BOUN 164
BOUN 165
BOUN 166
BOUN 167
BOUN 168
BOUN 169
BOUN 170
BOUN 171
BOUN 172
BOUN 173
BOUN 174
BOUN 175

```

BOUN

```
7015 FORMAT(1H0,5X,8HSTATION=,I3,3X,5HRTA=,E16.9,2X,3HXI=,E16.9,2X,2HS
1=,      E16.9,2X,8HETAINF =,E16.9 )
9999 FORMAT(1H0/45X,37H***** CASE TERMINATED ***** // )
C      RETURN
1000 CONTINUE
      END
```

BOUN 176
BOUN 177
BOUN 178
BOUN 179I
BOUN 180C
BOUN 181

BOUN

INPT

```

C
C **
C
C
      SUBROUTINE INPT
      SURROUTINE INPT
      THIS SUBROUTINE PROCESSES ALL THE INPUT DATA TO THE PROGRAM
C
      COMMON NX,NP,NPPR,JI,IT,NRVP,LSP,NPMI,JJI,JIMI,NTC,NXT,NXM,NXM
      ,TITLE(15)
      COMMON LG16,LG17,LG18,LG32,LG40
      ,IGOL,IGOT,IGOW,IGON,IGCV,YGEG,YGNP,IGRC,IGTR
      COMMON /HEADR/ CASE, IPAGE
      COMMON/BLC7/VGP,DETA1
      COMMON/BLC3/XI(100),XS(100),ETAINF(100),BETA(100)
      COMMON/BLC12/TI,RMI,UI,RI,PR,PRT,FK,RL,RMIUI,RHOI,PSI,HE
      ,UE(100),RO(100),YW(100),GW(100),RP(100),FW(100)
      ,PR(100),TE(100),RHOE(100),RMIUE(100),GW(100),GPW(100)
      ,RF1(100),RF2(100),YS(100),IGX1(100),FPW(100),ROL(100)
      COMMON/BL13/EPSLN
      COMMON /BL15/ NXY
      COMMON/RADIUS/ ROMAX
      DIMENSION S(301),XR(301),DUEDX(100),PE(100)
      DATA DATA1/1.4/, DATA2/6035.0/
C
C
C
      EPSLN = .005
      PR = .72
      READ CASE DATA
      READ(5,5005) TITLE,CASE
      READ(5,5010) NXT,LG16,LG17,LG18,LG32,LG26,LG40,LG41
      READ(5,5020) TI,RMI,UI,FK,RL,RI
      READ(5,5025) ROMAX,DFTA1,VGP
      IF(LG40.EQ.0) GO TO 7000
      READ(5,1013) NXM
      READ(5,1014) (XS(I),I=1,NXM)
      READ(5,1014) (YS(I),I=1,NXM)

```

INPT

```

INPT 001
INPT 002
INPT 003
INPT 004
INPT 005
INPT 006
INPT 007
INPT 008
INPT 009
INPT 010
INPT 011
INPT 012
INPT 013
INPT 014
INPT 015
INPT 016
INPT 017
INPT 018
INPT 019
INPT 020
INPT 021
INPT 022
INPT 023
INPT 024
INPT 025
INPT 026
INPT 027
INPT 028
INPT 029
INPT 030
INPT 031
INPT 032
INPT 033
INPT 034
INPT 035

```

INPT

```

      READ(5,1014) (UE(I),I=1,NXM)
      GO TO 7001
7000 CONTINUE
      READ(3) NXM
      READ(3) (XS(I),I=1,NXM)
      READ(3) (YS(I),I=1,NXM)
      READ(3) (UE(I),I=1,NXM)
7001 CONTINUE
      NXY=NXM
      DO 50 I=1,NXM
        RO(I) = YS(I)
        GW(I)=0.0
        RF2(I) = 0.
        FW(I) = 0.
        GW(I) = 0.
        GPW(I) = 0.
        RF1(I)=0.
        TW(I)=0.
        RP(I)=0.
        FPW(I)=0.
        BR(I)=0.
50   IGX1(I)=0.
        ETAINF(1) = 6.
        ETAINF(2) = 10.
        NXNS=NXM
85   CALL HEAD
        WRITE(6,2050) TITLE,CASE
        WRITE(6,2500) LG16,LG17,LG18,LG32,NXY
150  XS1=0.0
        SD1=0.0
160  DO 180 I=2,NXM
          SDA1=(XS(I)-XS(I-1))*2+(YS(I)-YS(I-1))*2
          SQDA1= SQRT(SDA1)
          SD2=SD1+ ABS(SQDA1)
          S(2*I+1) = SD2

```

INPT

INPT

```

SD1=SD2
IF(I.EQ.2) S(3)=XS1
180 CONTINUE
WRITE(2) NXM
WRITE(2) (S(2*I+1), I=1, NXM)
LC = 1
LCMAX = 36
WRITE(6,2550)
DO 185 I=1, NXM
IF(LC.LT. LCMAX) GO TO 182
CALL HEAD
WRITE(6,2550)
LC = 1
LCMAX = 49
182 XBG = XS(I) * RL
SBG = S(2*I+1) * RL
WRITE(6,3100) I, XS(I), YS(I), XBG, SBG, S(2*I+1)
LC = LC+1
IF(FK.EQ. 1) R0(I) = YS(I)*RL
YS(I)=XS(I)
XS(I) = SBG
185 CONTINUE
IF(LCMAX.EQ.36 .AND. LC.GT.18) CALL HEAD
IF(LCMAX.EQ.49 .AND. LC.GT.45) CALL HEAD
IF(FK.EQ. 0) .OR. LG18.NE. 1) GO TO 203
CALL SLOPE(NXM, XS, YS, RF1, 1)
IF(RL.EQ. 1.0) GO TO 203
DO 202 I=1, NXM
202 RF1(I) = RF1(I)*RL
C-----
203 IF(UI.NE.0. .OR. RMI.NE.0.) GO TO 204
WRITE(6,9030)
LSP = 1
GO TO 1800
204 IF(TI.NE.0.) GO TO 205

```

INPT

```

INPT 071
INPT 072
INPT 073
INPT 074
INPT 075
INPT 076
INPT 077
INPT 078
INPT 079
INPT 080
INPT 081
INPT 082
INPT 083
INPT 084
INPT 085
INPT 086
INPT 087
INPT 088
INPT 089
INPT 090
INPT 091
INPT 092
INPT 093
INPT 094
INPT 095
INPT 096
INPT 097
INPT 098
INPT 099
INPT 100
INPT 101
INPT 102
INPT 103
INPT 104
INPT 105

```

INPT

```

IF(LG41.EQ.0) GO TO 201
WRITE(6,9045)
YI=519.*(5./9.)
GO TO 205
201 CONTINUE
WRITE(6,9040)
TI = 519.0
205 IF(RMI.NE.0.) UI = 0.
IF(LG41.EQ.1) GO TO 206
IF(UI.NE.0.) RMI=UI/(SQRT(YI)*49.1)
IF(RMI.NE.0.) UI=RMI*SQRT(YI)*49.1
RMUI=1.0E-06*(.90311226E-03*YI+1.238522*(.56843634E-06*YI*YI
1+.38312556E-03*YI+1.436156)**0.5)
RMUI=RMUI*RI/UI
PSI=RHUI*YI*1718.0
RMI2=RMI*RMI
DKI=RMI2*(DATA1-1.0)*0.5
UEA4=DATA1*RMI2*0.5
SHI=DATA2*YI
207 HE = SHI + .5*(UI**2)
GO TO 209
206 TIR=YI*.5.
UII=UI/.3048
IF(UT.NE.0.) RMI=UII/(SQRT(TIR)*49.1)
IF(RMI.NE.0.) UI=(RMI*SQRT(TIR)*49.1)*.3048
RMUI=1.0E-06*(.90311226E-03*TIR+1.238522*(.56843634E-06*YIR*TIR
1+.38312556E-03*TIR+1.436156)**0.5)
RMUI=RMUI*RI/UII
PSI=RHUI*TIR*1718.0
SHI=DATA2*TIR
HF=SHI+.5*(UII**2)
RMUI=RMUI*47.88025
RHUI=RHUI*515.379
PSI=PSI*47.88025
HE=HF*.3048*.3048

```

```

INPT 106
INPT 107
INPT 108
INPT 109
INPT 110
INPT 111
INPT 112
INPT 113
INPT 114
INPT 115
INPT 116
INPT 117
INPT 118
INPT 119
INPT 120
INPT 121
INPT 122
INPT 123
INPT 124
INPT 125
INPT 126
INPT 127
INPT 128
INPT 129
INPT 130
INPT 131
INPT 132
INPT 133
INPT 134
INPT 135
INPT 136
INPT 137
INPT 138
INPT 139
INPT 140

```

INPT

```

209 CONTINUE
   IF(LG26.EQ.2) GO TO 270
   IF(LG26.EQ.3) GO TO 210
   WRITE(6,9050)
   LSP=1
   GO TO 1800
210 CONTINUE
208 DO 220 I=1,NXM
   UE(I)=UI* SQRT(1.0-UE(I))
220 CONTINUE
   GO TO 300
270 DO 280 I=1,NXM
   UE(I)=UE(I)*UI
280 CONTINUE
C ----
300 CONTINUE
   DO 320 I=1,NXM
   RHOE(I)=RHOI
   RMUE(I)=RMUI
   PF(I) = 0.
   TE(I) = 0.
320 CONTINUE
500 IST = 1
   MULT = 0
   CALL SLOPE(NXM,XS,UE,DUEDX,MULT)
C ----
510 DO 1500 I=1,NXM
   IF(I.GT.1) GO TO 520
   VT1=RHOI*RMUI
520 VT2=VT1*UE(I)
   VT3=VT2*UE(I)
   IF(PK.NE.0.) GO TO 550
   VT4=1.0
   VT5=1.0
   VT42=1.0

```

INPT

```

INPT 141
INPT 142
INPT 143
INPT 144
INPT 145
INPT 146
INPT 147
INPT 148
INPT 149
INPT 150
INPT 151
INPT 152
INPT 153
INPT 154
INPT 155
INPT 156
INPT 157
INPT 158
INPT 159
INPT 160
INPT 161
INPT 162
INPT 163
INPT 164
INPT 165
INPT 166
INPT 167
INPT 168
INPT 169
INPT 170
INPT 171
INPT 172
INPT 173
INPT 174
INPT 175

```

INPT

INPT

```

GO TO 600
550 IF(FK.NE.1.0) GO TO 560
   IF(R0(I).NE.0.) GO TO 555
   IF(I.GT.1) WRITE(6,9095) I
   R0(I) = .0001*RL
555 VT4=R0(I)/RL
   VT42=VT4*VT4
   VT5=RL/R0(I)
   GO TO 600
560 WRITE(6,9060)
   LSP=1
   GO TO 1800
600 ROL(I) = VT4
   FX2=VT2*VT42
   IF(I.EQ.1) XI(1)=FX2*XS(1)
   IF(I.EQ.1) GO TO 680

```

```

650 XI(I)=XI(I-1)+(FX1+FX2)*(XS(I)-XS(I-1))*0.5

```

```

680 FX1 = FX2
   IF(I.NE.1) GO TO 930
   IF(IST.EQ.0) GO TO 1500
   BETA(1) = 1.0
   IF(FK.EQ.1.) BETA(1) = BETA(1)/2.
   GO TO 1500

```

```

930 IF(I.EQ.2) GO TO 950
   BETA(I)=2.*XI(I)/(VT3*VT42)*DUEDX(I)
   GO TO 1500

```

```

950 BETA(I)=2.0*XI(I)*(UE(I)-UE(I-1))/(VT3*VT42*(XS(I)-XS(I-1)))
1500 CONTINUE

```

C----

```

WRITE(6,2600) DETAI, RL, PR, VGP, RHOI, SWP, FK, RMUI, HE, FPSLN

```

```

INPT 176
INPT 177
INPT 178
INPT 179
INPT 180
INPT 181
INPT 182
INPT 183
INPT 184
INPT 185
INPT 186
INPT 187
INPT 188
INPT 189
INPT 190
INPT 191
INPT 192
INPT 193
INPT 194
INPT 195
INPT 196
INPT 197
INPT 198
INPT 199
INPT 200
INPT 201
INPT 202
INPT 203
INPT 204
INPT 205
INPT 206
INPT 207
INPT 208
INPT 209
INPT 210

```

INPT

INPT

```

1      ,UI, YI, RI, RMI
      CALL HEAD
      WRITE(6,2900)
      WRITE(6,3000)
      LC=1
      LCMAX=45
      DO 1550 I=1,NXM
      IF(LC.LT. LCMAX) GO TO 1520
      CALL HEAD
      WRITE(6,3000)
      LC=1
      LCMAX=49
1520  IF(FK.NE. 0.) GO TO 1530
      WRITE(6,3200) I,VS(I),RO(I), TW(I), UE(I), PE(I), BR(I)
      GO TO 1540
1530  WRITE(6,3200) I,VS(I),ROL(I),TW(I), UE(I), PF(I), BR(I)
1540  CP=1.-UE(I)*UE(I)/(UI*UI)
      WRITE(6,3250) XS(I), RF1(I), QW(I), CP , RMUE(I), FPM(I)
      RMACH = 0.
      WRITE(6,3250) BETA(I), RF2(I), RP(I), RMACH, YE(I), XI(I)
      LC = LC+4
1550  CONTINUE
1590  IGXI=0
      IF(XI(1).GE.0.) GO TO 1600
      WRITE(6,9070)
      IGXI=1
1600  IF(NXM.FQ. 1) RETURN
      DO 1700 I=2,NXM
      IF(XI(I).GT.0.) GO TO 1620
      WRITE(6,9080) I
      IGXI=1
1620  IF(XI(I).GT.XI(I-1)) GO TO 1700
      WRITE(6,9090) I
      IGXI=1
1700  CONTINUE

```

INPT

```

INPT 211
INPT 212
INPT 213
INPT 214
INPT 215
INPT 216
INPT 217
INPT 218
INPT 219
INPT 220
INPT 221
INPT 222
INPT 223
INPT 224
INPT 225
INPT 226
INPT 227
INPT 228
INPT 229
INPT 230
INPT 231
INPT 232
INPT 233
INPT 234
INPT 235
INPT 236
INPT 237
INPT 238
INPT 239
INPT 240
INPT 241
INPT 242
INPT 243
INPT 244
INPT 245

```

INPT

```

IF(IGXI.EQ.0) RETURN
ISP=1
1800 RETURN
C -- --
1013 FORMAT(I4)
1014 FORMAT(6F10.0)
2050 FORMAT(1H,25X,15A4,10X,6HCASE,A4,///1H,54X,10H CASE DATA,///)
2500 FORMAT(1H0,10X,8HTRFLAG=,I1,10X,7HTRINT=,I1,10X,5HYVC=,I1,
1 10X,8HSHORTP=,I1,///1H,30X,31HTRANSITION SPECIFIED AT STATION,I4
1)
2550 FORMAT(1H,50X,19HBODY GEOMETRY DATA /
1 1H0,21X,1HK,9X,3HX/C,15X,3HY/C,16X,1HX,17X,1HS,16X,3HS/C /)
2600 FORMAT(1H0,1H0,40X,43HREFERENCE QUANTITIES AND CONTROL PARAMETERS,
A /1H0,16X,6MH1=,F9.5,16X,8HC=,E15.7,10X,
1 8HPRO=,F9.5, / 1H0,16X,6HK=,F9.5,16X,8HRHOREF=,
2 E15.7,10X,8HSWEEP=,F9.4 / 1H0,16X,6HKK=,F9.5,16X,
3 RHMUREF=,E15.7,10X,8HHE=,E15.7 / 1H0,16X,6HEPS1=,
4 F15.7,10X,8HVRFF=,E15.7,10X,8HTRFF=,F10.3 / 1H0,16X,
5 3IX,8HREY=,E15.7,10X,8HMREF=,E15.7 /)
2900 FORMAT(1H,50X,12HSTATION DATA//)
3000 FORMAT(1H0,7X,1HN,12X,3HX/C,13X,4HRO/C,14X,2HTW,16X,2HUE,15X,2HPE,
1 14X,2HFW, / 1H,20X,4H S,12X,6HALPHA1,13X,2HGW,16X,2HCP,14X,
2 3HMUE,13X,3HFPW, / 1H,20X,4HBFTA,12X,6HALPHA2,13X,2HRR,16X,
3 2HME,15X,2HTE,12X,5HSQUIG, /)
3100 FORMAT(1H,19X,13,5(3X,E15.7))
3200 FORMAT(1H / 1H,18,3X,6E17.6)
3250 FORMAT(1H,11X,6E17.6)
5005 FORMAT(15A4,A4)
5010 FORMAT(I4,7I1)
5020 FORMAT(5F10.0,E12.6)
5025 FORMAT(3F10.0)
5030 FORMAT(2F8.0,F6.0,F5.0,F6.0,F7.0,2F6.0,F7.0,8X,F4.0,I1)
5040 FORMAT(3E14.9)
9004 FORMAT(1H,37H**ERROR = INPUT REFERENCE LENGTH = 0. /)
9005 FORMAT(1H,51H**ERROR = INPUT SURFACE DISTANCE AT STATION 1 LT 0.)

```

INPT


```

9006 FORMAT(1H ,66H**ERROR - INPUT SURFACE DISTANCE NOT IN ASCENDING OR
      1 DER AT STATION, I3 //)
9010 FORMAT(1H ,51H**ERROR - INPUT X NOT IN ASCENDING ORDER AT STATION,
      1 I3 //)
9020 FORMAT(1H0,51H**ERROR - INPUT NTR OR S AT STATION 1 ARE INCORRECT)
9030 FORMAT(1H0,42H**ERROR - NO INPUT FOR EITHER VREF OR MREF)
9040 FORMAT(1H0,52H***** WARNING - YREF INPUT = 0., VALUE RESET TO 519.
      1)
9045 FORMAT(1H0,67H***** WARNING - TREF INPUT = 0., VALUE RESET TO 288.3
      133 DEGREES KFLVIN )
9050 FORMAT(1H0,27H**ERROR - CHECK CPCM INPUT )
9060 FORMAT(1H0,48H**ERROR - INPUT FLOW INDEX NOT EQUAL TO 1, OR 0. )
9070 FORMAT(1H ,38H**ERROR - XI AT STATION 1 NE OR GT 0. )
9080 FORMAT(1H ,25H** ERROR - XI AT STATION ,I3,I2H IS NEGATIVE)
9090 FORMAT(1H ,25H** ERROR - XY AT STATION ,I3,I2H IS NOT IN ASCENDING
      1 ORDER)
9095 FORMAT(1H0,41H***** WARNING - ROIC INPUT=0. AT STATION , I3,
      1 I2H - VALUE RESET TO .0001 )
9100 FORMAT(1H0, 40X,25HINSS NOT SUCCESSFUL NER = ,I2,2X,I0HAT STATION,
      1 IX,I3/IH ,I2X,I1H,15X,3HX/C,22X,3HY/C, //)
9150 FORMAT(1H0,47H** ERROR - INPUT CP EXCEEDS ALLOWABLE LIMITS OF,
      1 2E17,6,1X, I0HAT STATION,I3 /)
9200 FORMAT(1H ,11X,I3,2E20,9)
9300 FORMAT(1H0,40X,25HINSR NOT SUCCESSFUL NER = ,I2,2X,I0HAT STATION,
      1 IX,I3, /IH ,I2X,I1H,15X,3HXIC,22X,3HYIC, //)
      FND

```

INPT

```

INPT 281
INPT 282
INPT 283
INPT 284
INPT 285
INPT 286
INPT 287
INPT 288
INPT 289
INPT 290
INPT 291
INPT 292
INPT 293
INPT 294
INPT 295
INPT 296
INPT 297
INPT 298
INPT 299
INPT 300
INPT 301
INPT 302
INPT 303
INPT 304
INPT 305
INPT 306

```

INPT

EINF

```

SUBROUTINE EINF
C ** SUBROUTINE EINF
C THIS SUBROUTINE CALCULATES THE TRANSFORMED Y - GRID POINTS
C
COMMON NX,NP,NPPH,JI,IT,NRVP,LSP,NPMI,JTI,JTM,NTC,NXT,NXM,NXM
1 ,TITLE(15)
COMMON LG16,LG17,LG18,LG32,LG40
1 ,IGOL,IGOT,IGOW,IGON,IGCV,IGEG,IGNP,IGRC,IGTR
COMMON/BLC1/F(100,2),U(100,2),V(100,2),ETA(100),DELETA(100)
COMMON/BLC3/XI(100),XS(100),ETAINF(100),BETA(100)
COMMON/BLC7/VGP,DETA1
C
C
C
30 IF(IGCV.EQ.1) GO TO 30
IF(NX.EQ.1) GO TO 50
IF(NX.EQ.2) GO TO 250
IF(IGNP.EQ.1) GO TO 300
IF(IGNP.EQ.0) GO TO 800
WRITE(6,9910)
LSP=1
GO TO 1800
C
C
C
50 IF(IGNP.EQ.0) GO TO 1000
IF(IGNP.EQ.1) GO TO 100
WRITE(6,9920)
LSP=1
GO TO 1800
C
C
C
100 DO 120 J=2,NP
IF(ABS(V(J,2)).LT.1.E-5) GO TO 500
IF(ABS(V(J,2)).LT.1.E-6) GO TO 500
120 CONTINUE
DO 140 J=2, NP
IF(ABS(V(J,2)).LT.1.E-4) GO TO 500

```

EINF 001
EINF 002
EINF 003
EINF 004
EINF 005
EINF 006
EINF 007
EINF 008
EINF 009
EINF 010
EINF 011
EINF 012
EINF 013
EINF 014
EINF 015
EINF 016
EINF 017
EINF 018
EINF 019
EINF 020
EINF 021
EINF 022
EINF 023
EINF 024
EINF 025
EINF 026
EINF 027
EINF 028
EINF 029
EINF 030
EINF 031
EINF 032
EINF 033
EINF 034
EINF 035

EINF

EINF

```

      IF(U(J,2).GE..999999) GO TO 500
      IF(U(J,2).LT.0.) GO TO 400
140  CONTINUE
      WRITE(6,9930)
      J = NP
      GO TO 530
C ----
250  IF(IGNP.EQ.0) GO TO 1000
300  DO 320 J=JI,NP
      IF( ABS(V(J,2)).LT.1.E-5) GO TO 500
      IF( ABS(V(J,2)).LT.1.E-6) GO TO 500
320  CONTINUE
      DO 340 J=JI,NP
      IF( ABS(V(J,2)).LT.1.E-4) GO TO 500
      IF(J.EQ.NP) GO TO 330
      IF(U(J,2).GE..999999) GO TO 500
330  IF(U(J,2).LT.0.) GO TO 400
340  CONTINUE
C ----
      WRITE(6,9980)
      IGRC=1
      ETAINF(NX)=ETAINF(NX)+10.
      GO TO 1010
C ----
400  WRITE(6,9940) J
      LSP=1
      GO TO 1800
C ----
500  IF(IGTR.GT.1) GO TO 600
530  ETAINF(NX)=ETA(J)
      JI=J
      IGNP=0
      WRITE(6,6010) ETAINF(NX)
      GO TO 1800
600  IGTR=0

```

EINF

```

EINF 036
EINF 037
EINF 038
EINF 039
EINF 040
EINF 041
EINF 042
EINF 043
EINF 044
EINF 045
EINF 046
EINF 047
EINF 048
EINF 049
EINF 050
EINF 051
EINF 052
EINF 053
EINF 054
EINF 055
EINF 056
EINF 057
EINF 058
EINF 059
EINF 060
EINF 061
EINF 062
EINF 063
EINF 064
EINF 065
EINF 066
EINF 067
EINF 068
EINF 069
EINF 070

```

EINF

```

C ----
      800 K = NX-1
          IF(K.EQ. NXT) GO TO 820
          IF((ETAINF(NX-1).GT.ETAINF(NX-2)).AND.(IGTR .LE. 1)) GO TO 850
          ETAINF(NX) = ETAINF(NX-1) + 2.
      820 IF(IGOT.EQ.1) ETAINF(NX)=ETAINF(NX-1)+10.
          GO TO 1000
      850 ETAINF(NX)=ETAINF(NX-2)+(XI(NX)-XI(NX-2))/(XI(NX-1)-XI(NX-2))*
          1(ETAINF(NX-1)-ETAINF(NX-2))
C ----
      1000 IF(NX.GT.1) NPPR=NP
      1010 IF(VGP.EQ.1.)GO TO 1020
          ARGLOG=1.+ETAINF(NX)/DETA1*(VGP-1.)
          DLOG1=ALOG(ARGLOG)
          ARGINT=1.+DLOG1/ALOG(VGP)
          NP= INT(ARGINT)+1
          GO TO 1050
      1020 ARGINT=ETAINF(NX)/DETA1+1.
          NP= INT(ARGINT)
      1050 NPM1=NP-1
          IF(NP.LE.100) GO TO 1060
          WRITE(6,9970) NX, NP
          LSP=1
          GO TO 1800
      1060 ETA(1)=0.
          DELETA(1)=DETA1
          M = 1
          M1 = M+1
          NP = M*(NP-1)+1
          NPM1 = NP-1
          DO 1080 J= M1,NP,M
              N = J-M+1
          ETA(J) = DETA1 + VGP*ETA(N-1)
          DELETA(J-1) = ETA(J) - ETA(N-1)

```

EINF 071
 EINF 072
 EINF 073
 EINF 074
 EINF 075
 EINF 076
 EINF 077
 EINF 078
 EINF 079
 EINF 080
 EINF 081
 EINF 082
 EINF 083
 EINF 084
 EINF 085
 EINF 086
 EINF 087
 EINF 088
 EINF 089
 EINF 090
 EINF 091
 EINF 092
 EINF 093
 EINF 094
 EINF 095
 EINF 096
 EINF 097
 EINF 098
 EINF 099
 EINF 100
 EINF 101
 EINF 102
 EINF 103
 EINF 104
 EINF 105

EINF

EINF

```

IF(M.EQ. 1) GO TO 1080
DELETE(J-1) = DELETE(J-1)/M
ETA(J-1) = ETA(J) - DELETE(J-1)
DELETE(J-2) = DELETE(J-1)
IF(M.EQ. 2) GO TO 1080
ETA(J-2) = ETA(J-1) - DELETE(J-2)
DELETE(J-3) = DELETE(J-1)
1080 CONTINUE
IF(VGP.NE.1.)ETAINF(NX)=ETA(NP)
TGNP=1
1800 RETURN
C ---
6010 FORMAT(1H ,/16X,10H* ETAE = ,F10.6)
9910 FORMAT(1H ,22H** ERROR AT FTAE(1) **)
9920 FORMAT(1H ,22H** ERROR AT ETAE(2) **)
9930 FORMAT(1H0,49H** WARNING - INPUT ETAE AT STATION IS TOO SMALL /
1 1H ,48H** CALCULATIONS CONTINUING WITH THE INPUT ETAINF )
9940 FORMAT(1H ,1X,39H**ERROR - FP PROFILE TS NEGATIVE AT I =, I3)
9970 FORMAT(1H ,1X,16H**ERROR - IMAX (, I3, 20H) EXCEEDS 100 -IMAX=,I3)
9980 FORMAT(1H ,38H** WARNING - ETAE IS BEING REESTIMATED )
C2000 CONTINUE
FND

```

EINF 106
EINF 107
EINF 108
EINF 109
EINF 110
EINF 111
EINF 112
EINF 113
EINF 114
EINF 115
EINF 116
EINF 117
EINF 118
EINF 119
EINF 120
EINF 121
EINF 122
EINF 123
EINF 124
EINF 125
EINF 126
EINF 127

EINF

IVPF

```

SURROUTINE IVPF
C **
C *** SURROUTINE IVPF
C THIS SUBROUTINE GENERATES THE INITIAL VELOCITY PROFILE
C
COMMON NX,NP,NPPR,JI,IT,NRVP,LSP,NPM1,J11,JIM1,NTC,NXT,NXM,NXM
1,TITLE(15)
COMMON/BLC1/F(100,2),U(100,2),V(100,2),ETA(100),DELETA(100)
COMMON/BLC3/XI(100),XS(100),ETAINF(100),BETA(100)
COMMON/BLC5/EM(100,2),EDV(100,2),E(100,2),EB(100,2),VPRT(100)
C
C
IF(IT.LE.1.AND.NX.EQ.1) E(1,1)=1.
F(1,2)=0.
U(1,2)=0.
C ---POLHAUSEN INITIAL VELOCITY PROFILE
VPGT=ETAINF(1)*BETA(1)/6.
V(1,2)=2./ETAINF(1)+VPGT
DO 50 J=2,NP
EDVE=ETA(J)/ETAINF(1)
EDVE2=EDVE*EDVE
EDVE3=EDVE2*EDVE
EDVE4=EDVE3*EDVE
FPGT=(.5-EDVE+.75*EDVE2-.2*EDVE3)*ETA(J)**2*ETAINF(1)*BETA(1)/6.
F(J,2)=EDVE2*ETAINF(1)*(1.-0.5*EDVE2+0.2*EDVE3)+FPGT
UPGT=EDVE*(1.-3.)*(EDVE-EDVE2)-EDVE3*ETAINF(1)**2*BETA(1)/6.
U(J,2)=2.*EDVE-2.*EDVE3+EDVE4+UPGT
VPGT=(1.-6.*EDVE+9.*EDVE2-4.*EDVE3)*ETAINF(1)*BETA(1)/6.
V(J,2)=2./ETAINF(1)*(1.-3.*EDVE2+.2*EDVE3)+VPGT
50 CONTINUE
1800 RETURN
END

```

IVPF 001
IVPF 002
IVPF 003
IVPF 004
IVPF 005
IVPF 006
IVPF 007
IVPF 008
IVPF 009
IVPF 010
IVPF 011
IVPF 012
IVPF 013
IVPF 014
IVPF 015
IVPF 016
IVPF 017
IVPF 018
IVPF 019
IVPF 020
IVPF 021
IVPF 022
IVPF 023
IVPF 024
IVPF 025
IVPF 026
IVPF 027
IVPF 028
IVPF 029
IVPF 030
IVPF 031
IVPF 032

IVPF

```

C
C * SURROUTINE FLPR
C * CALCULATE THE FLUID PROPERTIES AND THE TVC TERM
C
      SURROUTINE FLPR
      COMMON NX,NP,NPPR,JI,IT,NRVP,LSP,NPH1,JI1,JIM1,NTC,NXT,NXM,NXM
      1 TITLE(15)
      COMMON LG16,LG17,LG18,LG32,LG40
      1 ,IG0L,IG0T,IG0W,IG0N,IGCV,IGEG,IGNP,IGRC,IGTR
      COMMON/BLC1/F(100,2),U(100,2),V(100,2),ETA(100),DELETA(100)
      COMMON/BLC3/XI(100),XS(100),ETAINF(100),BETA(100)
      COMMON/BL12/YI,RMI,UI,RI,PR,PRT,FK,RL,RMUI,RHDI,PSI,HE
      1 ,UE(100),RO(100),TW(100),QW(100),RP(100),FW(100)
      2 ,BR(100),TE(100),RHOE(100),RMUE(100),GW(100),GPW(100)
      3 ,RF1(100),RF2(100),YS(100),IGX1(100),FPW(100),ROL(100)
      COMMON/BL19/C(100,2),G(100,2),GP(100,2),
      1 RHO(100),RMU(100),TVCT(100)
      C
      C
      C
      A1 = 0.
      IF(XI(NX) .GT. 0.) A1 = SQRT(2.*XI(NX))/( RHOI *UE(NX))
      C ----
      G(NP,2) = 1.0
      SUM = 0.
      F1 = RF1(NX)
      TVCT(1) = 1.0
      DO 500 I=2,NP
      IF(LG18.EQ. 0) GO TO 450
      F2 = RF1(NX)
      SUM = SUM + (F1+F2)/2.*DELETA(I-1)
      TVCT(I) = SQRT(1. + 2.*A1*SUM/(RL*ROL(NX)*ROL(NX)))
      F1 = F2
      GO TO 500
      C---- IF NO TVC THEN TVC = TERM = 1.0

```

```

FLPR 001
FLPR 002
FLPR 003
FLPR 004
FLPR 005
FLPR 006
FLPR 007
FLPR 008
FLPR 009
FLPR 010
FLPR 011
FLPR 012
FLPR 013
FLPR 014
FLPR 015
FLPR 016
FLPR 017
FLPR 018
FLPR 019
FLPR 020
FLPR 021
FLPR 022
FLPR 023
FLPR 024
FLPR 025
FLPR 026
FLPR 027
FLPR 028
FLPR 029
FLPR 030
FLPR 031
FLPR 032
FLPR 033
FLPR 034
FLPR 035

```

FLPR

FLPR 036
FLPR 037
FLPR 038
FLPR 039

450 TVCT(I) = 1.0
500 CONTINUE
1800 RETURN
FND

FLPR

300

```

GO TO 3000
C----- E P S F O R T U R B U L E N T F L O W S
600 SUM = 0.
    SUMT = 0.
    F1 = 1.0
    F3 = 0.
    DO 620 J=1,NP
        EM(J,2)=1.0
        EDV(J,2) = 0.
        IF(J.EQ. 1) GO TO 620
        F2 = (1.-U(J,2))/TVCT(J)
        F4 = F2*U(J,2)
        SUM = SUM + (F1+F2)/2.*DELETE(J=1)
        SUMT = SUMT + (F3+F4)/2.*DELETE(J=1)
        F1 = F2
        F3 = F4
620 CONTINUE
        RTHI = UE(NX)*(RHOI/RMUI ) * SUMT/TC
        IF(RTHI.LT. 425.) GO TO 720
        IF(RTHI.GT. 6000.) GO TO 750
        XPHI= RTHI/425.*1.0
        CPHI= .55*(1.-EXP(-.243*SQR(XPHI)*.298*XPHI))
        GO TO 770
720 CPHI = 0.0
        GO TO 770
750 CPHI=.55
770 DATAN=DATA1*(1.55/(1.+CPHI))
C-----
        IFLGED = 0
        IF(IT.LE. 1) E(1,2) = E(1,1)
        J = 1
        SUM1 = 0.
        F1=1.0
        VMPSRT = V(1,2)
        DUDYW = TC*UF(NX)*ABS(VMPSRT)

```

```

EDVS 036
EDVS 037
EDVS 038
EDVS 039
EDVS 040
EDVS 041
EDVS 042
EDVS 043
EDVS 044
EDVS 045
EDVS 046
EDVS 047
EDVS 048
EDVS 049
EDVS 050
EDVS 051
EDVS 052
EDVS 053
EDVS 054
EDVS 055
EDVS 056
EDVS 057
EDVS 058
EDVS 059
EDVS 060
EDVS 061
EDVS 062
EDVS 063
EDVS 064
EDVS 065
EDVS 066
EDVS 067
EDVS 068
EDVS 069
EDVS 070

```

```

1025 TAUW = RMUI      *DUDYW *E(1,2)
      USTAR = SQRT(TAUW/RHNI)
      DPOX = -TC*TC*UE(NX)*RMUI      *RETA(NX)
      PPLUS = -RMUI      *DPOX/(RHNI*RHNI      *USTAR*USTAR* USTAR)
      A = 26.
      ARMT = 1.-11.8*PPLUS
1030 CONTINUE
1045 APLUS = A/SQRT(ARMT)
      EDVN(J) = DATAN*UE(NX)*(RHNI/RMUI      ) * ABS(SUM/TC)
      VPRT(J) = PRT
      IF (IFLGED.EQ. 1) GO TO 1098
      F2 = 1./TVCT(J)
      IF(J.EQ. 1) GO TO 1060
      SUM1 = SUM1 + (F1+F2)/2.*DELETA(J-1)
      F1 = F2
1060 Y = SUM1 /TC
      IF(TVCT(J).GT. 1.005) Y = R0(NX)*ALOG(TVCT(J))
      YPLUS = Y*USTAR*RHNI/RMUI
      YA = YPLUS/APLUS
      EL = DATA2*Y
      IF(YA.LT. 20.) EL = EL *(1.-EXP(-YA))
      BPLUS = 34.
      IF(J.NE. 1) GO TO 1065
      VPRT(J) = DATA2/DATA4 * BPLUS/APLUS
      GO TO 1070
1065 VPRT(J) = EL/(DATA4*Y)
      YB = YA*APLUS/BPLUS
      IF(YB.LT. 20.) VPRT(J) = VPRT(J)/(1.-EXP(-YB))
      VWPST = V(J,2)
1070 DUDY = TC*UE(NX)*ARS(VWPST) / F2
      EDVI(J) = EL*EL*DUDY*RHNI/RMUI      * TVCT(J)
      IF(EDVI(J).LT. EDVU(J)) GO TO 1100
      IFLGED=1
      IF (J.LE. 2) WRITE(6,9030)
1098 EDV(J,2)=EDVN(J)

```

EDVS

```

      GO TO 1200
      EDV(J,2) = EDVI(J)
      J = J + 1
      IF (J .LE. NP) GO TO 1030
C-----
      IF (IFLGED.EQ.1) GO TO 2050
      WRITE(6,9020)
      EDV(J,2)=EDVN(J)
      2050 IF(LG17.EQ.0 .OR. IGTR.EQ.2) GO TO 2500
      UR = UE(NX)*RHOI/RMUI
      IF(NX .GT. NXT) GO TO 2150
      F1 = 0.
      SUMT = 0.
      DO 2100 J=2,NP
      F2 = U(J,2)*(1.-U(J,2))
      SUMT = SUMT + (F1+F2)*DELETA(J-1)*.5
      F1 = F2
      2100 CONTINUE
      RTHTR = UR*SUMT/TC
      IF(LG16 .NE. 0) GO TO 2300
      UEIN = 0.
      ROIN = 0.
      GO TO 2300
      2150 IF(IT .GT. 1) GO TO 2500
      UEIN = UFIN + .5*((1./UE(NX))+(1./UE(NX-1)))*(XS(NX)-XS(NX-1))
      IF(FK .EQ. 0.) GO TO 2200
      ROIN = ROIN + .5*((1./RO(NX))+(1./RO(NX-1)))*(XS(NX)-XS(NX-1))
      GO TO 2300
      2200 ROIN = XS(NX)-XS(NXT)
      2300 ATR = 60.
      GTR = ((UR/ATR)*.2)*UE(NX)/(RTHTR*.2.6A)
      ARFXP = GTR*UEIN*ROIN
      IF(FK .NE. 0.) AREXP = ARFXP*RO(NXT)
      IF(AREXP .GT. 10.) GO TO 2500
      GAMAT = 1. - EXP(-ARFXP)

```

EDVS 106
EDVS 107
EDVS 108
EDVS 109
EDVS 110
EDVS 111
EDVS 112
EDVS 113
EDVS 114
EDVS 115
EDVS 116
EDVS 117
EDVS 118
EDVS 119
EDVS 120
EDVS 121
EDVS 122
EDVS 123
EDVS 124
EDVS 125
EDVS 126
EDVS 127
EDVS 128
EDVS 129
EDVS 130
EDVS 131
EDVS 132
EDVS 133
EDVS 134
EDVS 135
EDVS 136
EDVS 137
EDVS 138
EDVS 139
EDVS 140

EDVS

EDVS

```

WRITE(6,9500) GAMAT
2500 DO 2550 J=1,NP
  IF(J.GT.1) GO TO 2510
  EDVM(1) = EDV(1,2)
  GO TO 2550
2510 IF(J.EQ.NP) GO TO 2520
  EDVM(J) = (EDV(J-1,2)+EDV(J,2)+EDV(J+1,2))/3.0
  GO TO 2550
2520 EDVM(NP) = (EDV(NP-2,2)+EDV(NP-1,2)+EDV(NP,2))/3.0
2550 CONTINUE
DO 2560 J=1,NP
  EDV(J,2)=EDVM(J)
  IF(LG17.EQ.0 .OR. IGTR.EQ.2) GO TO 2560
  EDV(J,2) = EDV(J,2)*GAMAT
2560 CONTINUE
3000 E(1,2)=(EM(1,2)+EDV(1,2))
DO 3010 J=2,NP
  E(J,2)=(EM(J,2)+EDV(J,2))
  E8(J-1,2) = 0.5* (E(J,2) + E(J-1,2))
  *TVCT(J)*TVCT(J)
3010 CONTINUE
1800 RETURN
C-----
9010 FORMAT(1H ,30X,43H**PLUS EXCEEDS THE LAMINARIZATION LIMIT **)
9020 FORMAT(1H ,30X,45H**NOTE - EPS DISTRIBUTION = EPS(INNER) ONLY**)
9030 FORMAT(1H ,30X,45H**NOTE - EPS DISTRIBUTION = EPS(OUTER) ONLY**)
9500 FORMAT(1H ,41X,11MGAMMA(TR) =, E17.6)
END

```

```

EDVS 141
EDVS 142
EDVS 143
EDVS 144
EDVS 145
EDVS 146
EDVS 147
EDVS 148
EDVS 149
EDVS 150
EDVS 151
EDVS 152
EDVS 153
EDVS 154
EDVS 155
EDVS 156
EDVS 157
EDVS 158
EDVS 159
EDVS 160
EDVS 161
EDVS 162
EDVS 163
EDVS 164
EDVS 165
EDVS 166
EDVS 167

```

EDVS

SHFT

```

C ** SUBROUTINE SHFT
C SUBROUTINE SHFT
C THIS SUBROUTINE PROVIDES THE INITIAL GUESSES FOR EACH STATION
C
COMMON NX,NP,NPPR,JI,IT,NRVP,LSP,NPM1,J11,J1M1,NTC,NXT,NXM,NXM
1 ,YTILE(15)
COMMON LG16,LG17,LG18,LG32,LG40
1 ,IGOL,IGOT,IGOW,IGON,IGCV,IGEG,IGNP,IGRC,IGTR
COMMON/BLC1/F(100,2),U(100,2),V(100,2),ETA(100),DELETA(100)
COMMON/BLC3/XI(100),XS(100),ETAINF(100),BETA(100)
COMMON/BLC5/EM(100,2),EDV(100,2),E(100,2),VPRT(100)
COMMON/BL19/C(100,2),G(100,2),GP(100,2),
1 RHO(100),RMU(100),TVCT(100)
COMMON/BL21/ A1(100,2),A2(100,2)
- - - - -
IF(IGRC.EQ.1) GO TO 200
JI1=JI+1
50 J1M1=JI-1
PHI=F(JI,2)-FTAINF(NX=1)
DO 70 J=1,JI
60 F(J,1)=F(J,2)
U(J,1)=U(J,2)
V(J,1)=V(J,2)
65 EDV(J,1)=EDV(J,2)
E(J,1)=E(J,2)
IF(J.EQ.JI) GO TO 70
ER(J,1)=EB(J,2)
70 CONTINUE
80 DO 90 J=JI1,NP
85 F(J,1)=PHI+ETA(J)
U(J,1)=1.
V(J,1)=0.
EDV(J,1)=EDV(JI,2)
SHFT 001
SHFT 002
SHFT 003
SHFT 004
SHFT 005
SHFT 006
SHFT 007
SHFT 008
SHFT 009
SHFT 010
SHFT 011
SHFT 012
SHFT 013
SHFT 014
SHFT 015
SHFT 016
SHFT 017
SHFT 018
SHFT 019
SHFT 020
SHFT 021
SHFT 022
SHFT 023
SHFT 024
SHFT 025
SHFT 026
SHFT 027
SHFT 028
SHFT 029
SHFT 030
SHFT 031
SHFT 032
SHFT 033
SHFT 034
SHFT 035

```

SHFT

SHFT

```

      E(J,1)=E(JI,2)
      F8(J-1,1)=E8(JIM1,2)
      90 CONTINUE
      IF(IGRC.EQ.0) GO TO 100
      IGRC=0
      GO TO 1800

C ----
      100 DO 120 J=JI, NP
          F(J,2)=PHI+ETA(J)
          U(J,2)=1.
          V(J,2)=0.
      120 CONTINUE
      IF(IGRC.EQ.1) GO TO 80
      GO TO 1800
      200 DO 220 J=1, JI
      210 F(J,2)=F(J,1)
          U(J,2)=U(J,1)
          V(J,2)=V(J,1)
      215 EDV(J,2)=EDV(J,1)
          F(J,2)=F(J,1)
          IF(J.EQ.JI) GO TO 220
          EB(J,2)=EB(J,1)
      220 CONTINUE
          PHI=F(JI,2)-ETAINF(NX=1)
          IF(IGTR.GT.1) PHI = F(JI,2)-ETAINF(NX)
          GO TO 100
      1800 RETURN
      END

```

```

SHFT 036
SHFT 037
SHFT 038
SHFT 039
SHFT 040
SHFT 041
SHFT 042
SHFT 043
SHFT 044
SHFT 045
SHFT 046
SHFT 047
SHFT 048
SHFT 049
SHFT 050
SHFT 051
SHFT 052
SHFT 053
SHFT 054
SHFT 055
SHFT 056
SHFT 057
SHFT 058
SHFT 059
SHFT 060
SHFT 061
SHFT 062
SHFT 063

```

SHFT


```

DO 320 J = 2, NP
  320 A(J) = DELETA(J-1) / 2.
C ----
DO 900 J = 2, NP
  FB = (F(J,2) + F(J-1,2)) * 0.5
  VB = (V(J,2) + V(J-1,2)) * 0.5
  IF (NX.GT. 1) GO TO 600
  CFB = 0.
  CUR = 0.
  CVB = 0.
  GO TO 700
600 CFB = (F(J,1) + F(J-1,1)) * 0.5
  CUR = (U(J,1) + U(J-1,1)) * 0.5
  CVB = (V(J,1) + V(J-1,1)) * 0.5
C ----
700 TM1 = A(J) / FB(J-1,2)
  A1(J) = TM1 * ((1. + CEL(NX)) * VB + CEL(NX) * CVB )
  R1(J) = 1. + TM1 * ((E (J,2)-E (J-1,2))/DELETA(J-1) + (1.
    1 + CEL(NX)) * FB - CEL(NX) * CFB )
C ----
IF (NX.EQ. 1) RB = 0.
IF (NX.GT. 1) RB = (EB(J-1,1) * ((V(J,1) - V(J-1,1)) / DELETA
  1 (J-1)) + ((E (J,1) - E (J-1,1)) / DELETA(J-1)) + CFB
  2 ) * CVB + BETA(NX-1) * 5
  3 - CEL(NX) * (CFB * CVB - CUB * CUB) + BETA(NX-1) * 5
  S(J) = V(J-1,2) - V(J,2) - DELETA(J-1) / EB(J-1,2) * ((1. + CEL(NX)
  1 ) * FB * VB - (BETA(NX) + CEL(NX)) * ((U(J,2) + U(J-1,2)) * 5) * 2
  2 - CEL(NX) * CFB * VB + BETA(NX) * 5
  3 + VB * (E(J,2) - E(J-1,2)) / DELETA(J-1) + BETA(NX) * 5)
  900 CONTINUE
C ----
905 D(2) = -.5 * (-A(2) / EB(1,2) * (BETA(NX) + CEL(NX)) + (U(2,2) + U(1,2))
  1 + A(2) * A1(2) + B1(2) / A(2))
  SE(2) = - A(2)
  G1(2) = - D(2) - 1. / A(2)

```



```

      DELF(1) = 0.
      DELV(1) = X(2) - D(2) * DELU(2)
      DELU(1) = 0.
C ----
      IF (IT.EQ. 1) WRITE (6, 9510)
      WRITE (6, 9521) IT, V(1,2), DELV(1)
C ----
      DO 1020 J=1,NP
      IF (J.EQ. NP) GO TO 1010
      U(J,2) = U(J,2) + DELU(J)
      1010 F(J,2) = F(J,2) + DELF(J)
      V(J,2) = V(J,2) + DELV(J)
      1020 CONTINUE
      DELV1 = DELV(1)
      1000 RETURN
C ----
      9510 FORMAT (1H0, 21X,1HY,20X,4HFPPW , 26X,5HDELVW )
      9521 FORMAT(1H ,20X,12,10X,E20.9,10X,E20.9)
      END

```

MOMX 106
 MOMX 107
 MOMX 108
 MOMX 109
 MOMX 110
 MOMX 111
 MOMX 112
 MOMX 113
 MOMX 114
 MOMX 115
 MOMX 116
 MOMX 117
 MOMX 118
 MOMX 119
 MOMX 120
 MOMX 121
 MOMX 122
 MOMX 123
 MOMX 124

MOMX


```

GO TO 57
55 RTH1P=AG1*THETA(NX)*ROL(NX)
S2=0.
DO 56 I=2,NX
  DELS3= XS(I)-XS(I-1)
56 S2=S2+(ROL(I)*2)*(DELS3)
  RX12=AG1*S2
57 CONTINUE
  IF(IGTR.NE.0) GO TO 60
  RX1=1.E-05 * RX12
  RTH1=RTH12
  IGTR=1
  GO TO 1800
60 RX2=1.E-05 * RX12
  RTH2=RTH12
  IF(RX2 .LT. 1.) GO TO 550
  RTHE9 = C1 + C2*RX2 + C6*SQRT(C3*RX2*RX2+C4*RX2+C5)
  RTD = RTHE9-RTH2
  IF(RTD.GT.0. .AND. RTD.GE.10.) GO TO 550
  IF(ARS(RTD) .GE. 10.) GO TO 65
  IGTR=3
  ROT1=0.
  ROT2=RX2
  GO TO 95
C ----
65 IGTR=3
  AG1=RTH2-((RTH2-RTH1)/(RX2-RX1))*RX2
  AG2=(RTH2-RTH1)/(RX2-RX1)
  AG3=AG2+3.357287
  AG4=AG1-66.4663
  C(1)=12.31885-AG3*AG3
  C(2)=48447.19-2.0*AG3*AG4
  C(3)=-19886.08-AG4*AG4
  RSM4AC = C(2)*C(2) - 4.*C(1)*C(3)
  IF(RSM4AC .GE. 0.) GO TO 70

```

TRNS

```

TRNS 036
TRNS 037
TRNS 038
TRNS 039
TRNS 040
TRNS 041
TRNS 042
TRNS 043
TRNS 044
TRNS 045
TRNS 046
TRNS 047
TRNS 048
TRNS 049
TRNS 050
TRNS 051
TRNS 052
TRNS 053
TRNS 054
TRNS 055
TRNS 056
TRNS 057
TRNS 058
TRNS 059
TRNS 060
TRNS 061
TRNS 062
TRNS 063
TRNS 064
TRNS 065
TRNS 066
TRNS 067
TRNS 068
TRNS 069
TRNS 070

```

TRNS

TRANS

```

WRITE(6,7000) NX
GO TO 550
70 ROT1 = (-C(2) + SQRT(BSM4AC))/(2.*C(1))
ROT2 = (-C(2) - SQRT(BSM4AC))/(2.*C(1))
IF(ROT1.LE.0.,AND.ROT2.LE.0.) GO TO 550
IF(ROT1.GT.0.,AND.ROT2.GT.0.) GO TO 80
IF(ROT1.GT.0.) RX=1.E05*ROT1
IF(ROT2.GT.0.) RX=1.E05*ROT2
GO TO 100
80 IIGR=1
RX=ROT1 * 1.E05
GO TO 100
90 IIGR=2
RX=ROT2 * 1.E05
C ----
GO TO 100
95 RX=1.E05*ROT2
XTR=XS(NX)
GO TO 200
100 UETR = UE(NX) + (UE(NX)-UE(K))*(1.E-05*RX-RX1)/(RX2-RX1)
XTR=RX*RMUI/(RHOI*UETR)
IF(XTR=XS(NX)) 300,200,500
200 WRITE(6,6010) NX
GO TO 700
300 IF(XTR.LE.XS(K)) GO TO 500
WRITE(6,6020) XTR
GO TO 1000
500 IF(IIGR.EQ.1) GO TO 90
550 IF(V(1,2).LE.0.) GO TO 600
IF(IGTR.EQ.0) GO TO 1800
RX1=RX2
RTH1=RTH2
CF0 = CF1
CFSUM0 = CFSUM
RETURN

```

TRANS 071
 TRANS 072
 TRANS 073
 TRANS 074
 TRANS 075
 TRANS 076
 TRANS 077
 TRANS 078
 TRANS 079
 TRANS 080
 TRANS 081
 TRANS 082
 TRANS 083
 TRANS 084
 TRANS 085
 TRANS 086
 TRANS 087
 TRANS 088
 TRANS 089
 TRANS 090
 TRANS 091
 TRANS 092
 TRANS 093
 TRANS 094
 TRANS 095
 TRANS 096
 TRANS 097
 TRANS 098
 TRANS 099
 TRANS 100
 TRANS 101
 TRANS 102
 TRANS 103
 TRANS 104
 TRANS 105

TRANS

TRNS

```

600 IGTR=2
    LG17 = 0
    IF(V(1,2).LT.0.) GO TO 800
    WRITE(6,6030) NX
700 NXT=NX
    WRITE(6,6050) NXT
    CF1 = CF0
    CFSUM = CFSUM0
    IF(LG17.EQ.0) GO TO 1800
    ROIN = 0.
    UEIN = 0.
    GO TO 1800
800 XTR=XS(NX)-(XS(NX)-XS(K))* V(1,2)/(V(1,2)-V(1,1) )
    WRITE(6,6040) XTR
C ----
1000 NXT=NX
    WRITE(6,6050) NXT
    CF1 = CF0
    CFSUM = CFSUM0
    IF(LG17.EQ.0) GO TO 1800
    ROIN = XS(NX) - XTR
    UEIN = ROIN/UE(NX)
    IF(FK.NE.0.) ROIN = ROIN/RO(NX)
1800 RETURN
C ----
6010 FORMAT(1H1////////// 30X,
1 34HTRANSITION HAS OCCURRED AT STATION, I3/)
6020 FORMAT(1H1////////// 30X,
1 30HTRANSITION HAS OCCURRED AT S =, F12.6 /)
6030 FORMAT(1H1////////// 45X,38HLAMINAR SEPARATION OCCURRED AT STATION, I3,
1 /)
6040 FORMAT(1H1////////// 45X,34HLAMINAR SEPARATION OCCURRED AT S =,F12.6)
6050 FORMAT(1H0,35X,33HTURBULENT FLOW STARTED WITH NTR = ,I3 ////)
7000 FORMAT(1H1////////40X,39HATTEMPT TO FIND X(1R) FAILED AT STATION ,I3/)
9010 FORMAT(1H ,24H** ERROR IN TRFLAG INPUT, /)

```

TRNS

TRNS 106
 TRNS 107
 TRNS 108
 TRNS 109
 TRNS 110
 TRNS 111
 TRNS 112
 TRNS 113
 TRNS 114
 TRNS 115
 TRNS 116
 TRNS 117
 TRNS 118
 TRNS 119
 TRNS 120
 TRNS 121
 TRNS 122
 TRNS 123
 TRNS 124
 TRNS 125
 TRNS 126
 TRNS 127
 TRNS 128
 TRNS 129
 TRNS 130
 TRNS 131
 TRNS 132
 TRNS 133
 TRNS 134
 TRNS 135
 TRNS 136
 TRNS 137
 TRNS 138
 TRNS 139
 TRNS 140

TRNS

TRNS 141C
TRNS 142

2000 CONTINUE
END

TRNS

SLOP

```

C
C  **  SURROUTINE SLOPE
C  COMPUTE THE DERIVATIVE DYDX FROM X VS Y INPUT
C
      SURROUTINE SLOPE(NPX,XC, YC,DYDX, MER)
      DIMENSION XC(150),YC(150),DYDX(150)
      DIMENSION X(300), Y(300), XY(301)
      XY(1) = NPX
      IF(MER .NE. 0) GO TO 20
      NP2M1 = NPX
      DO 10 I=1,NPX
        X(I) = XC(I)
        Y(I) = YC(I)
10    CONTINUE
      GO TO 40
20    NP2 = 2*NPX
      NP2M1 = NP2-1
      DO 40 I=1,NPX
        XY(I+2) = XC(I)
        XY(2*I+1) = YC(I)
40    CONTINUE
      NLQ = 2
      DO 50 I=2,NP2,2
        X(I-1) = XY(I)
        Y(I-1) = XY(I+1)
        IF(I .EQ. NP2) GO TO 50
        X(I) = (XY(I)+XY(I+2))*5
        CALL INSI(X(I),XY, Y(I),NLQ,MER)
50    CONTINUE
      DO 200 I=1,NP2M1
        IF(I .GT. 1) GO TO 100
        DYDX(I) = (Y(I+1)-Y(I)) / (X(I+1)-X(I))
        GO TO 200
100   IF(I .LT. NP2M1) GO TO 150
        DYDX(I) = (Y(I)-Y(I-1)) / (X(I)-X(I-1))

```

SLOP

SLOP 001
 SLOP 002
 SLOP 003
 SLOP 004
 SLOP 005
 SLOP 006
 SLOP 007
 SLOP 008
 SLOP 009
 SLOP 010
 SLOP 011
 SLOP 012
 SLOP 013
 SLOP 014
 SLOP 015
 SLOP 016
 SLOP 017
 SLOP 018
 SLOP 019
 SLOP 020
 SLOP 021
 SLOP 022
 SLOP 023
 SLOP 024
 SLOP 025
 SLOP 026
 SLOP 027
 SLOP 028
 SLOP 029
 SLOP 030
 SLOP 031
 SLOP 032
 SLOP 033
 SLOP 034
 SLOP 035

SLOP

```

GO TO 200
150 IF(V(I-1).EQ.V(I)).AND. V(I).EQ.V(I+1)) GO TO 180
A1 = (X(I)-X(I+1)) / ((X(I-1)-X(I))*(X(I-1)-X(I+1)))
A2 = (2.*X(I)-X(I+1)-X(I-1)) / ((X(I)-X(I-1))*(X(I)-X(I+1)))
A3 = (X(I)-X(I-1)) / ((X(I+1)-X(I-1))*(X(I+1)-X(I)))
DYDX(I) = A1*V(I-1) + A2*V(I) + A3*V(I+1)
GO TO 200
180 DYDX(I) = 0.
200 CONTINUE
IF(MER.EQ.0) RETURN
DO 300 I=1,NPX
300 DYDX(I) = DYDX(2*I-1)
RETURN
END

```

SLOP 036
SLOP 037
SLOP 038
SLOP 039
SLOP 040
SLOP 041
SLOP 042
SLOP 043
SLOP 044
SLOP 045
SLOP 046
SLOP 047
SLOP 048
SLOP 049

SLOP

copy

```

DELS(NX) = 0.
RX(NX)=XS(NX)*RH0J*UE(NX)/RMUI
RTHETA = 0.
H=0.
CF(NX) = 0.
USTUF = 0.
YPLUS = 0.
UPLUS = 0.
IF(NX.EQ. 1) CF1 = 0.
IF(NX.EQ. 1) CFSUM = 0.
CFA(NX) = 0.
ST(NX) = 0.
TNP(NX)=NP
FTA(NX) = ETA(NP)
FPPW(NX) = V(1,2)

C-----
IF(XI(NX).EQ. 0.) GO TO 300
A1 = SQRT(2.*XI(NX))/( RHUI *UF(NX)*ROL(NX))
JINP = NP
SUM1=0.0
SUM2 = 0.
F1=0.
F3=1.0
DO 90 J=2,JINP
F2 = U(J,2)*(1.0-U(J,2))
SUM1 = SUM1 + (F1+F2)/2.*DFLETA(J-1)
F1=F2
90 CONTINUE
THETA(NX) = SUM1*A1
DELS(NX) = A1*(ETA(NX) + F(1,2) - F(JINP,2))
RTHETA = RX(NX)*THETA(NX)/XS(NX)
H = DELS(NX)/THETA(NX)
CF(NX) = SQRT(2./XI(NX))* RMUI *V(1,2)*ROL(NX)
CF(NX) = ABS(CF(NX))
USTUF = SQRT(CF(NX)/2.)

```

DTPT 036
DTPT 037
DTPT 038
DTPT 039
DTPT 040
DTPT 041
DTPT 042
DTPT 043
DTPT 044
DTPT 045
DTPT 046
DTPT 047
DTPT 048
DTPT 049
DTPT 050
DTPT 051
DTPT 052
DTPT 053
DTPT 054
DTPT 055
DTPT 056
DTPT 057
DTPT 058
DTPT 059
DTPT 060
DTPT 061
DTPT 062
DTPT 063
DTPT 064
DTPT 065
DTPT 066
DTPT 067
DTPT 068
DTPT 069
DTPT 070

*F(1,2)

OTPT

```

IF(FK .GE. 1.0) GO TO 200
IF(NX .EQ. 1) CF1 = CF(NX)*UEUI*UEUT
IF(NX .EQ. 1) GO TO 300
CF2 = CF(NX) *UEUI*UEUT
CFSUM = CFSUM + (CF1+CF2)*(YS(NX)-YS(NX-1))**.5
IF(XI(NX-1) .EQ. 0.) CFSUM = 2.*THETA(NX)
CFA(NX) = CFSUM / (YS(NX)-YS(1))
CF1 = CF2
GO TO 300
200 CONTINUE
IF(NX .EQ. 1) CF1=CF(NX)*UEUI*UEUI*R0(NX)
IF(NX .EQ. 1) GO TO 300
CF2=CF(NX)*UEUI*UEUI*R0(NX)
CFSUM=CFSUM + (CF1+CF2) * (YS(NX)-YS(NX-1))**.5*RL
IF(XI(NX-1) .EQ. 0.) CFSUM=2.*THETA(NX)
CFA(NX)=CFSUM * 2. / (R0MAX*R0MAX)
CF1=CF2
300 IF(LG32.EQ.1 .AND. IGX1(NX).EQ.0) GO TO 420
LCMAX=42
LC=60
SUMY = 0.
F1=1.0
DO 400 J=1,NP
IF(LC .LT. LCMAX) GO TO 340
LC=1
CALL HEAD
WRITE(6,200)NX,YS(NX)
IF((LG32.EQ.0.OR.IGX1(NX).NE.0))
IF(LG32.EQ. 2) WRITE(6,2150)
340 IF(J.EQ. 1) GO TO 350
F2=1./TVCT(J)
SUMY = SUMY + (F1+F2)/2.*DFLETA(J-1)
F1 = F2
350 I = 1 + ((J-1)/IPRT)*IPRT
IF(J.NF.I .AND. J.NE.NP) GO TO 400

```

WRITE(6,2100)

OTPT

OTPT

```

Y(J) = SUMY*A1
IF(USTUE.EQ. 0.) GO TO 370
YPLUS = Y(J)*UE(NX)*RHDE(NX)*USTUE/RMUF(NX)
UPLUS = U(J,2)/USTUE
LC=LC+1
370 WRITE(6,6060)
1 J,ETA(J),F(J,2),U(J,2),V(J,2),Y(J),YPLUS,UPLUS,FDV(J,2)
400 CONTINUE
420 CONTINUE
C-----
C -----
700 IF(LG32.EQ.1 .AND. IGX1(NX).EQ.0) GO TO 800
WRITE(6,3000)
WRITE(6,3200) NX,XS(NX), ITHETA(NX), DELS(NX),CF(NX),V(1,2),GW(NX)
WRITE(6,3250) YS(NX), RX(NX),RTHETA, H, CFA(NX),GPW(NX),ST(NX)
800 IF(IOUT.EQ. 0) GO TO 1800
C-----
900 CALL HEAD
WRITE(6,3500) TITLE
LCMAX=45
LC=1
WRITE(6,4000)
IF(LSP.EQ. 1 .AND. NX.GT. 1) NX=NX-1
DO 1000 I=1,NX
IF(LC.LT. LCMAX) GO TO 940
CALL HEAD
WRITE(6,4000)
LC=1
940 RTHETA=0.
H=0.
IF(XI(I).EQ. 0.) GO TO 950
RTHETA = RX(I)*ITHETA(I)/XS(I)
H = DELS(I)/THETA(I)
950 WRITE(6,4200) I,XS(I),THETA(I),DELS(I),CF(I),FPPW(I),GW(I),INP(I)
WRITE(6,4250) YS(I), RX(I),RTHETA, H, CFA(I),GPW(I),ST(I),ETA(I)

```

OTPT

OTPT

```

LC=LC+3
1000 CONTINUE
DO 1003 I=1,NX
1003 DELS(I)=DELS(I)/RL
WRITE(2) NX
WRITE(2) (DELS(K), K=1,NX)
C THE CALCULATION OF THE BASE DRAG IS DONE AT THIS POINT USING
C A METHOD GIVEN IN HOERNERS= BOOK ON AERODYNAMIC DRAG
IF(R0(NX) .LT. R0MAX) GO TO 1010
CDRASE=.029/SQRT(CFA(NX))
GO TO 1020
1010 CFA=CFAC(NX)
CDBASE=.029*(R0(NX)/R0MAX)**3/SQRT(CFAB)
1020 WRITE(6,1030) CDBASE
1030 FORMAT(1H0, 77M THE BASE DRAG FOR THIS CONFIGURATION BASED ON THE
1 MAXIMUM FRONTAL AREA IS = , F15,A)
1000 RETURN
C - - -
2000 FORMAT(1H ,3X,11MSTATION NO.,13,30X, 5HS/C =,F12.6 /)
2100 FORMAT(1H0,2X,1HI,7X,3META,11X,1HF,14X,2HFP,14X,3HFPP,14X,1HY,14X,
1 SHYPLUS,12X,SHUPLUS,12X, 4HEPS+ /)
2150 FORMAT(1H0,2X,1HI,7X,3META,11X,1HF,14X,2HFP,14X,3HFPP,11X,
1 7HY/TMETA,9X,5HYPLUS,12X,SHUPLUS,12X,4HEPS+, /)
2200 FORMAT(1H0,2X,1HI,7X,3META,11X,1HF,14X,2HFP,14X,3HFPP,14X,1HY,12X,
1 4HW/WE,12X,5H WP ,12X,4HEPS+, /)
2300 FORMAT(1H0,2X,1HI,7X,3META,11X,1HG,14X,2HGP,14X,2H Y,13X,4H T ,
1 14X,4H PRT,12X,2HMMU,14X,2HM , /)
2400 FORMAT(1H0,2X,1HI,7X,3META,11X,1HG,14X,2HGP,11X,7HY/TMETA, 10X,
1 4HT/TE,11X,10H PRT ,8X, 6HMMU/MUE,10X, 4HM/ME, /)
3000 FORMAT(1H0// 7X, 1HN, 12X,4H S ,13X,5HTMETA,12X,4HDELS,14X,2HCF,
1 14X,4HFPPW,14X,2HGW, /1H ,5X, 3HX/C,12X,2HRX,13X,6HRTMETA,14X
2 ,1HH,15X,3HCFA,14X,3HGPW, 14X, 2HST, /)
3200 FORMAT(1H /1H ,17,4X, 6E17.6 )
3250 FORMAT(1H ,F11.5,6E17.6 )
3500 FORMAT(1H ,42X,14HOUTPUT SUMMARY,15A4/ )

```

OTPT

OTPT 141
OTPT 142
OTPT 143
OTPT 144
OTPT 145
OTPT 146
OTPT 147
OTPT 148
OTPT 149
OTPT 150
OTPT 151
OTPT 152
OTPT 153
OTPT 154
OTPT 155
OTPT 156
OTPT 157
OTPT 158
OTPT 159
OTPT 160
OTPT 161
OTPT 162
OTPT 163
OTPT 164
OTPT 165
OTPT 166
OTPT 167
OTPT 168
OTPT 169
OTPT 170
OTPT 171
OTPT 172
OTPT 173
OTPT 174
OTPT 175

OTPT

```
4000 FORMAT(1H0/ 7X,1HN,12X,4H S ,15X,5HTHETA,12X,4HDELS,14X,2HCF,14X,  
1 4HPPW,14X,2HGW,15X,4HIMAX,/1H ,5X,3HX/C,12X,2HRX,13X,  
2 6HRTHTA,14X,1HH,15X,3HCFA,14X,3HGPW,14X,2HST,14X,6HETATNF,/)
4200 FORMAT(1H /1H ,17,4X, 6E17.6, 8X, 14)
4250 FORMAT(1H ,F11.6,6E17.6, 4X, F11.6)
6060 FORMAT(1H ,I3,2X,F10.6, 7E16.6 )
9000 CONTINUE
      END
```

OTPT 176
OTPT 177
OTPT 178
OTPT 179
OTPT 180
OTPT 181
OTPT 182C
OTPT 183

OTPT


```

C
C **
C
      SUBROUTINE HFAD
      SUBROUTINE HFAD
      COMMON /HEAD/ CASF, IPAGE
      WRITE (6,100) CASE
      IPAGE = IPAGE + 1
      RETURN
100 FORMAT(1H1,/1H ,2X,6H CASE ,A4,21X,51H***** CEBECI-KELLER BOUNDAR
      1Y LAYER PROGRAM ***** 23X , 13HPROGRAM K99A )
      END

```

HEAD

```

HEAD 001
HEAD 002
HEAD 003
HEAD 004
HEAD 005
HEAD 006
HEAD 007
HEAD 008
HEAD 009
HEAD 010
HEAD 011

```

HEAD

SMOT

```

OVERLAY(AXSY,6,0)
PROGRAM SMOOTH
SUBROUTINE SMOOTH
*****
THIS SUBROUTINE CONTROLS THE SMOOTHING OF THE INPUT COORDINATES
*****
DIMENSION X(100),Y(100),XU(100),YU(100)
REWIND 1
REWIND 10
READ(5,1) NPTS , ITAPE
IF(ITAPE .NE. 0) GO TO 5
READ(5,2) (X(I),I=1,NPTS)
READ(5,2) (Y(I),I=1,NPTS)
GO TO 7
5 READ(1) (X(I),I=1,NPTS)
7 READ(1) (Y(I),I=1,NPTS)
7 CONTINUE
CALL SM5PT(X,Y,XU,YU,NPTS)
WRITE(10,10) (XU(I),I=1,NPTS)
WRITE(10,10) (YU(I),I=1,NPTS)
REWIND 10
1 FORMAT(2I4)
2 FORMAT(6F10,0)
10 FORMAT(6F10,6)
C RETURN
20 CONTINUE
END

```

```

SMOT 001C
SMOT 002C
SMOT 003I
SMOT 004
SMOT 005
SMOT 006
SMOT 007
SMOT 008
SMOT 009
SMOT 010
SMOT 011
SMOT 012
SMOT 013
SMOT 014
SMOT 015
SMOT 016
SMOT 017
SMOT 018
SMOT 019
SMOT 020
SMOT 021
SMOT 022
SMOT 023
SMOT 024
SMOT 025I
SMOT 026C
SMOT 027

```

SMOT

```

C      SUBROUTINE SMSPT (XI,YI,XO,YO,N)
C      THIS ROUTINE USES THE OPTIMUM 5 POINT SMOOTHING METHOD.  A 3 POINT
C      METHOD IS USED AT THE END POINTS.
C
C      DIMENSION XI(1),YI(1),XO(1),YO(1)
C
C      J = 2
C      I = -1
10  XO(J+I) = XI(J+I)
   YO(J+I) = YI(J+I)
   XO(J) = 0.25*(XI(J-1) + 2.0*XI(J) + XI(J+1))
   YO(J) = 0.25*(YI(J-1) + 2.0*YI(J) + YI(J+1))
   IF (I.EQ. 1) GO TO 20
   J = N-1
   I = 1
   GO TO 10
C
20  CONTINUE
   N2 = N - 2
   DO 30 J=3,N2
   XO(J) = (-XI(J-2)+4.0*XI(J-1)+10.0*XI(J)+4.0*XI(J+1)+XI(J+2))*
1     0.0625
30  YO(J) = (-YI(J-2)+4.0*YI(J-1)+10.0*YI(J)+4.0*YI(J+1)+YI(J+2))*
1     0.0625
C
   RETURN
   END

```

```

SMSPT 001
SMSPT 002
SMSPT 003
SMSPT 004
SMSPT 005
SMSPT 006
SMSPT 007
SMSPT 008
SMSPT 009
SMSPT 010
SMSPT 011
SMSPT 012
SMSPT 013
SMSPT 014
SMSPT 015
SMSPT 016
SMSPT 017
SMSPT 018
SMSPT 019
SMSPT 020
SMSPT 021
SMSPT 022
SMSPT 023
SMSPT 024
SMSPT 025
SMSPT 026
SMSPT 027
SMSPT 028
SMSPT 029

```

SMSPT

ITRT

```

OVERLAY(AXSY,7,0)
PROGRAM TIFRAT
SURROUTINE ITERAT
DIMENSION S(100),DELLS(100),X(100),Y(100),SURF(100),SINAL(100),
1 COSAL(100),SMD(100),DFLSTR(201),TSINAL(201),TCOSAL(201),
2 XNEW(100),YNEW(100),DESU(100)
REWIND 15
REWIND 2
SURFACE DISTANCES FROM BOUNDARY LAYER INPUT
READ(2) N
READ(2) (S(I),I=1,N)
BOUNDARY LAYER DISPLACEMENT THICKNESS
READ(2) NN
READ(2) (DELLS(I),I=1,NN)
THIS DO LOOP IS USED IN CASE THE BOUNDARY LAYER DOES NOT
CALCULATE A COMPLETE BOUNDARY DISPLACEMENT THICKNESS ARRAY
DUE TO TURBUENT BOUNDARY LAYER SEPARATION
DO 10 I=NN,N
10 DELLS(I) = DELLS(NN)
THE COORDINATES OF THE TRANSFORMED BODY ARE READ IN AT THIS POINT
READ(15) NTS
READ(15) (X(I),I=1,NTS)
READ(15) (Y(I),I=1,NTS)
THE SURFACE DISTANCE OF THE INPUT BODY COORDINATES ARE CALCULATED
SURF(1)=0,0
DO 30 I=2,NTS
DESURF=SQRT((X(I)-X(I-1))**2+(Y(I)-Y(I-1))**2)
30 SURF(I)=DESURF+SURF(I-1)
S(N)=SURF(NTS)
NOTE S(I) IS SURFACE DISTANCE FROM LEADING EDGE TO TRAILING EDGE
BASED ON COORDINATES ASSOCIATED WITH THE BOUNDARY LAYER SOLUTION
SURF(I) IS SURFACE DISTANCE FROM LEADING EDGE TO TRAILING FDGE
BASED ON THE X AND Y COORDINATES OF THE TRANSFORMED ORIGINAL
BODY AT WHICH THE VALUE OF DISPAACEMENT THICKNESS IS TO BE ADDED
NEXT THE COSINE AND SIN OF THE LOCAL SURFACE ANGLES

```

ITRT 001C
ITRT 002C
ITRT 0031
ITRT 004
ITRT 005
ITRT 006
ITRT 007
ITRT 008
ITRT 009
ITRT 010
ITRT 011
ITRT 012
ITRT 013
ITRT 014
ITRT 015
ITRT 016
ITRT 017
ITRT 018
ITRT 019
ITRT 020
ITRT 021
ITRT 022
ITRT 023
ITRT 024
ITRT 025
ITRT 026
ITRT 027
ITRT 028
ITRT 029
ITRT 030
ITRT 031
ITRT 032
ITRT 033
ITRT 034
ITRT 035

ITRT

ITRT

```

C ARE FOUND AT THE MIDPOINTS OF THE X AND Y COORDINATES
NTSM=NTS-1
NTSM=NTS+1
DO 40 I=1,NTSM
  DESU(I)=SQRT((X(I+1)-X(I))**2+(Y(I+1)-Y(I))**2)
  SINAL(I+1) = (Y(I+1)-Y(I))/DESU(I)
  COSAL(I+1) = (X(I+1)-X(I))/DESU(I)
40 SINAL(1) = SINAL(2)
   COSAL(1) = COSAL(2)
  SINAL(NTSM)=SINAL(NTS)
  COSAL(NTSM)=COSAL(NTS)
C THE SURFACE DISTANCE CORRESPONDING TO EACH OF THESE SIN AND COSINE
C PAIRS ARE CALCULATED HERE
SMD(1)=0.0
SMD(2)=.5*SURF(2)
DO 50 I=2,NTSM
  SMD(I+1) = SMD(I)+.5*(SURF(I+1)-SURF(I-1))
  SMD(NTSM)=SMD(NTS)+.5*(SURF(NTS)-SURF(NTSM))
C DISPLACEMENT THICKNESS AT THE VALUES OF S AND Y ARE FOUND HERE
CALL TABLE1(N,S,DELS,DELSB)
CALL TABLE1(NTSM,SMD,SINAL,TSINAL)
CALL TABLE1(NTSM,SMD,COSAL,TCOSAL)
C NEW COORDINATES ARE FORMED HERE
DO 60 I=1,NTS
  SURFF=SURF(I)
  CALL INS1(SURFF,DELSR,DELS,1,NER)
  CALL INS1(SURFF,TSINAL,SINU,1,NER)
  CALL INS1(SURFF,TCOSAL,COSU,1,NER)
  XNFW(I)=X(I)-DELS* SINU
  YNFW(I)=Y(I)+DELS* COSU
  XNFW(1) = X(1) - DELS(2)
60 IF SEPARATION HAS OCCURRED, THE BODY IS MODIFIED TO ACCOUNT
C FOR THIS BY ADDING A CIRCULAR RADIUS TO CREATE A SEPARATION BUBBLE
IF(NN.EQ. N) GO TO 80
XNFW1=XNFW(NN-3)

```

ITRT

```

ITRT 036
ITRT 037
ITRT 038
ITRT 039
ITRT 040
ITRT 041
ITRT 042
ITRT 043
ITRT 044
ITRT 045
ITRT 046
ITRT 047
ITRT 048
ITRT 049
ITRT 050
ITRT 051
ITRT 052
ITRT 053
ITRT 054
ITRT 055
ITRT 056
ITRT 057
ITRT 058
ITRT 059
ITRT 060
ITRT 061
ITRT 062
ITRT 063
ITRT 064
ITRT 065
ITRT 066
ITRT 067
ITRT 068
ITRT 069
ITRT 070

```

ITRT

```

XNEW2=XNEW(NN-2)
XNEW3=XNEW(NN-1)
YNEW1=YNEW(NN-3)
YNEW2=YNEW(NN-2)
YNEW3=YNEW(NN-1)
CALL CIRCLE(XNEW1,XNEW2,XNEW3,YNEW1,YNEW2,YNEW3,RADIUS,XCENT,
1 YCENT,DYDX)
NNN=NN-1
DO 70 I=NN,NTS
DELTA=X(I)-XCENT
IF(DELTA,GE,0.) KM=1
IF(DELTA,GE,0.) GO TO 90
YCIR=(RADIUS**2-DELTA**2)
IF(DYDX,GE,0.) GO TO 65
YNEW(I)=YCENT-SQRT(YCIR)
GO TO 70
65 YNEW(I)=YCENT+SQRT(YCIR)
70 CONTINUE
GO TO 80
90 CONTINUE
DO 100 I=KM,NTS
YNEW(I)=YNEW(KM-1)
80 CONTINUE
C IF THE BODY RADIUS BECOMES EQUAL TO THE DISPLACEMENT THICKNESS AT
C SOME POINT THEN THE NEW BODY IS MODIFIED TO KEEP THE SAME AREA
C DUE TO THE DISPLACEMENT THICKNESS
NXSL=NTS/2
DO 105 K=NXSL,NTS
DYNEW=YNEW(K)-Y(K)
IF(DYNEW,GE,Y(K)) KSL=K-2
IF(DYNEW,GE,Y(K)) GO TO 110
105 CONTINUE
GO TO 115
110 DAREA=3.14159*(YNEW(KSL)**2-Y(KSL)**2)
DO 112 I=KSL,NTS

```

```

ITRT 071
ITRT 072
ITRT 073
ITRT 074
ITRT 075
ITRT 076
ITRT 077
ITRT 078
ITRT 079
ITRT 080
ITRT 081
ITRT 082
ITRT 083
ITRT 084
ITRT 085
ITRT 086
ITRT 087
ITRT 088
ITRT 089
ITRT 090
ITRT 091
ITRT 092
ITRT 093
ITRT 094
ITRT 095
ITRT 096
ITRT 097
ITRT 098
ITRT 099
ITRT 100
ITRT 101
ITRT 102
ITRT 103
ITRT 104
ITRT 105

```

ITRT

ITRT

```

      ARFA=3.14159*Y(I)*Y(I)+DARFA
112 YNFW(I)=SQRT(ARFA/3.14159)
115 WRITE(6,4)
      WRITE(6,5) (XNEW(I),YNEW(I),I=1,NTS)
      XNFW AND YNFW ARE THE VISCOS COORDINATES WHICH SHOULD BE WRITTEN
      ON TAPE AND TRANSFERRED TO THE SMOOTHING ROUTINE
      REWIND 1
      WRITE(1) (XNFW(I),I=1,NTS)
      WRITE(1) (YNEW(I),I=1,NTS)
      4 FORMAT(1H,10X,4HXNEW,20X,4HYNFW)
      5 FORMAT(2F20,8)
      RETURN
      END

```

```

ITRT 106
ITRT 107
ITRT 108
ITRT 109
ITRT 110
ITRT 111
ITRT 112
ITRT 113
ITRT 114
ITRT 115
ITRT 116
ITRT 117
ITRT 118

```

ITRT

TAB1

```

SUBROUTINE TAB1(N,X,Y,TAB1)
  DIMENSION X(100),Y(100),TAB1(201)
  THIS ROUTINE SFTS UP TABLES FOR INPUT TO SUBROUTINE INS1
  N IS THE NUMBER OF VALUES OF X AND Y TO BE PUT INTO ARRAYS
  J=2
  DO 200 I=1,N
    TAB1(J)=X(I)
    TAB1(J+1) = Y(I)
    J=J+2
  200 CONTINUE
  TAB1(1)=N
  RETURN
  END

```

TAB1 001
 TAB1 002
 TAB1 003
 TAB1 004
 TAB1 005
 TAB1 006
 TAB1 007
 TAB1 008
 TAB1 009
 TAB1 010
 TAB1 011
 TAB1 012
 TAB1 013

TAB1


```

SURROUTINE CIRCLE (X1,X2,X3,Y1,Y2,Y3,R,XCENT,YCENT,OYDX)
  XY1=(X1*X1+Y1*Y1)
  XY2=(X2*X2+Y2*Y2)
  XY3=(X3*X3+Y3*Y3)
  E1=(XY1-XY2)*(X2-X3)-(XY2-XY3)*(X1-X2)
  E2=(Y1-Y2)*(X2-X3)-(Y2-Y3)*(X1-X2)
  E=E1/E2
  CENTK=E/2.
  D=((XY2-XY3)-E*(Y2-Y3))/(X2-X3)
  H=D/2.
  F=XY1-D*X1-E*Y1
  R=SQRT(H*H+CENK**2-F)
  OYDX=((X3-H)/(Y3-CENK)
  C=1./R
  DYDXS=DYDX*DYDX
  CC=C*(1.+DYDXS)**1.5
  CC=ABS(CC)
  DDYDX=ABS(DYDX)
  PHI=ATAN(DDYDX)
  IF(DYDX.GE.0.) GO TO 20
  XCENT=X3+R*SIN(PHI)
  YCENT=Y3+R*COS(PHI)
  GO TO 30
20 XCENT=X3+R*STN(PHI)
   YCENT=Y3-R*COS(PHI)
30 CONTINUE
   RETURN
   END

```

```

CIRC 001
CIRC 002
CIRC 003
CIRC 004
CIRC 005
CIRC 006
CIRC 007
CIRC 008
CIRC 009
CIRC 010
CIRC 011
CIRC 012
CIRC 013
CIRC 014
CIRC 015
CIRC 016
CIRC 017
CIRC 018
CIRC 019
CIRC 020
CIRC 021
CIRC 022
CIRC 023
CIRC 024
CIRC 025
CIRC 026
CIRC 027
CIRC 028

```

REFERENCES

1. Thwaites, B.: Incompressible Aerodynamics. Oxford at the Clarendon Press, p. 62, 1960.
2. Callaghan, J. G. and Beatty, T. D.: A Theoretical Method for the Analysis and Design of Multi-element Airfoils. Journal of Aircraft Volume 9, No. 12, December 1972.
3. Stevens, W. A.; Goradia, S. H.; and Braden, J. A.: Mathematical Model for Two-Dimensional Multi-Component Airfoils in Viscous Flow, NASA CR-1843, July 1971.
4. Bhateley, I. C. and McWhirter, J. W.: Development of Theoretical Method for Two-Dimensional Multi-element Airfoil Analysis and Design. Air Force Flight Dynamics Laboratory, TR-72-96, Part I, August 1972.
5. Hess, J. L.: Calculation of Potential Flow about Arbitrary Three-Dimensional Lifting Bodies. McDonnell Douglas Report No. MDC J5679-01, done under Contract No. N00019-71-C-0524 for Naval Air Systems Command.
6. Hess, J. L. and Smith, A. M. O.: Calculation of Potential Flow about Arbitrary Bodies. Progress in Aeronautical Sciences, Volume 8, Pergamon Press, New York, 1966.
7. Smith, A. M. O. and Pierce, J.: Exact Solution of the Neumann Problem. Calculation of Plane and Axially Symmetric Flows about or within Arbitrary Boundaries. Douglas Aircraft Company Report No. 26988, April 1958. (A brief summary is contained in the proceedings of the third U.S. National Congress of Applied Mechanics, Brown University, 1958).
8. Cebeci, T. and Smith, A. M. O.: A Finite-Difference Solution of the Incompressible Turbulent Boundary Layer Equations by an Eddy-Viscosity Concept. Computation of Turbulent Boundary Layers, AFOSR-IFP Stanford Conference, Volume 1, Stanford University Press, Stanford, California, 1968, pp. 346-356.
9. Faulkner, S.; Hess, J. L.; and Giesing, J. P.: Comparison of Experimental Pressure Distributions with those Calculated by the Neumann Program. Douglas Aircraft Company Report LB 31831, December 1964.

10. Bauer, A. B.; Smith, A. M. O.; and Hess, J. L.: Potential Flow and Boundary Layer Theory as Design Tools in Aerodynamics. Canadian Aeronautics and Space Journal, Volume 16, No. 2, February 1970.
11. Hess, J. L.: Numerical Solution of the Integral Equation for the Neumann Problem with Application to Aircraft and Ships. Presented to Symposium on Numerical Solution of Integral Equations with Physical Applications. SIAM Meeting, October 11, 12, 13, 1971, University of Wisconsin, Madison, Wisconsin, Douglas Engineering Paper 5987.
12. Hess, J. L.: Calculation of Potential Flow about Bodies of Revolution Having Axes Perpendicular to the Freestream Direction. Douglas Aircraft Company Report No. ES 29812, October 1, 1960.
13. Hess, J. L.: Extension of the Douglas-Neumann Program for Axisymmetric Bodies to Include Calculation of Potential, Non-uniform Cross Flow, Added Mass, and Conductor Problems. Douglas Aircraft Company Report No. 31765, September 1, 1964. This work performed for Naval Ordnance Test Station, Pasadena Annex under Contract No. N60530-10053.
14. Hess, J. L.: Extension of the Douglas Axisymmetric Potential Flow Program to Include the Effects of Ring Vorticity with Application to the Program of Specified Tangential Velocity. Douglas Aircraft Company Report No. 33195, June 10, 1966. This work performed for Naval Ordnance Test Station, Pasadena Annex under Contract No. N60530-11208.
15. Hess, J. L.: Improved Ring-Source Formulas for Small Values of Distance from the Symmetry Axis. A Modification of the Douglas-Neumann Program for Axisymmetric Bodies. Douglas Aircraft Company Report No. 70002, August 1969.
16. Hess, J. L.: Modification of the Douglas-Neumann Program for Axisymmetric Bodies to Include the Dirichlet Problem for a Potential that Varies as the Cosine of Twice the Circumferential Angle. Douglas Aircraft Company Report No. 70001, August 1969. This work performed under Air Force Contract AF0(694)-953 on the Reentry Systems Environment Protection Program.

17. Hess, J. L. and Schoor, C.: Extension of the Douglas-Neumann Axisymmetric Potential Flow Program to the Problem of a Ring Wing Having a Known Ring Vortex Wake Issuing from its Trailing Edge. McDonnell Douglas Report No. MDC J0741/01, April 25, 1970. This work performed for Naval Undersea Research and Development Center under Contract No. N66001-70-C-0436.
18. Probstein, R. F. and Elliott, D.: The Transverse Curvature Effect in Compressible Axially Symmetric Laminar-Boundary-Layer Flow. Journal of Aeronautical Sciences, March 1956.
19. Hartree, D. R. and Womersley, J. R.: A Method for the Numerical or Mechanical Solution of Certain Types of Partial Differential Equations. Procedure Royal Society Series A, Volume 161, No. 906, p. 353, August 1937.
20. Keller, H. B.: A New Difference Scheme for Parabolic Problems in "Numerical Solution of Partial Differential Equations." Volume II, Academic Press, New York, 1970.
21. Keller, H. B.; and Cebeci, T.: Simple Accurate Numerical Methods for Boundary Layers. I. Two-Dimensional Laminar Flows. Proceedings of the Second International Conference on Numerical Methods in Fluid Dynamics. Lecture Notes in Physics, Volume 8, Springer-Verlag, New York, 1971.
22. Keller, H. B.; and Cebeci, T.: Simple Accurate Numerical Methods for Boundary Layers. II. Two-Dimensional Turbulent Flows, AIAA Journal Volume 19, No. 9, pp. 1197-1200, September 1972.
23. Van Driest, E. R.: On Turbulent Flow Near a Wall. Journal Aeronautical Sciences, Volume 23, no. 11, p. 1007, November 1956.
24. Cebeci, T.: Eddy-Viscosity Distribution in Thick Axisymmetric Turbulent Boundary Layers. Journal of Fluids Engineering, June 1973, pp. 319 to 326.
25. Cebeci, T.: Kinematic Eddy Viscosity at Low Reynolds Numbers. AIAA Journal, Volume 11, No. 1, January 1973, pp. 102-104.

26. Coles, D.: The Turbulent Boundary Layer in a Compressible Fluid. Report R-403-PR., September 1962, Rand Corporation, Santa Monica, California.
27. Cebeci, T.: Laminar and Turbulent Incompressible Boundary Layers on Slender Bodies of Revolution in Axial Flow. Journal of Basic Engineering, Trans. ASME, Series D, Volume 92, No. 3, September 1979, pp. 545-554.
28. Cebeci, T.: Wall Curvature and Transition Effects in Turbulent Boundary Layers. AIAA Journal, Volume 9, No. 9, September 1971, pp. 1868-1870.
29. Chen, K. K. and Thyson, W. A.: Extension of Emmons' Spot Theory to Flows on Blunt Bodies. AIAA Journal, Volume 9, No. 5, pp. 821-825.
30. Emmons, H. W.: The Laminar-Turbulent Transition in a Boundary Layer. Journal of the Aerospace Sciences, Volume 18, Part I, 1950, p. 490.
31. Michel, R.: Etude de la Transition Sur Les Profils D'Aile-Etablissement d'un critere de Determination du Point de Transition et Calcul de la Traitee de Profil en Incompressible. Onera Rapport 1/1578A, July 1951.
32. Smith, A. M. O.: Transition, Pressure Gradient, and Stability Theory. Proceedings of the 9th International Congress of Applied Mechanics, Volume 4, 1956, p. 234.
33. Kaups, K.: Transition Prediction on Bodies of Revolution. McDonnell Douglas Report No. MDC J6530, prepared under U.S. Navy Undersea Center Contract No. N66001-74-C-0020, April 1974.
34. Cebeci, T.; Mosinskis, G. J.; and Smith, A. M. O.: Calculation of Viscous Drag and Turbulent Boundary Layer Separation on Two-Dimensional and Axisymmetric Bodies in Incompressible Flow. McDonnell Douglas Report No. MDC J0973-01, prepared under Contract No. N00014-70-C-0099, for the Naval Ship and Systems Command, November 1970.
35. Hoerner, S. F.: Base Drag and Thick Trailing Edges. Journal of the Aeronautical Sciences, 1959, p. 622.
36. Bauer, A. B.: Body of Revolution Drag Measurement and Results. McDonnell Douglas Corporation Report No. MDC J5167/01, December 1970.

37. Tomotike, S. and Imai, I.: On the Transition from Laminar to Turbulent Flow in the Boundary Layer of a Sphere. Aeronautical Research Institute of Tokyo University Report No. 167, p. 389-423, August 1938.
38. Achenbach, Elmar: Experiments on the Flow Past Spheres at Very High Reynolds Numbers. Journal of Fluid Mechanics Volume 54, Part 3, 1972, pp. 565-575.
39. Jacob, K.: Theoretische Berechnung von Druckverteilung und Kraftbeiwerten Für Beliebige Profile bei Inkompressibler Strömung mit Ablösung. Ava-Bericht 67 A 62 (1967).
40. Beatty, T.D.: Prediction of Flows with and without Partial Separation. Masters Thesis presented to Mechanical Engineering Department, California State University, Long Beach, July 1972.
41. Hahn, M.; Rubbert, P. E.; and Mahal, A.: Evaluation of Separation Criteria and Their Application to Separated Flow Analysis. Air Force Flight Dynamics Laboratory Report No. AFFDL-TR-72-145, January 1973.
42. Cebeci, T.; Mosinskis, G. J.; and Kaups, K.: A General Method for Calculating Three-Dimensional Incompressible Laminar and Turbulent Boundary Layers. 1. Swept Infinite Cylinders and Small Cross Flow McDonnell Douglas Aircraft Corporation Report No. MDC J5694, prepared under Contract No. N00014-72-C-0111, for the Naval Ship Systems Command.
43. Chang, P.K.: Separation of Flow. Pergamon Press, 1970.
44. Wang, K. C.: Separation Patterns of Boundary Layer Over an Inclined Body of Revolution. AIAA Journal, Volume 10, No. 8, August 1972.

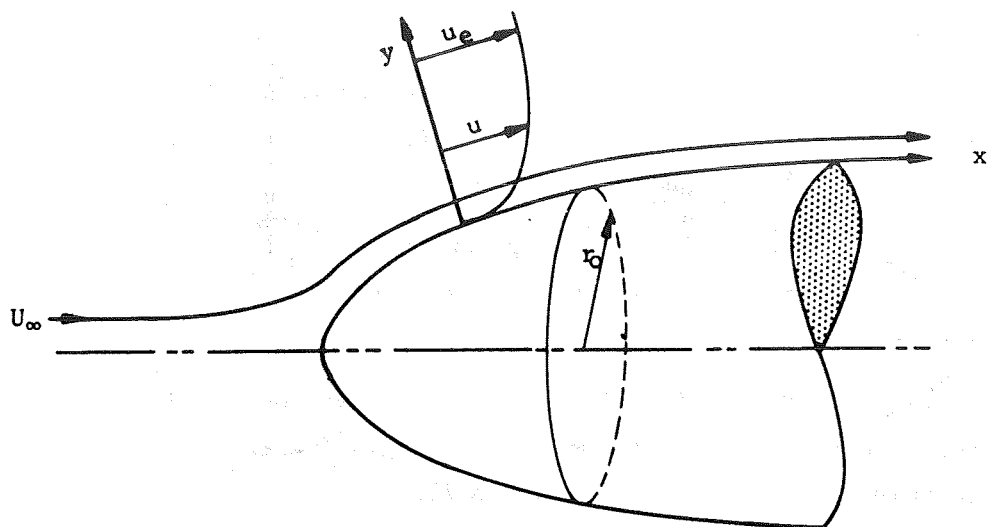


FIGURE 1. COORDINATE SYSTEM FOR THE BOUNDARY LAYER ON A BODY OF REVOLUTION

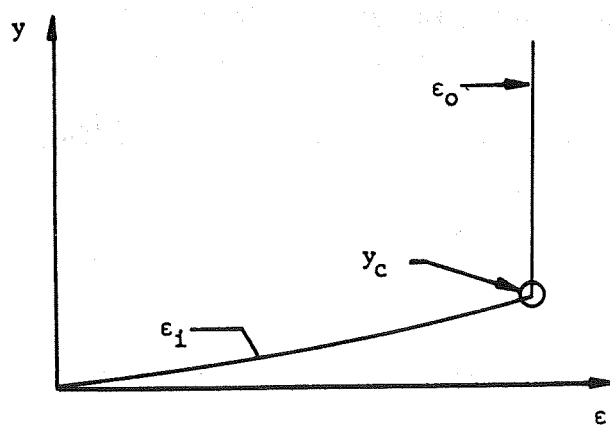


FIGURE 2. EDDY-VISCOSITY DISTRIBUTION ACROSS A BOUNDARY LAYER

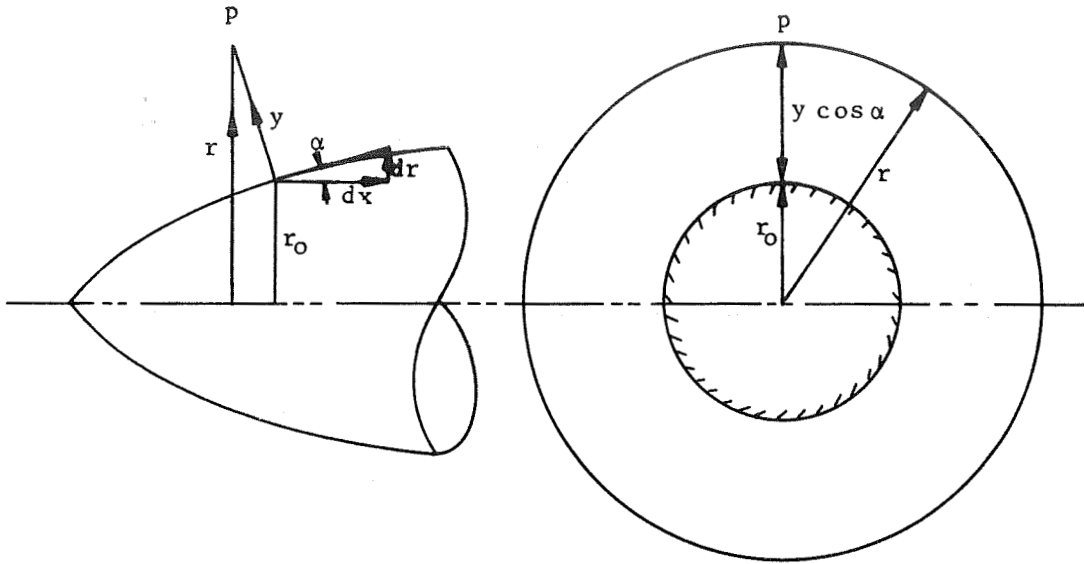


FIGURE 3. COORDINATES FOR AXIALLY SYMMETRIC BODY WITH THICK BOUNDARY LAYER

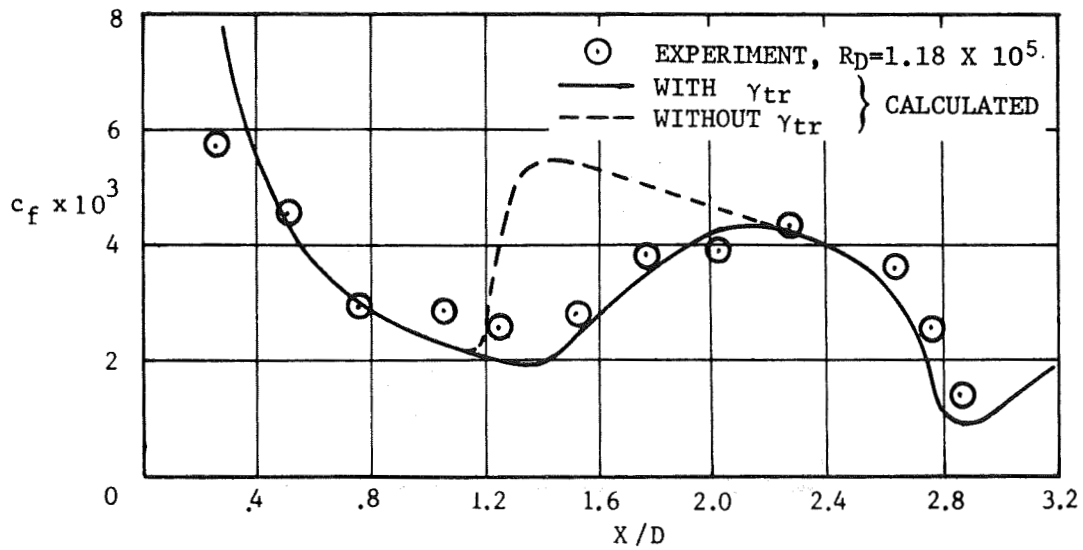


FIGURE 4. EFFECT OF TRANSITION REGION MODIFICATION ON THE SKIN FRICTION

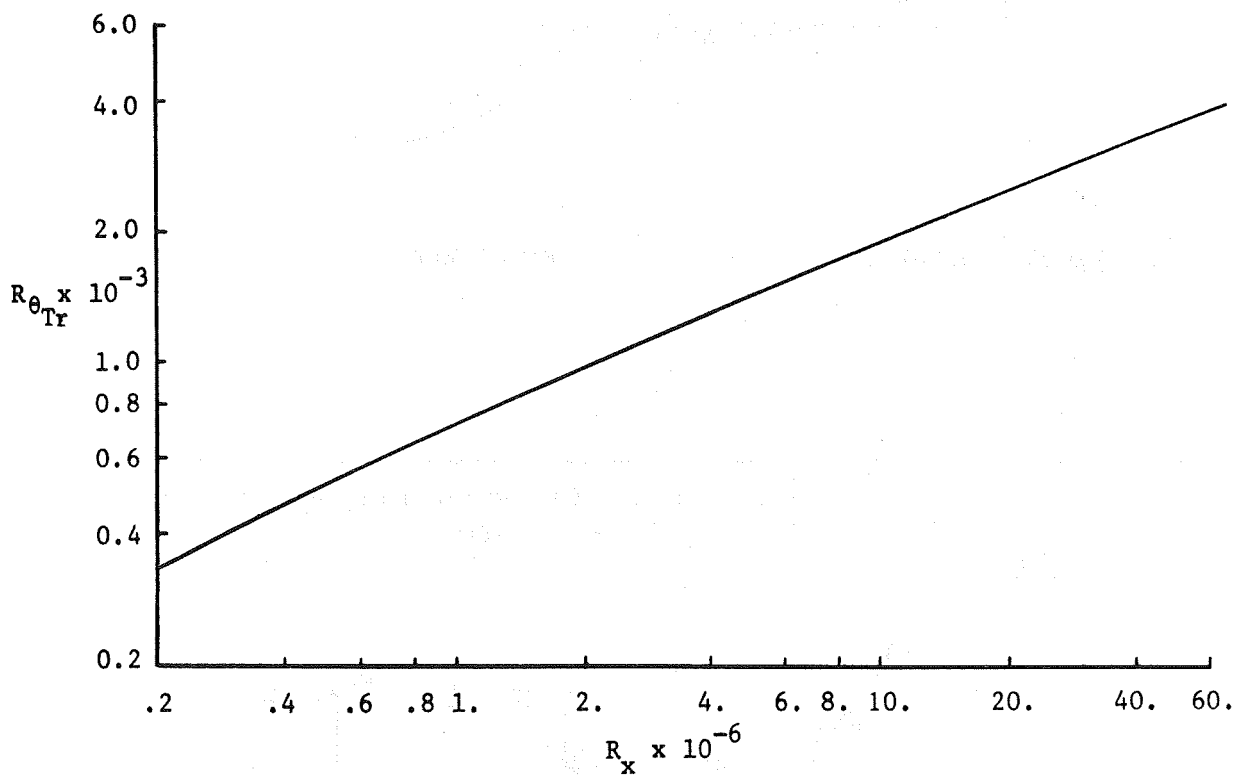


FIGURE 5. TRANSITION CORRELATION CURVE FROM REFERENCE 32

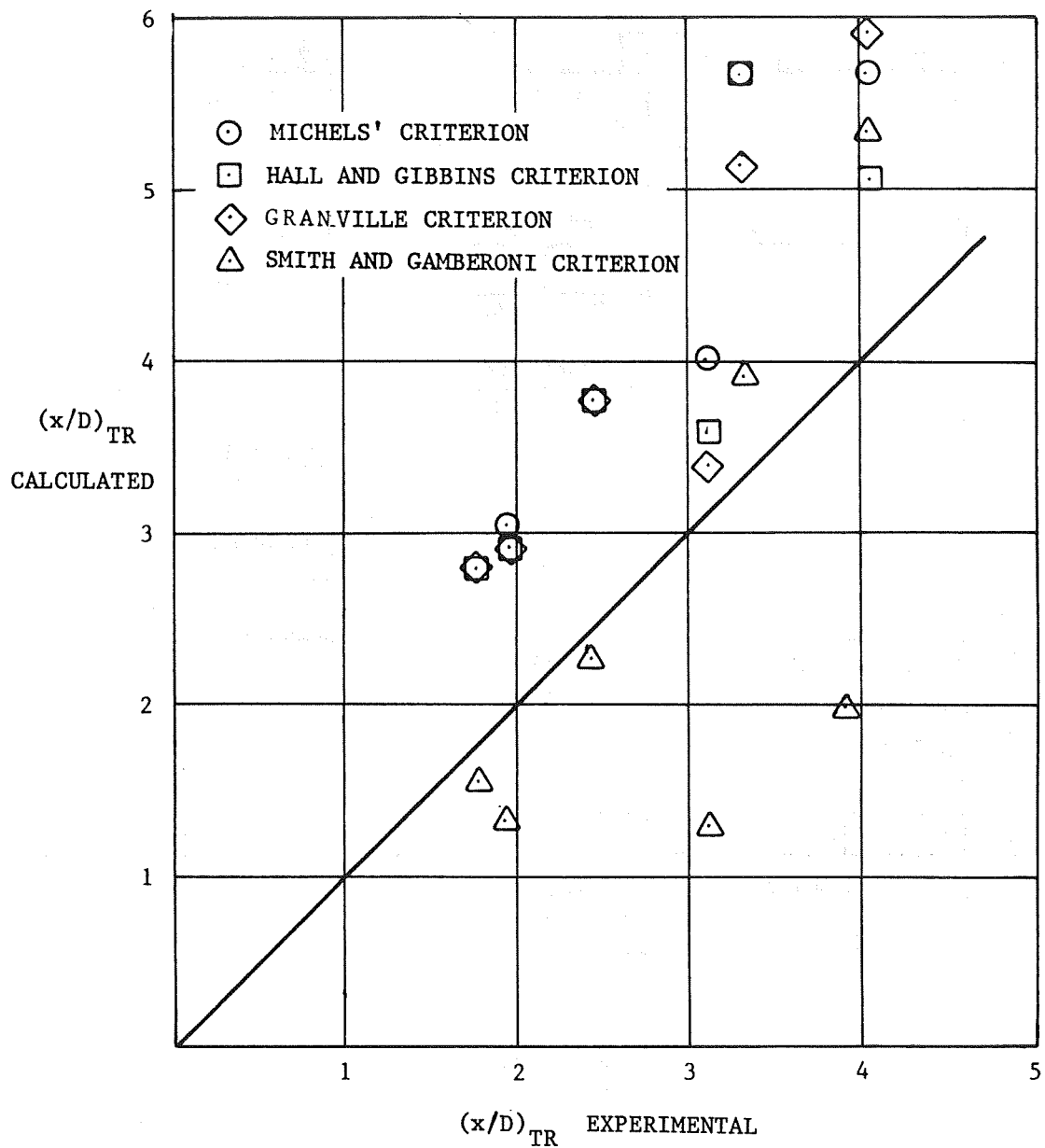


FIGURE 6. COMPARISON OF EXPERIMENTAL AND CALCULATED TRANSITION LOCATIONS FROM VARIOUS METHODS FOR FAVORABLE GRADIENT FLOWS

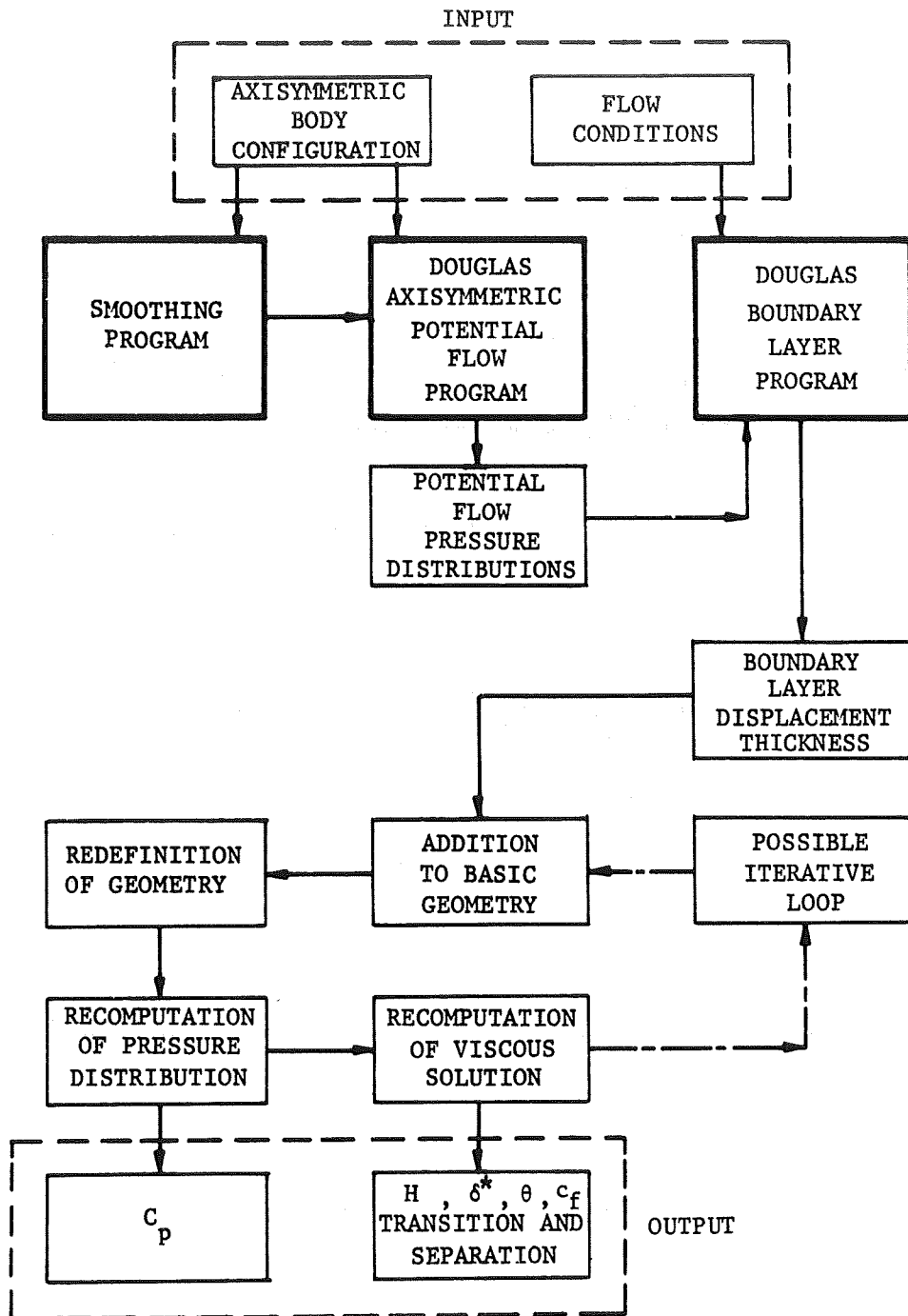


FIGURE 7. FLOW DIAGRAM OF COMPUTER PROGRAM FOR AXISYMMETRIC ANALYSIS AND DESIGN METHOD (ADAM)

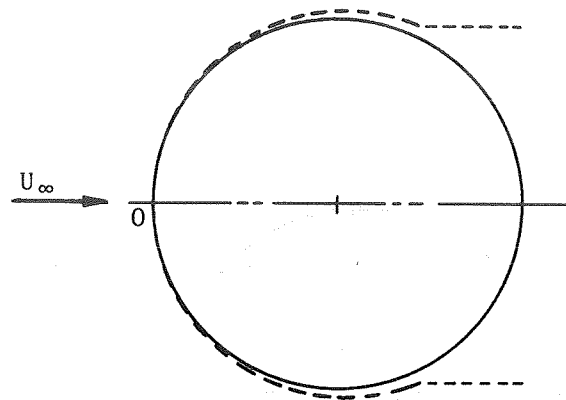


FIGURE 8. SCHEMATIC DIAGRAM OF CYLINDRICAL WAKE SHAPE USED TO MODEL SEPARATION

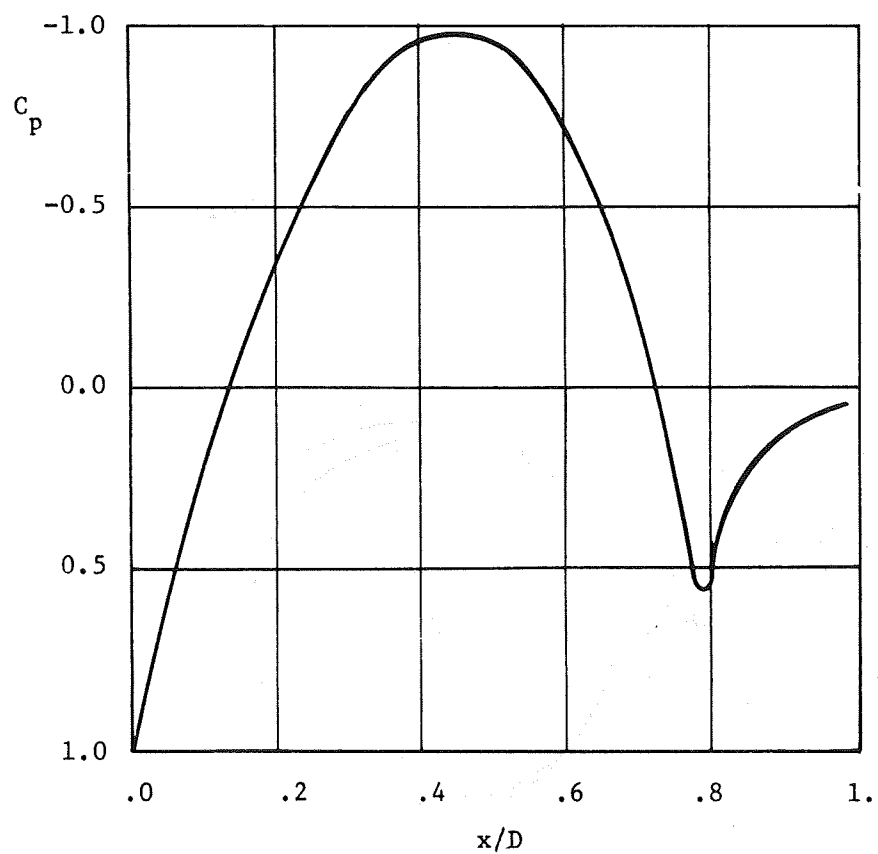


FIGURE 9. PRESSURE DISTRIBUTION FOR SPHERE IN SUPERCRITICAL REGION USING CYLINDRICAL SEPARATION MODEL

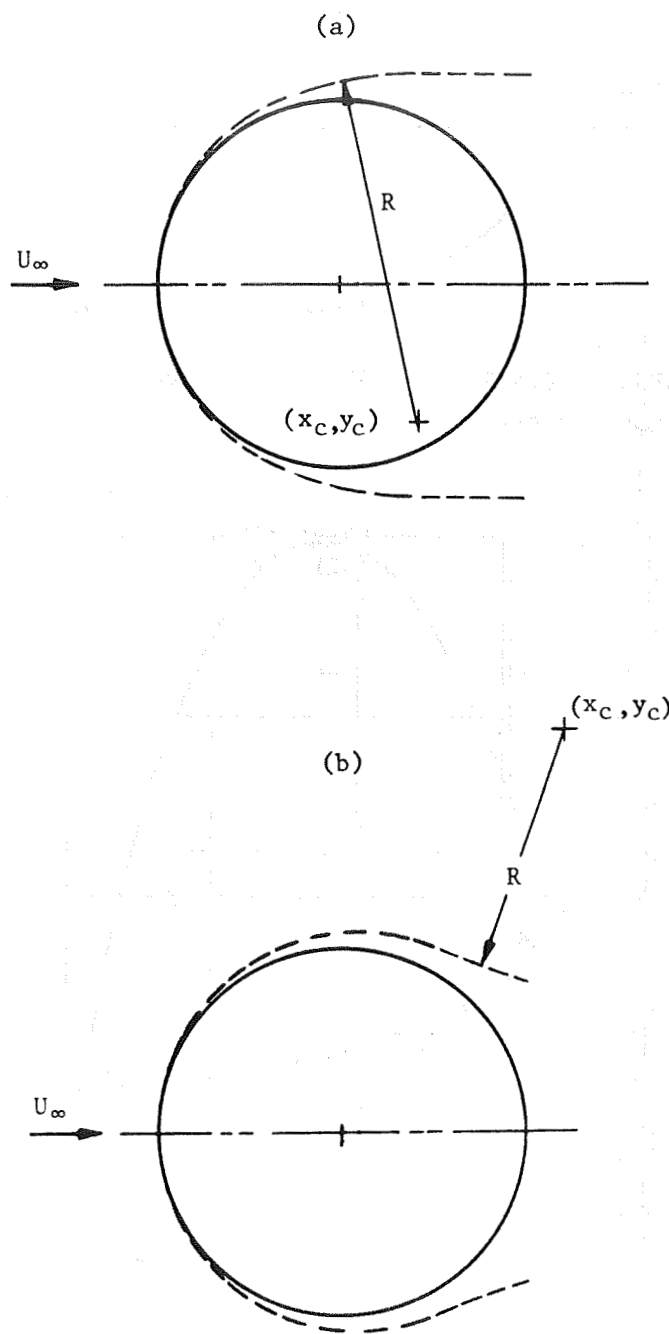


FIGURE 10. SCHEMATIC DIAGRAMS OF CIRCULAR ARC FAIRING USED IN THE MODEL FOR SEPARATED FLOW.

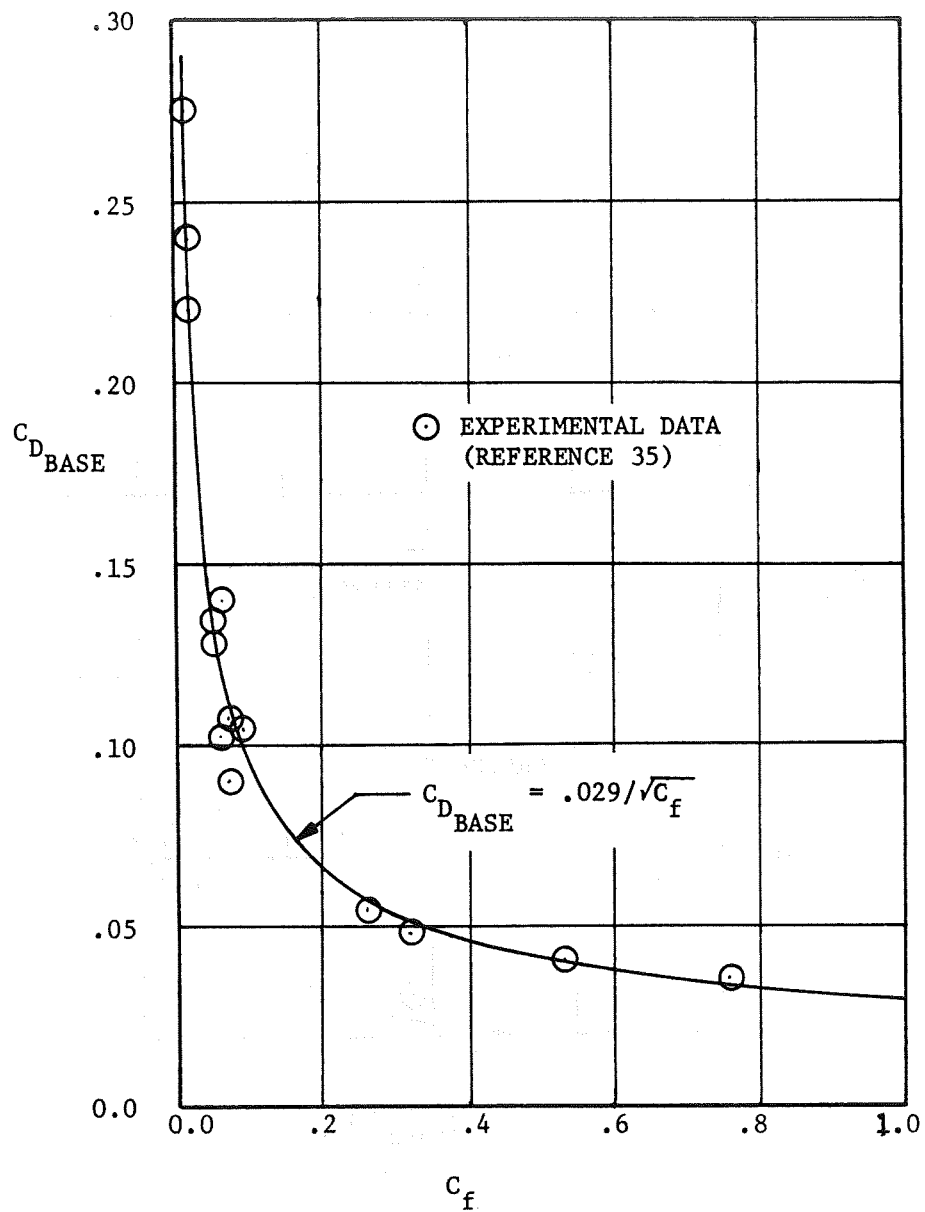


FIGURE 11 AXISYMMETRIC BASE DRAG AS A FUNCTION OF FOREBODY SKIN FRICTION COEFFICIENT

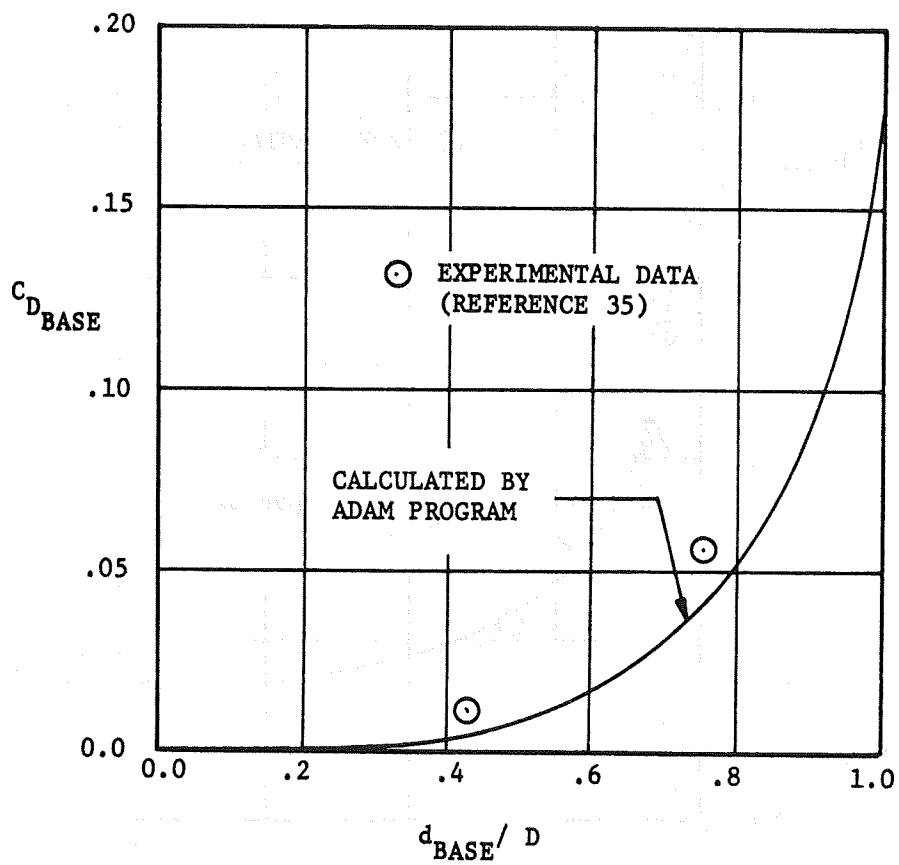


FIGURE 12 COMPARISON OF BASE DRAG CALCULATED BY ADAM TO EXPERIMENTAL DATA

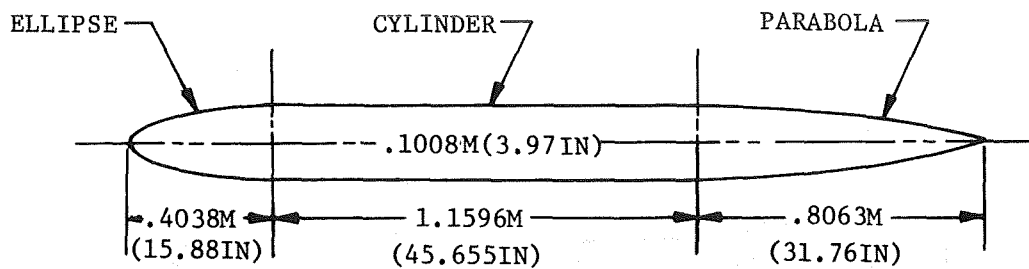


FIGURE 13. SCHEMATIC OF HIGH FINENESS RATIO BODY FROM REFERENCE 35

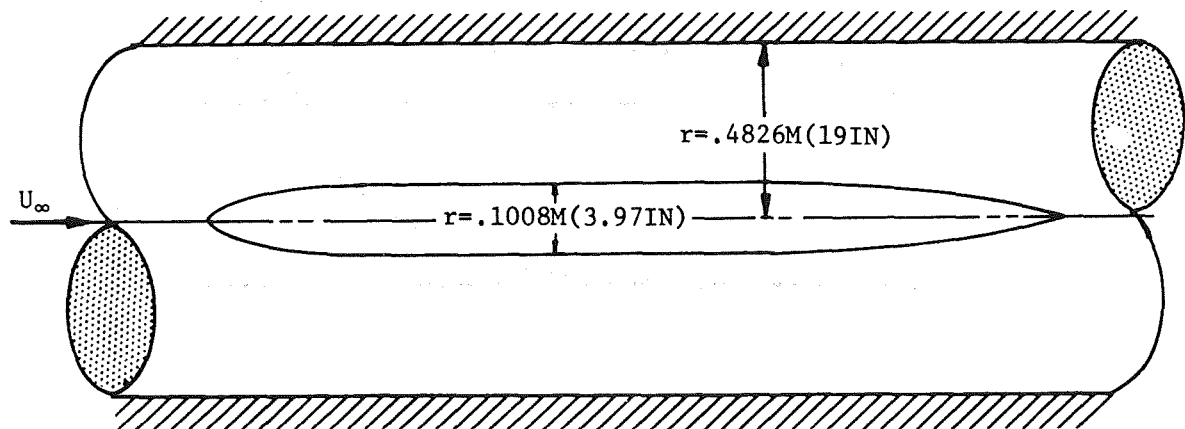


FIGURE 14. HIGH FINENESS RATIO BODY AND SIMULATED TUNNEL USED IN POTENTIAL FLOW PROGRAM TO ACCOUNT FOR WALL EFFECTS ON PRESSURE DISTRIBUTION

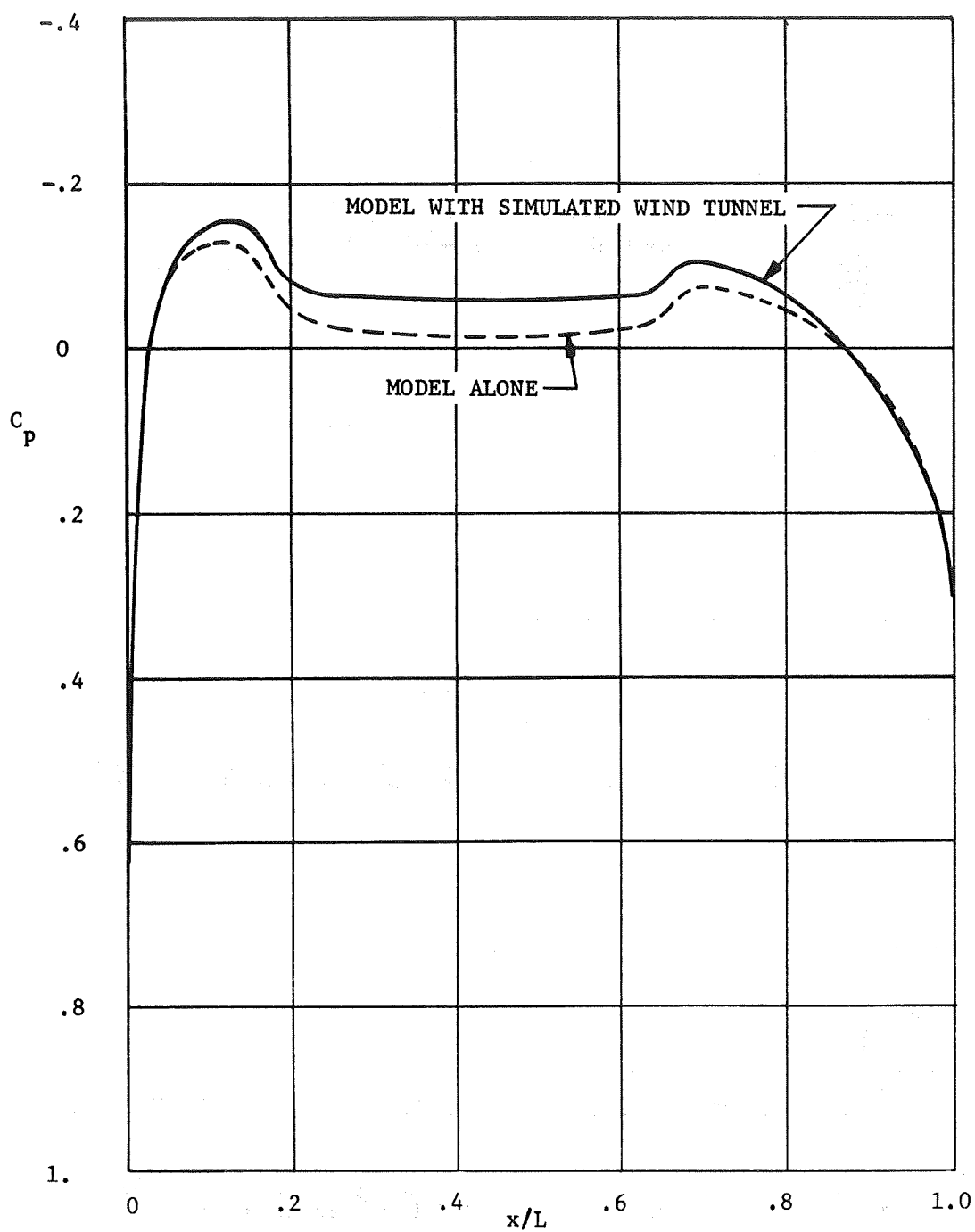


FIGURE 13. EFFECT OF WIND TUNNEL WALLS ON INVISCID PRESSURE DISTRIBUTION FOR HIGH FINENESS RATIO BODY AS CALCULATED BY POTENTIAL FLOW PROGRAM

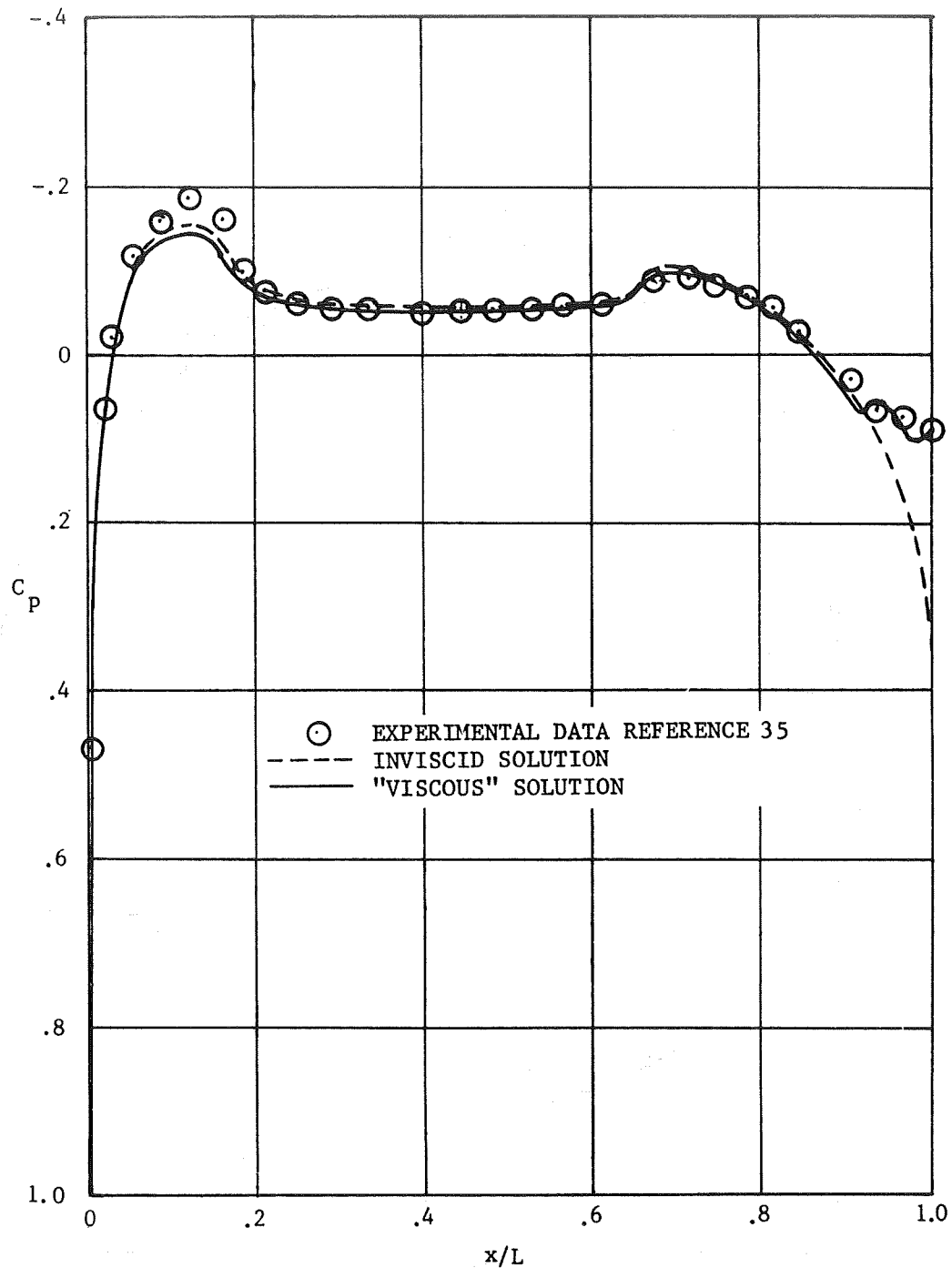


FIGURE 14. COMPARISON OF CALCULATED "VISCOUS" PRESSURE DISTRIBUTION FOR HIGH FINENESS RATIO BODY TO EXPERIMENTAL DATA

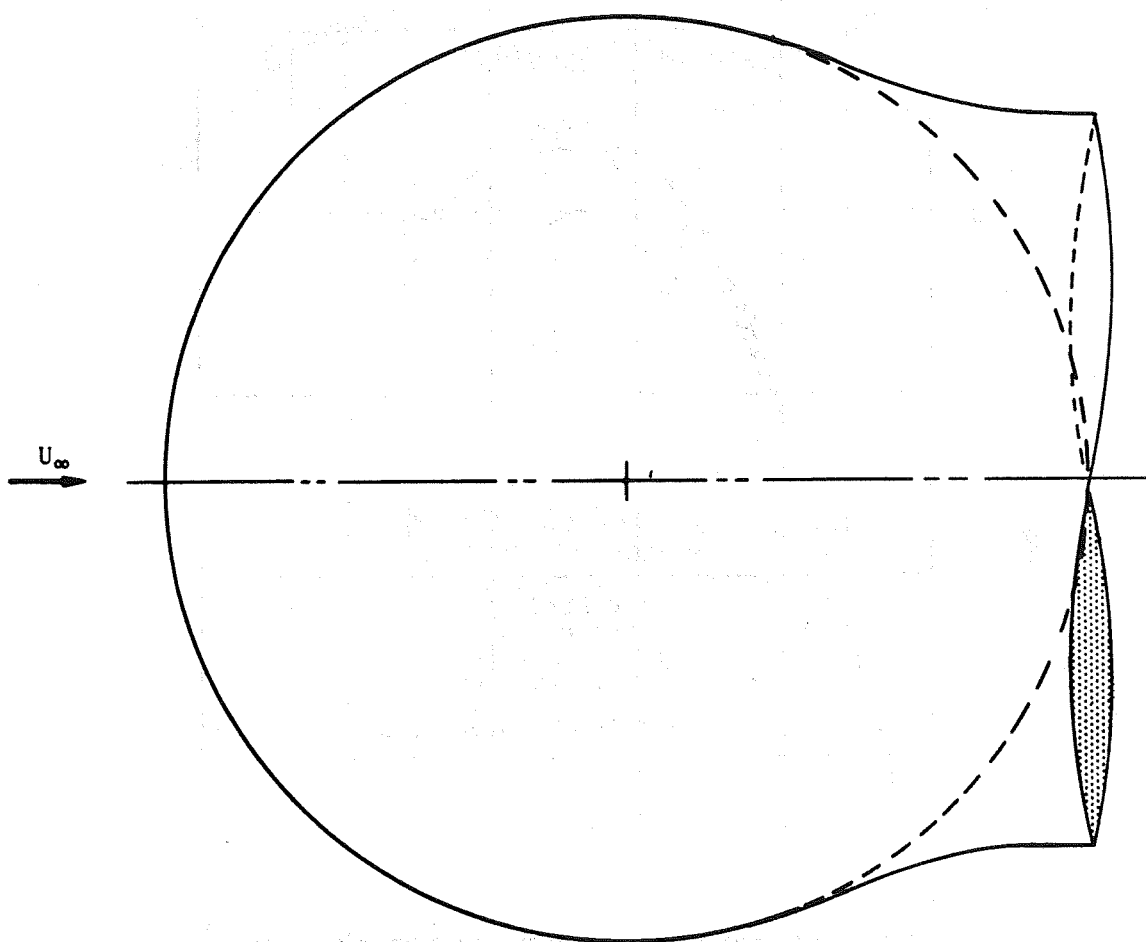


FIGURE 15. EQUIVALENT BODY INCLUDING SEPARATED WAKE USED TO CALCULATE "VISCOUS" FLOW ABOUT SPHERE IN SUPERCRITICAL REGIME

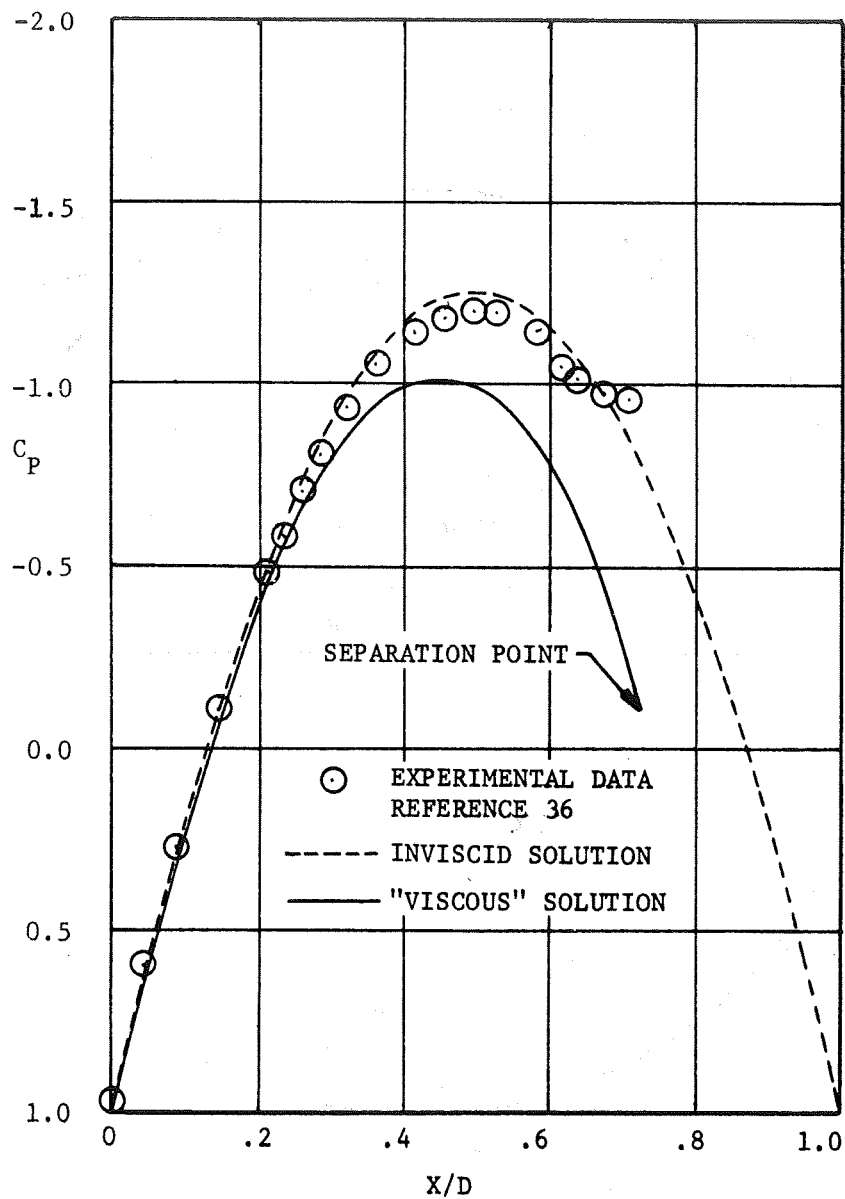


FIGURE 16. COMPARISON OF CALCULATED "VISCOUS" PRESSURE DISTRIBUTION FOR SPHERE IN SUPERCRITICAL REGIME TO EXPERIMENTAL DATA

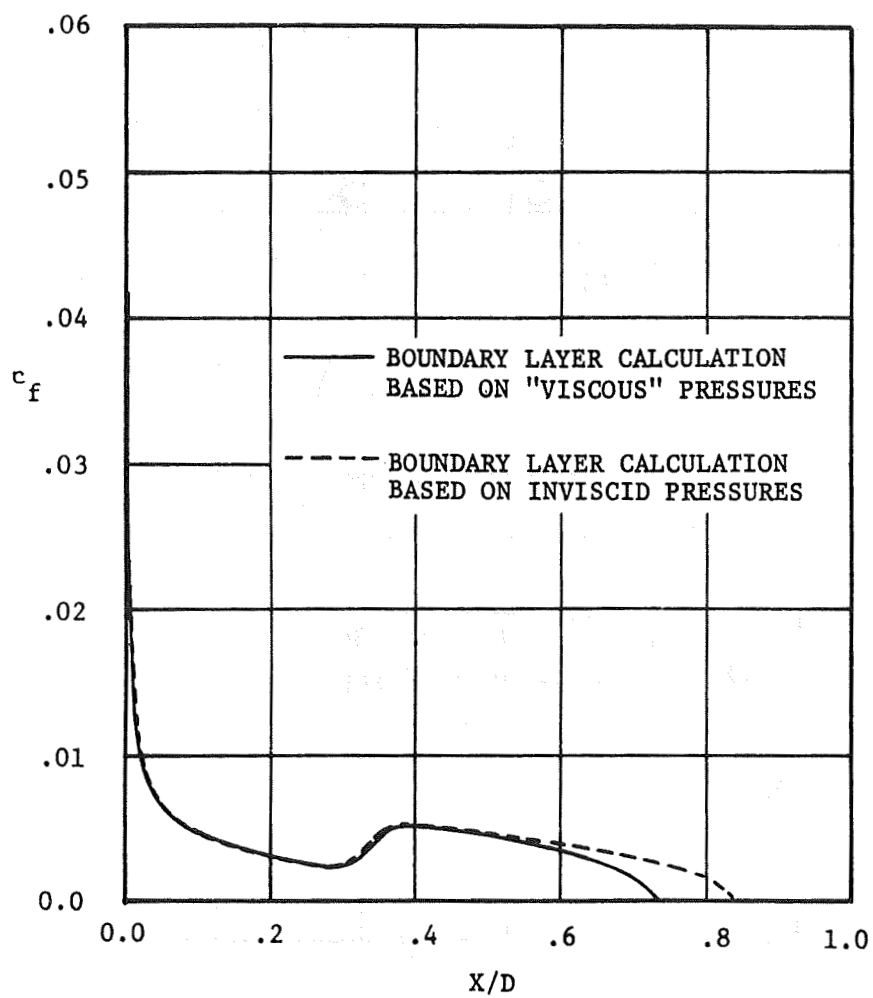


FIGURE . EFFECT OF "VISCOUS" MODELING ON CALCULATION OF LOCAL SKIN FRICTION COEFFICIENT FOR SPHERE IN SUPERCRITICAL REGIME

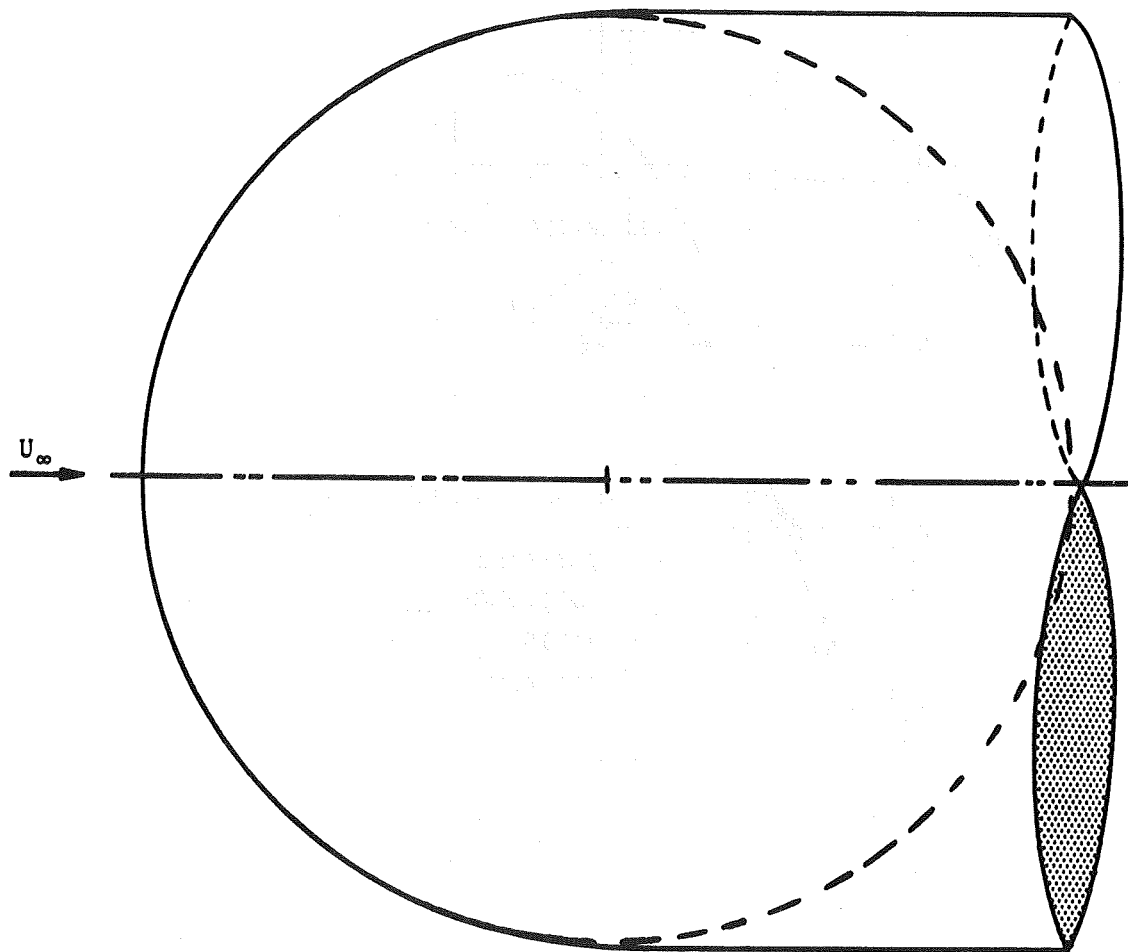


FIGURE 17. EQUIVALENT BODY INCLUDING SEPARATED WAKE USED TO CALCULATE "VISCOUS" FLOW ABOUT SPHERE IN SUBCRITICAL REGIME

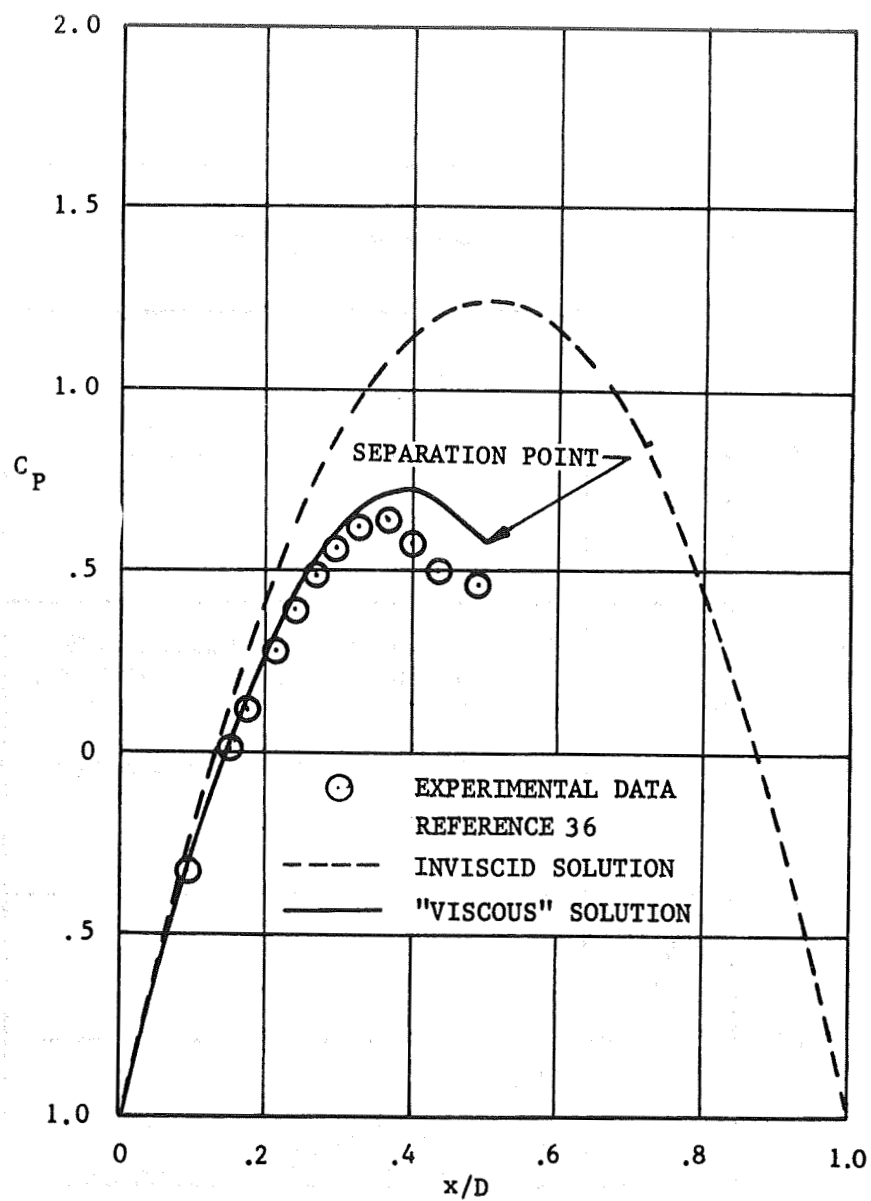


FIGURE 18. COMPARISON OF CALCULATED "VISCOUS" PRESSURE DISTRIBUTION FOR SPHERE IN SUBCRITICAL REGIME TO EXPERIMENTAL DATA

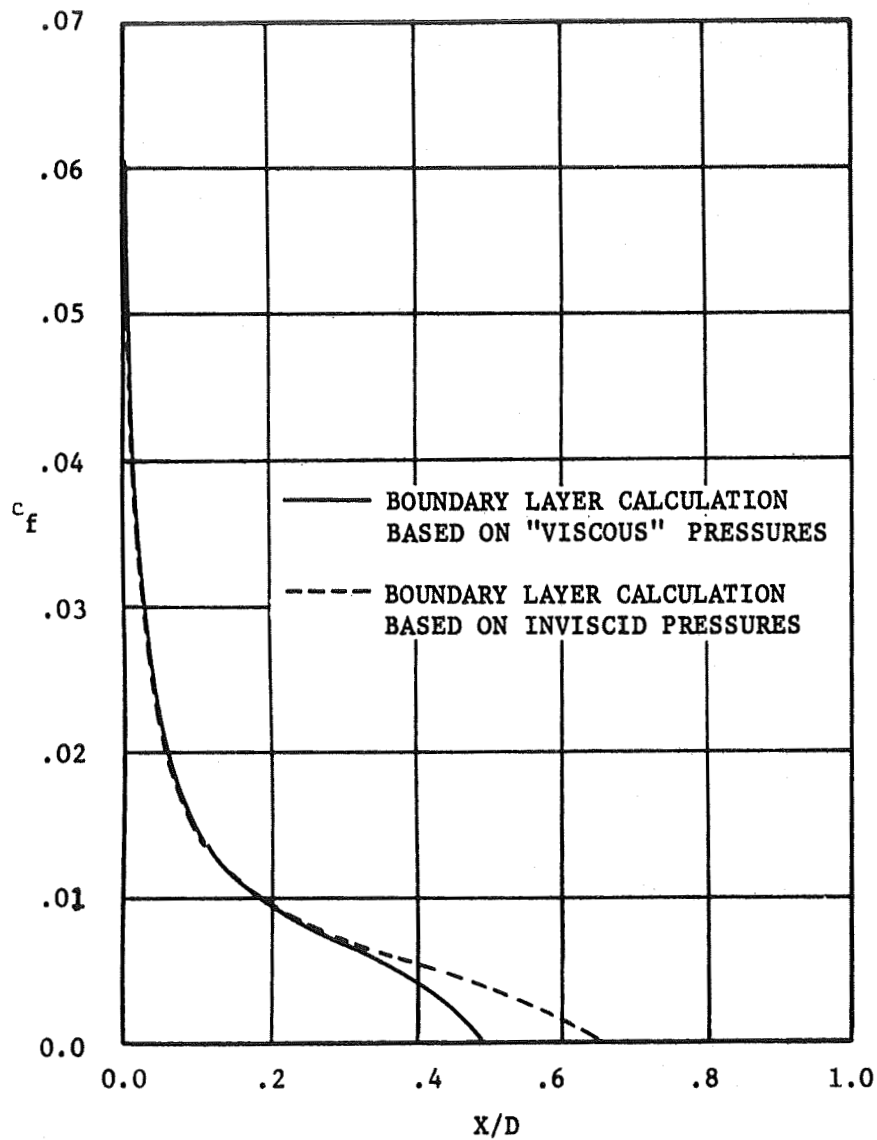


FIGURE . EFFECT OF "VISCOUS" MODELING ON CALCULATION OF LOCAL SKIN FRICTION COEFFICIENT FOR SPHERE IN SUBCRITICAL REGIME



POSTMASTER: If Undeliverable (Section 158
Postal Manual) Do Not Return

"The aeronautical and space activities of the United States shall be conducted so as to contribute . . . to the expansion of human knowledge of phenomena in the atmosphere and space. The Administration shall provide for the widest practicable and appropriate dissemination of information concerning its activities and the results thereof."

—NATIONAL AERONAUTICS AND SPACE ACT OF 1958

NASA SCIENTIFIC AND TECHNICAL PUBLICATIONS

TECHNICAL REPORTS: Scientific and technical information considered important, complete, and a lasting contribution to existing knowledge.

TECHNICAL NOTES: Information less broad in scope but nevertheless of importance as a contribution to existing knowledge.

TECHNICAL MEMORANDUMS: Information receiving limited distribution because of preliminary data, security classification, or other reasons. Also includes conference proceedings with either limited or unlimited distribution.

CONTRACTOR REPORTS: Scientific and technical information generated under a NASA contract or grant and considered an important contribution to existing knowledge.

TECHNICAL TRANSLATIONS: Information published in a foreign language considered to merit NASA distribution in English.

SPECIAL PUBLICATIONS: Information derived from or of value to NASA activities. Publications include final reports of major projects, monographs, data compilations, handbooks, sourcebooks, and special bibliographies.

TECHNOLOGY UTILIZATION PUBLICATIONS: Information on technology used by NASA that may be of particular interest in commercial and other non-aerospace applications. Publications include Tech Briefs, Technology Utilization Reports and Technology Surveys.

Details on the availability of these publications may be obtained from:

SCIENTIFIC AND TECHNICAL INFORMATION OFFICE

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION

Washington, D.C. 20546